



ISSN: 0067-2904

On the Grobner Basis of the Toric Ideal for $3 \times n$ - Contingency Tables

Hussein S. Mohammed Hussein*, Abdulrahman H. Majeed

Department of mathematics, College of science, University of Baghdad, Baghdad, Iraq

Abstract

In this paper, The Grobner basis Gr of the Toric Ideal I_A for $3 \times n$ - contingency tables related with the Markov basis \mathbf{B} introduced by Hussein S. MH, Abdulrahman H. M in 2018 is found. Also, the Grobner basis Gr is a reduced and universal Grobner basis are shown.

Keywords: Computational algebraic statistics, Toric ideal, Configuration matrix, Grobner basis, Reduced Grobner basis, Universal Grobner basis.

حول أساس كروينر للمثالية القرينة لجداول الطوارئ من النمط $3 \times n$

حسين سلمان محمد حسين*، عبدالرحمن حميد مجيد

قسم الرياضيات، كلية العلوم، جامعة بغداد، بغداد، العراق

الخلاصة

في هذا البحث وجد أساس كروينر Gr للمثالية القرينة I_A لجداول الطوارئ من النمط $3 \times n$ المتعلق بأساس ماركوف B الذي قدمه حسين سلمان و عبدالرحمن حميد مجيد في 2018 ، وايضاً، تم بيان أساس كروينر Gr هو أساس كروينر مخفض وشامل.

1. Introduction

Let I be a finite set and $|I| = n$, a cell is the element of I and it denoted by $\mathbf{i} \in I$. $\mathbf{i} = i_1 \dots i_m$, \mathbf{i} is often multi-index. A non-negative integer $x_i \in \mathbb{N} = \{1, 2, \dots\}$ denoted a frequency of the cell \mathbf{i} . A **contingency table** is a set of frequencies and stated as $\mathbf{x} = \{x_i\}_{i \in I}$, with an suitable arrangement of the cell, considered a contingency table $\mathbf{x} = \{x_i\}_{i \in I} \in \mathbb{N}^n$ as a n -dimansional column vector of non-negative integers. The contingency table can be treated as a function from I to \mathbb{N} defined as $\mathbf{i} \mapsto x_i$. A v -dimansional column vector $\mathbf{t} = (t_1, \dots, t_v)' \in \mathbb{Z}^v$ as $t_j = a'_{j\mathbf{x}}$, $j = 1, \dots, v$. Here $'$ denotes a transpose of the matrix or vector. Also define $v \times p$ matrix A , with its j -row being $a'_{j\mathbf{x}}$ given by

$A = \begin{bmatrix} a'_{1\mathbf{x}} \\ \vdots \\ a'_{v\mathbf{x}} \end{bmatrix}$, and if $\mathbf{t} = A\mathbf{x}$ is a v -dimensional column vector, we define the set $T = \{\mathbf{t} : \mathbf{t} = A\mathbf{x}, \mathbf{x} \in \mathbb{N}^n\} = A\mathbb{N}^n \subset \mathbb{Z}^v$, where denoted \mathbb{N} is a set of natural numbers. The set of \mathbf{x} 's for \mathbf{t} , $A^{-1}[\mathbf{t}] = \{\mathbf{x} \in \mathbb{N}^n : A\mathbf{x} = \mathbf{t}\}$ (\mathbf{t} -fibers), is treat for result *similar tests*. A set of \mathbf{t} -fibers deigns a taking apart of \mathbb{N}^n . An important noting is that \mathbf{t} -fiber depend on given out of its kernel $\ker(A)$. In fact, defined $\mathbf{x}_1 \sim \mathbf{x}_2 \leftrightarrow \mathbf{x}_1 - \mathbf{x}_2 \in \ker(A)$. With oneself kernel for different A 's, the set of \mathbf{t} -fibers are the same [1].

(P.Diaconis) and (B.Sturmfels's) publication in 1998 found a new path in the rapid-advancing field of computational algebraic statistics [2] and [3].

