



ISSN: 0067-2904

On Skew Left $*-n$ -Derivations of $*-Ring$

Anwar Khaleel Faraj*, Ruqaya Saadi Hashem

Department of Applied Sciences, University of Technology, Baghdad, Iraq

Abstract

In this paper, the commutativity of $*-ring$ and some related results are obtained by introducing the new concept which is called skew left $*-n$ -derivations.

Keywords: Prime $*-ring$, semiprime $*-ring$, $*-n$ -derivation, permuting mapping, skew left $*-n$ -derivation.

حول المشتقات اليسارية الملتوية من النمط $-n$ للحلقات $*$

انوار خليل فرج*، رقية سعدي هاشم

قسم العلوم التطبيقية، الجامعة التكنولوجية، بغداد، العراق

الخلاصة

في هذا البحث، ابدالية الحلقات $*$ و بعض النتائج المتعلقة بها قد تم الحصول عليها من خلال اعطاء مفهوم جديد يسمى المشتقة اليسارية الملتوية من النمط $-n$.

1. Introduction

Throughout this paper \mathcal{R} will represent an associative ring with center $Z(\mathcal{R})$. A ring \mathcal{R} is said to be n -torsion free if $na=0$ with $a \in \mathcal{R}$ then $a=0$, where n is nonzero integer [1]. For any $v, \gamma \in \mathcal{R}$, the commutator $v\gamma - \gamma v$ will be denoted by $[v, \gamma]$ and the anti-commutator $v \circ \gamma$ will be denoted by $v\gamma + \gamma v$ [2]. Recall that a ring \mathcal{R} is said to be prime if $a\mathcal{R}b=0$ implies that either $a=0$ or $b=0$ for all $a, b \in \mathcal{R}$ [3] and it is semiprime if $a\mathcal{R}a=0$ implies that $a=0$ for all $a \in \mathcal{R}$ [1]. An additive mapping $\xi: \mathcal{R} \rightarrow \mathcal{R}$ is called a derivation if $\xi(v\gamma) = \xi(v)\gamma + v\xi(\gamma)$ for all $v, \gamma \in \mathcal{R}$ [4]. An additive mapping $\xi: \mathcal{R} \rightarrow \mathcal{R}$ is called a left derivation if $\xi(v\gamma) = \gamma\xi(v) + v\xi(\gamma)$ for all $v, \gamma \in \mathcal{R}$ [5], it is clear that the concepts of derivation and left derivation are identical whenever \mathcal{R} is commutative. A map $\mathcal{F}: \mathcal{R} \rightarrow \mathcal{R}$ is said to be commuting (resp. centralizing) on \mathcal{R} if $[\mathcal{F}(v), v]=0$ (resp. $[\mathcal{F}(v), v] \in Z(\mathcal{R})$) for all $v \in \mathcal{R}$ [6]. An additive mapping $v \rightarrow v^*$ of \mathcal{R} into itself is called an involution if the following conditions are satisfied (i) $(v\gamma)^* = \gamma^*v^*$ (ii) $(v^*)^* = v$ for all $v, \gamma \in \mathcal{R}$ [2]. A ring equipped with an involution is known as ring with involution or $*-ring$. Let \mathcal{R} be a $*-ring$. An additive mapping $\xi: \mathcal{R} \rightarrow \mathcal{R}$ is called a $*-derivation$ if $\xi(v\gamma) = \xi(v)\gamma^* + v\xi(\gamma)$ for all $v, \gamma \in \mathcal{R}$ [7]. An additive mapping $\xi: \mathcal{R} \rightarrow \mathcal{R}$ is called a left $*-derivation$ $\xi(v\gamma) = \gamma^*\xi(v) + v\xi(\gamma)$ for all $v, \gamma \in \mathcal{R}$ [8]. There are many works dealing with the commutativity of prime and semi prime rings admitting certain types of derivations [4,5,9,10,11]. Bresar and Vukman [7] studied the notion of a $*-derivation$ of \mathcal{R} . Ali [12] defined symmetric $*-biderivation$ and studied some properties of prime $*-rings$ and semiprime $*-rings$. Recently Ashraf [13] defined the concept of $*-n$ -derivation in prime $*-rings$ and semiprime $*-rings$ and studied the commutativity and some of their properties. In the present paper we introduce the notion of skew left $*-n$ -derivation and study the commutativity and some related results involving skew left $*-n$ -derivations in $*-rings$.

*Email: anwar_78_2004@yahoo.com

2. Preliminaries

Some definitions and fundamental facts of skew left \ast - n -derivations are recalled in this section, which are principals of skew left \ast - n -derivation.

Proposition (2.1) [2]

Let \mathcal{R} be a ring, then for all $v, \gamma, z \in \mathcal{R}$ we have

- 1- $[v, \gamma z] = \gamma[v, z] + [v, \gamma]z$
- 2- $[v\gamma, z] = v[\gamma, z] + [v, z]\gamma$
- 3- $v \circ (\gamma z) = (v \circ \gamma)z - \gamma[v, z] = \gamma(v \circ z) + [v, \gamma]z$
- 4- $(v\gamma) \circ z = v(\gamma \circ z) - [v, z]\gamma = (v \circ z)\gamma + v[\gamma, z]$

Definition (2.2) [6]

A map $\xi: \mathcal{R}^n \rightarrow \mathcal{R}$ is called permuting (or symmetric) if the equation $\xi(v_1, v_2, \dots, v_n) = \xi(v_{\pi(1)}, v_{\pi(2)}, \dots, v_{\pi(n)})$ holds, for all $v_i \in \mathcal{R}$ and for every permutation $\{\pi(1), \pi(2), \dots, \pi(n)\}$.