In 2000, (M. Dyer), and (C. Greenhill), found a Polynomial-time compute and sampling of contingency tables[4].

*Email: husseinsalman88@yahoo.com

In 2003, (A.Dobra) showed that the only moves have to be inclusive in a Markov basis that connects all contingency tables with fixed marginals [5].

In 2018, (H. Mohammed Hussein), and (A. Majeed), found a Markov basis and toric ideals for $(25n^3 - 66n^2 + 44n) \times 3 \times n$ - contingency tables with it have a fixed dimensional marginal [6].

In this paper, we find the Grobner basis Gr of the Toric Ideal I_A for $3 \times n$ - contingency tables related with the Markov basis \mathbf{B} , also, we show that the Grobner basis Gr is a reduced and universal Grobner basis.

2. Some Basic Concepts

In this section, we review some basic definitions and notations of the monomial, the support of f , Grobner basis, toric ideals, and configuration matrix that we need in our work.

Definition (2.1) [7]: A monomial in the variables x_1, x_2, \dots, x_k is the product of the form $\prod_{i=1}^k x_i^{a_i} = x_1^{a_1} x_2^{a_2} \dots x_k^{a_k}$, where each a_i is a nonnegative integer.

Definition (2.2) [7]: The degree of the monomial $\prod_{i=1}^k x_i^{a_i} = x_1^{a_1} x_2^{a_2} \dots x_k^{a_k}$ is $\sum_{i=1}^k a_i$, in particular $1 = x_1^0 x_2^0 \dots x_k^0$ is a monomial of degree 0.

Definition (2.3) [7]: The monomial $f = \prod_{i=1}^k x_i^{a_i}$ divides $g = \prod_{i=1}^k x_i^{b_i}$ if $a_i \leq b_i$ for all $1 \leq i \leq k$, we write $f \mid g$ if f divides g .

Definition (2.4) [7]: Let μ_n denote the set of monomials in the variables x_1, x_2, \dots, x_k , let M be a nonempty subset of μ_n . A monomial $f \in M$ is called a minimal element of M if $g \in M$ and $g \mid f$, then $f = g$.

Definition (2.5) [7]: Given a nonzero polynomial $f = f_1 + f_2 + \dots + f_t$ of $K[x]$, where the notation K stands for one of \mathbb{Q}, \mathbb{R} and \mathbb{C} and f_1, f_2, \dots, f_t are monomials with $f_1 > f_2 > \dots > f_t$, then the support of f is the set of monomials appearing in f . It is written as $supp(f)$. Thus $supp(f) = \{f_1, f_2, \dots, f_t\}$ and $in_{<}(f) = f_1$.

Definition (2.6) [7]: The Grobner basis of an ideal $I \neq \langle 0 \rangle$ of $K[x]$ is a set $\{f_1, f_2, \dots, f_t\} \subseteq I$ of nonzero polynomials such that $\{in_{<}(f_1), in_{<}(f_2), \dots, in_{<}(f_t)\}$ is a system of monomial generators of the initial ideal $in_{<}(I)$, where $in_{<}(I) = \langle in_{<}(f) : 0 \neq f \in I \rangle$.

Definition (2.7) [7]: A Grobner basis $\{f_1, f_2, \dots, f_t\}$ of an ideal $I \neq \langle 0 \rangle$ of $K[x]$ is called reduced Grobner basis if the following conditions are satisfied:

1. The coefficient of $in_{<}(f_i)$ in f_i is 1 for all $1 \leq i \leq t$.
2. If $i \neq j$, then none of the monomials belonging to $supp(f_i)$ is divided by $in_{<}(f_j)$.

Definition (2.8) [8]: A finite Grobner basis $\{f_1, f_2, \dots, f_t\}$ of an ideal I_A is called a universal Grobner basis and it is denoted by u_A .

Definition (2.9) [7]: Let $a = [a_1 \ a_2 \ \dots \ a_m]'$ and $b = [b_1 \ b_2 \ \dots \ b_m]'$, then the inner product of the vectors a and b is defined as $a \cdot b = \sum_{i=1}^m a_i b_i$.

Definition (2.10) [7]: Let $A = (a_{ij})_{\substack{1 \leq i \leq m \\ 1 \leq j \leq n}}$ be a $m \times n$ matrix and $a_j = [a_{1j} \ a_{2j} \ \dots \ a_{mj}]'$,

$1 \leq j \leq n$ is the column vectors of A , a matrix A is called a configuration matrix if there exists $c \in \mathbb{R}^m$ such that $a_j \cdot c = 1, 1 \leq j \leq n$.

Remark (2.11) [6]: Let n be a natural number, $n \geq 2$, and let $x_j \in A^{-1}[t], j = 1, \dots, k$ be the representative elements of the set of $3 \times n$ -contingency tables and $\mathbf{B} = \{\mathbf{z}_1, \mathbf{z}_2, \dots, \mathbf{z}_k\}$ such that each $\mathbf{z}_m, m = 1, 2, \dots, k$, is a matrix of dimension $3 \times n$ either has two non-zero columns and the other columns are zero denoted by $2\mathbf{z}_m$, or it has three non-zero columns and the other columns are zero denoted by $3\mathbf{z}_m$, like

$$\begin{bmatrix} 1 & 0 & -1 \\ -1 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 2 & -2 & 0 \\ 0 & 0 & 0 \\ -2 & 2 & 0 \end{bmatrix}, \begin{bmatrix} 2 & -1 & -1 \\ -1 & 0 & 1 \\ -1 & 1 & 0 \end{bmatrix}.$$

Also, we write the elements of \mathbf{B} as one dimensional column vector as follows:

$\mathbf{z}_m = (z_1, \dots, z_{3n})', m = 1, \dots, k$ and $z_s = 0, 1, -1, 2$ or $-2, s = 1, 2, \dots, 3n$ such that If $s = 1, 2, \dots, n$, then

$$z_s = \begin{cases} 1 & \text{if } z_{s+n} + z_{s+2n} = -1 \text{ and } \sum_{\substack{i=1 \\ i \neq s}}^n z_i = -1 \\ 2 & \text{if } z_{s+n} + z_{s+2n} = -2 \text{ and } \sum_{\substack{i=1 \\ i \neq s}}^n z_i = -2 \\ 0 & \text{if } z_{s+n} + z_{s+2n} = 0 \text{ and } \sum_{\substack{i=1 \\ i \neq s}}^n z_i = 0 \\ -1 & \text{if } z_{s+n} + z_{s+2n} = 1 \text{ and } \sum_{\substack{i=1 \\ i \neq s}}^n z_i = 1 \\ -2 & \text{if } z_{s+n} + z_{s+2n} = 2 \text{ and } \sum_{\substack{i=1 \\ i \neq s}}^n z_i = 2 \end{cases} \quad (1)$$

If $s = n + 1, n + 2, \dots, 2n$, then

$$z_s = \begin{cases} 1 & \text{if } z_{s-n} + z_{s+n} = -1 \text{ and } \sum_{\substack{i=n+1 \\ i \neq s}}^{2n} z_i = -1 \\ 2 & \text{if } z_{s-n} + z_{s+n} = -2 \text{ and } \sum_{\substack{i=n+1 \\ i \neq s}}^{2n} z_i = -2 \\ 0 & \text{if } z_{s-n} + z_{s+n} = 0 \text{ and } \sum_{\substack{i=n+1 \\ i \neq s}}^{2n} z_i = 0 \\ -1 & \text{if } z_{s-n} + z_{s+n} = 1 \text{ and } \sum_{\substack{i=n+1 \\ i \neq s}}^{2n} z_i = 1 \\ -2 & \text{if } z_{s-n} + z_{s+n} = 2 \text{ and } \sum_{\substack{i=n+1 \\ i \neq s}}^{2n} z_i = 2 \end{cases} \quad (2)$$

If $s = 2n + 1, 2n + 2, \dots, 3n$, then

$$z_s = \begin{cases} 1 & \text{if } z_{s-n} + z_{s-2n} = -1 \text{ and } \sum_{\substack{i=2n+1 \\ i \neq s}}^{3n} z_i = -1 \\ 2 & \text{if } z_{s-n} + z_{s-2n} = -2 \text{ and } \sum_{\substack{i=2n+1 \\ i \neq s}}^{3n} z_i = -2 \\ 0 & \text{if } z_{s-n} + z_{s-2n} = 0 \text{ and } \sum_{\substack{i=2n+1 \\ i \neq s}}^{3n} z_i = 0 \\ -1 & \text{if } z_{s-n} + z_{s-2n} = 1 \text{ and } \sum_{\substack{i=2n+1 \\ i \neq s}}^{3n} z_i = 1 \\ -2 & \text{if } z_{s-n} + z_{s-2n} = 2 \text{ and } \sum_{\substack{i=2n+1 \\ i \neq s}}^{3n} z_i = 2 \end{cases} \quad (3)$$

Theorem (2.12) [6]:

The number of elements in \mathbf{B} is equal to $25n^3 - 66n^2 + 41n$.

Remark (2.13) [6]:

Given a contingency table \mathbf{x} , the entry of the matrix A in the column indexed by $\mathbf{x} = (x_1, x_2, \dots, x_{3n})$ and row $(\sum_{i=1}^n x_i, \sum_{i=n+1}^{2n} x_i, \sum_{i=2n+1}^{3n} x_i, x_1 + x_{n+1} + x_{2n+1}, x_2 + x_{n+2} + x_{2n+2}, \dots, x_n + x_{2n} + x_{3n})$ will be equal to one if x_i a pears in the $(\sum_{i=1}^n x_i)$ and it will zero otherwise. Then

$$A = \begin{bmatrix} 1 & 1 & \dots & 1 & 1 & 0 & 0 & \dots & 0 & 0 & 0 & 0 & \dots & 0 & 0 \\ 0 & 0 & \dots & 0 & 0 & 1 & 1 & \dots & 1 & 1 & 0 & 0 & \dots & 0 & 0 \\ 0 & 0 & \dots & 0 & 0 & 0 & 0 & \dots & 0 & 0 & 1 & 1 & \dots & 1 & 1 \\ 1 & 0 & \dots & 0 & 0 & 1 & 0 & \dots & 0 & 0 & 1 & 0 & \dots & 0 & 0 \\ 0 & 1 & \dots & 0 & 0 & 0 & 1 & \dots & 0 & 0 & 0 & 1 & \dots & 0 & 0 \\ \vdots & \vdots & \dots & \vdots & \vdots & \vdots & \vdots & \dots & \vdots & \vdots & \vdots & \vdots & \dots & \vdots & \vdots \\ 0 & 0 & \dots & 0 & 1 & 0 & 0 & \dots & 0 & 1 & 0 & 0 & \dots & 0 & 1 \end{bmatrix}_{(n+3) \times 3n}$$

Theorem (2.14) [6]:

$\mathbf{B} = \{z_1, \dots, z_{(25n^3 - 66n^2 + 41n)}\}$ is a set of moves.

Corollary (2.15) [6]:

The set \mathbf{B} of moves in theorem (2.14) is a Markov basis.

Corollary (2.16) [6]: Let \mathbf{B} is a Markov basis for A Then toric ideal I_A for $(25n^3 - 66n^2 + 41n) \times 3 \times n$ contingency tables is $I_A = \langle P_{i+l} P_{j+r} - P_{j+l} P_{i+r}, P_{i+l}^2 P_{j+r} P_{j+s} - P_{j+l}^2 P_{i+r} P_{i+s}, P_{i+l}^2 P_{j+r} P_{k+r} - P_{i+r}^2 P_{j+l} P_{k+l}, P_{i+l}^2 P_{j+r}^2 P_{k+s} - P_{j+l}^2 P_{i+r} P_{i+s} P_{k+r}, P_{i+l}^2 P_{j+r}^2 P_{k+s}^2 - P_{i+r}^2 P_{j+s}^2 P_{k+l}^2, P_{i+l}^2 P_{j+r}^2 P_{k+s}^2 - P_{i+s} P_{i+r} P_{j+s} P_{j+l} P_{k+r} P_{k+l}, P_{i+l}^2 P_{j+r} P_{k+s} - P_{i+r} P_{i+s} P_{j+l} P_{k+l} : i, j, k = 1, 2, \dots, n$ and $l, s, r = 0, n, 2n$, such that $i \neq j \neq k$ and $l \neq s \neq r \rangle \subset \mathbb{C}[P_1, P_2, \dots, P_{3n}]$.

3. The Main Results

Theorem (3.1): The matrix A in Remark (2.13) is a configuration matrix.

Proof:

To prove A is a configuration matrix,

$$\text{Since } A = \begin{bmatrix} 1 & 1 & \dots & 1 & 1 & 0 & 0 & \dots & 0 & 0 & 0 & 0 & \dots & 0 & 0 \\ 0 & 0 & \dots & 0 & 0 & 1 & 1 & \dots & 1 & 1 & 0 & 0 & \dots & 0 & 0 \\ 0 & 0 & \dots & 0 & 0 & 0 & 0 & \dots & 0 & 0 & 1 & 1 & \dots & 1 & 1 \\ 1 & 0 & \dots & 0 & 0 & 1 & 0 & \dots & 0 & 0 & 1 & 0 & \dots & 0 & 0 \\ 0 & 1 & \dots & 0 & 0 & 0 & 1 & \dots & 0 & 0 & 0 & 1 & \dots & 0 & 0 \\ \vdots & \vdots & \dots & \vdots & \vdots & \vdots & \vdots & \dots & \vdots & \vdots & \vdots & \vdots & \dots & \vdots & \vdots \\ 0 & 0 & \dots & 0 & 1 & 0 & 0 & \dots & 0 & 1 & 0 & 0 & \dots & 0 & 1 \end{bmatrix}_{(n+3) \times 3n}$$

Therefore, $a_j = \begin{bmatrix} a_{1j} \\ a_{2j} \\ \vdots \\ a_{(n+3)j} \end{bmatrix}, 1 \leq j \leq 3n$. From Definition (2.10).

Let $c = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}_{(n+3)}$, then $a_j \cdot c = \sum_{i=1}^{n+3} a_i c_i = a_1 + a_2 + a_3$ from Definition (2.9).

- Case1: if $1 \leq j \leq n$, then $a_1 = 1$ and $a_2 = a_3 = 0 \Rightarrow a_j \cdot c = 1$.
- Case2: if $n + 1 \leq j \leq 2n$, then $a_2 = 1$ and $a_1 = a_3 = 0 \Rightarrow a_j \cdot c = 1$.
- Case3: if $2n + 1 \leq j \leq 3n$, then $a_3 = 1$ and $a_1 = a_2 = 0 \Rightarrow a_j \cdot c = 1$.

So, $a_j \cdot c = 1, 1 \leq j \leq 3n$, Therefore, A is a configuration matrix from Definition (2.10).

Theorem (3.2): The Grobner basis of an ideal I_A is $Gr = \{P_{i+l} P_{j+r} - P_{j+l} P_{i+r} : i, j = 1, 2, \dots, n$ and $l, r = 0, n, 2n$, such that $i \neq j$ and $l < r\}$.

Proof:

To prove Gr is a Grobner basis of an ideal I_A .

It is clear that $Gr \subseteq I_A$,

From Definition (2.6) we get the system of monomial $\{in_{<}(f) : 0 \neq f \in Gr\} = \{P_{i+l} P_{j+r} : i, j = 1, 2, \dots, n$ and $l, r = 0, n, 2n$, such that $i \neq j$ and $l < r\}$. And

$$in_{<}(I_A) = \langle in_{<}(f) : 0 \neq f \in I_A \rangle = \langle P_{i+l} P_{j+r}, P_{i+l}^2 P_{j+r} P_{j+s}, P_{i+l}^2 P_{j+r} P_{k+r}, P_{i+l}^2 P_{j+r}^2 P_{k+s}, P_{i+l}^2 P_{j+r}^2 P_{k+s}^2, P_{i+l}^2 P_{j+r}^2 P_{k+s}^2, P_{i+l}^2 P_{j+r} P_{k+s} : i, j, k = 1, 2, \dots, n$$
 and $l, s, r = 0, n, 2n$, such that $i \neq j \neq k$ and $l \neq s \neq r \rangle = \langle P_{i+l} P_{j+r} : i, j = 1, 2, \dots, n$ and $l, r = 0, n, 2n$, such that $i \neq j$ and $l \neq r \rangle$.

So, $in_{<}(I_A) = \langle in_{<}(f) : 0 \neq f \in Gr \rangle$, implies that the system of monomial $\{in_{<}(f) : 0 \neq f \in Gr\}$ generators of the initial ideal $in_{<}(I)$.

Then Gr is a Grobner basis of an ideal I_A .

Corollary (3.3): The Grobner basis Gr in Theorem (3.2) is a reduced Grobner basis.

Proof:

Since $Gr = \{P_{i+l} P_{j+r} - P_{j+l} P_{i+r} : i, j = 1, 2, \dots, n$ and $l, r = 0, n, 2n$, such that $i \neq j$ and $l < r\}$,

Suppose $f_1, f_2 \in Gr$, such that $in_{<}(f_2) \mid f$ where $f \in supp(f_1)$

Therefore, from Definition of Gr and Definition (2.5) we get

$$in_{<}(f_2) = P_{i+l} P_{j+r}, l < r$$

Then $supp(f_1) = \{P_{i+l} P_{j+r}, P_{j+l} P_{i+r}\}, l < r$.

From Definition of Gr and Definition (2.3) we get $f_1 = f_2 = P_{i+l} P_{j+r} - P_{j+l} P_{i+r}$.

Implies that Gr is a reduced Grobner basis from Definition (2.7).

Corollary (3.4): The Grobner basis Gr in Theorem (3.2) is a universal Grobner basis.

Proof:

It is clear that Gr is a universal Grobner basis because it is finite by using Theorem (3.2) and Definition (2.8).

Example (3.5): For $n = 2$, there are 18 moves in a Markov basis \mathbf{B} according to Theorem (2.14) for 3×2 -contingency table, then

$$\mathbf{B} = \left\{ \begin{array}{l} \left[\begin{array}{cc} 1 & -1 \\ -1 & 1 \end{array} \right], \left[\begin{array}{cc} 1 & -1 \\ 0 & 0 \end{array} \right], \left[\begin{array}{cc} 0 & 0 \\ 1 & -1 \end{array} \right], \left[\begin{array}{cc} -1 & 1 \\ 1 & -1 \end{array} \right], \left[\begin{array}{cc} -1 & 1 \\ 0 & 0 \end{array} \right], \left[\begin{array}{cc} 0 & 0 \\ -1 & 1 \end{array} \right], \\ \left[\begin{array}{cc} 2 & -2 \\ -2 & 2 \end{array} \right], \left[\begin{array}{cc} 2 & -2 \\ 0 & 0 \end{array} \right], \left[\begin{array}{cc} 0 & 0 \\ 2 & -2 \end{array} \right], \left[\begin{array}{cc} -2 & 2 \\ 2 & -2 \end{array} \right], \left[\begin{array}{cc} -2 & 2 \\ 0 & 0 \end{array} \right], \left[\begin{array}{cc} 0 & 0 \\ -2 & 2 \end{array} \right], \\ \left[\begin{array}{cc} 2 & -2 \\ -1 & 1 \end{array} \right], \left[\begin{array}{cc} -1 & 1 \\ 2 & -2 \end{array} \right], \left[\begin{array}{cc} -1 & 1 \\ -1 & 1 \end{array} \right], \left[\begin{array}{cc} -2 & 2 \\ 1 & -1 \end{array} \right], \left[\begin{array}{cc} 1 & -1 \\ -2 & 2 \end{array} \right], \left[\begin{array}{cc} 1 & -1 \\ 1 & -1 \end{array} \right], \left[\begin{array}{cc} 1 & -1 \\ -2 & 2 \end{array} \right] \end{array} \right\}$$

By Corollary (2.16) the toric ideal of 3×2 -contingency table

$$I_A = \langle P_1 P_4 - P_2 P_3, P_1 P_6 - P_2 P_5, P_3 P_6 - P_4 P_5, P_1^2 P_4 P_6 - P_2^2 P_3 P_5, P_1 P_4^2 P_5 - P_2 P_3^2 P_6, P_1 P_3 P_6^2 - P_2 P_4 P_5^2 \rangle \subset \mathbb{C}[P_1, P_2, P_3, P_4, P_5, P_6].$$

And from Theorem (3.2) the Grobner basis of an ideal I_A is $Gr = \{P_1 P_4 - P_2 P_3, P_1 P_6 - P_2 P_5, P_3 P_6 - P_4 P_5\}$, since

$$P_1^2 P_4 P_6 - P_2^2 P_3 P_5 = P_1 P_6 (P_1 P_4 - P_2 P_3) + P_2 P_3 (P_1 P_6 - P_2 P_5).$$

So $P_1^2 P_4 P_6 - P_2^2 P_3 P_5 \in \langle P_1 P_4 - P_2 P_3, P_1 P_6 - P_2 P_5 \rangle \subseteq \langle Gr \rangle$.

Moreover, in the same type we have $P_1 P_4^2 P_5 - P_2 P_3^2 P_6, P_1 P_3 P_6^2 - P_2 P_4 P_5^2 \in \langle Gr \rangle$

Implies that $I_A = \langle Gr \rangle$.

References

1. Aoki, S. and Takemura, A. **2008**. "The largest group of invariance for Markov bases and toric ideals", *J. Symbolic Computation*, **43**(5): 342–358.
2. Diaconis, P. and Sturmfels, B. **1998**. "Algebraic algorithms for sampling from conditional distributions", *The Annals of Statistics*, **26**: 363-397.
3. Diaconis, P., Eisenbud, D. and Sturmfels, B. **1998** "Lattice walks and primary decomposition", *Mathematical Essays in Honor of Gian-Carlo Rota*, eds. B. Sagan and R. Stanley, Progress in Mathematics, Vol. 161, Birkhauser, Boston, pp.173-193.
4. Dyer, M. and Greenhill, C. **2000** "Polynomial-time counting and sampling of two-rowed contingency tables", *Theoretical Computer Sciences*, **246**: 265-278.
5. Dobra, A. **2003** "Markov bases for decomposable graphical models", *Bernoulli*, **9**(6): 1093-1108.
6. Mohammed Hussein, H. S. and Majeed, A. H. **2018** "Toric Ideals for $(25n^3 - 66n^2 + 41n) \times 3 \times n$ - Contingency Tables", *Journal of Engineering and Applied Sciences*, accept.
7. Hibi, T. (Ed.) **2013** "Gröbner Bases-Statistics and Software Systems", Springer, Tokyo.
8. Christos, T. **2016**. "Generalized robust toric ideals", *Journal of Pure and Applied Algebra*, **220**(1): 263-277.