Definition (2.3) [13]

An n -additive mapping $\xi: \mathcal{R}^n \rightarrow \mathcal{R}$ is said to be a \ast - n -derivation if the following equations are identical:

$$\xi(v_1\gamma, v_2, \dots, v_n) = \xi(v_1, v_2, \dots, v_n)\gamma^\ast + v_1\xi(\gamma, v_2, \dots, v_n)$$

$$\xi(v_1, v_2\gamma, \dots, v_n) = \xi(v_1, v_2, \dots, v_n)\gamma^\ast + v_2\xi(v_1, \gamma, \dots, v_n)$$

•
•
•

$$\xi(v_1, v_2, \dots, v_n\gamma) = \xi(v_1, v_2, \dots, v_n)\gamma^\ast + v_n\xi(v_1, v_2, \dots, \gamma), \text{ for all } v_1, \gamma, v_2, \dots, v_n \in \mathcal{R}.$$

Now we introduce the concept of skew left \ast - n -derivation to get our main results.

Definition (2.4)

Let \mathcal{R} be a \ast -ring. An n -additive symmetric mapping $\xi: \mathcal{R}^n \rightarrow \mathcal{R}$ is said to be a skew left \ast - n -derivation if

$$\xi(v_1\gamma, v_2, \dots, v_n) = \gamma^\ast \xi(v_1, v_2, \dots, v_n) + v_1\xi(\gamma, v_2, \dots, v_n)$$

$$\xi(v_1, v_2\gamma, \dots, v_n) = \gamma^\ast \xi(v_1, v_2, \dots, v_n) + v_2\xi(v_1, \gamma, \dots, v_n)$$

•
•
•

$$\xi(v_1, v_2, \dots, v_n\gamma) = \gamma^\ast \xi(v_1, v_2, \dots, v_n) + v_n\xi(v_1, v_2, \dots, \gamma), \text{ for all } v_1\gamma, v_2, \dots, v_n \in \mathcal{R}.$$

The following example explains the notion of skew left \ast - n -derivation.

Example (2.5):

Let $\mathcal{R} = \left\{ \begin{pmatrix} 0 & a \\ 0 & 0 \end{pmatrix} \mid a \in \mathbb{R} \right\}$ be a ring, and \mathbb{R} be a ring of real numbers. A map $\xi: \mathcal{R}^n \rightarrow \mathcal{R}$ define by

$$\xi\left(\begin{pmatrix} 0 & a_1 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & a_2 \\ 0 & 0 \end{pmatrix}, \dots, \begin{pmatrix} 0 & a_n \\ 0 & 0 \end{pmatrix}\right) = \begin{pmatrix} 0 & a_1 a_2 \dots a_n \\ 0 & 0 \end{pmatrix}, \text{ for all}$$

$$\begin{pmatrix} 0 & a_1 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & a_2 \\ 0 & 0 \end{pmatrix}, \dots, \begin{pmatrix} 0 & a_n \\ 0 & 0 \end{pmatrix} \in \mathcal{R}. \text{ And } r \rightarrow r^\ast \text{ such that } \begin{pmatrix} 0 & a \\ 0 & 0 \end{pmatrix}^\ast = \begin{pmatrix} 0 & -a \\ 0 & 0 \end{pmatrix}$$

Then it easy to check that ξ is skew left \ast - n -derivation.

3. The Main Results

We investigate the commutativity of \ast -ring and some related results by using the notion of skew left \ast - n -derivations.

Theorem (3.1): let \mathcal{R} be a prime \ast -ring and ξ be a skew left \ast - n -derivation. Then \mathcal{R} is commutative ring or $\xi = 0$

Proof:

Since ξ is a skew left \ast - n -derivation, then

$$\xi((v_1\gamma)z, v_2, \dots, v_n) = z^\ast \xi(v_1\gamma, v_2, \dots, v_n) + v_1\gamma\xi(z, v_2, \dots, v_n)$$

$$= z^\ast \gamma^\ast \xi(v_1, v_2, \dots, v_n) + z^\ast v_1\xi(\gamma, v_2, \dots, v_n) + v_1\gamma\xi(z, v_2, \dots, v_n) \dots \dots \dots (1)$$

Also we have

$$\xi(v_1(\gamma z), v_2, \dots, v_n) = (\gamma z)^\ast \xi(v_1, v_2, \dots, v_n) + v_1\xi(\gamma z, v_2, \dots, v_n)$$

$$= z^\ast \gamma^\ast \xi(v_1, v_2, \dots, v_n) + v_1 z^\ast \xi(\gamma, v_2, \dots, v_n) + v_1\gamma\xi(z, v_2, \dots, v_n), \text{ for all } v, \gamma, z, v_2, \dots, v_n \in \mathcal{R}. \dots \dots \dots (2)$$

Combining equations (1) and (2), to have

$$z^*v_1\xi(\gamma, v_2, \dots, v_n) = v_1z^*\xi(\gamma, v_2, \dots, v_n)$$

Putting z instead of z^* in the last equation, we obtain

$$zv_1\xi(\gamma, v_2, \dots, v_n) = v_1z\xi(\gamma, v_2, \dots, v_n) \dots\dots\dots (3)$$

$$[z, v_1]\xi(\gamma, v_2, \dots, v_n) = 0 \dots\dots\dots (4)$$

Replacing $z=vr$ in equation (4) and using it, to get $[z, v_1]r\xi(\gamma, v_2, \dots, v_n) = 0$

Let $\gamma=v_1$ in above equation, then

$$[z, v_1]\mathcal{R}\xi(v_1, v_2, \dots, v_n) = 0$$

Then either $[z, v_1]=0$, which mean that \mathcal{R} is commutative or $\xi(v_1, v_2, \dots, v_n)=0$.

Theorem (3.2): Let \mathcal{R} be a 2-torsion free prime $*$ -ring and ξ_1 be a skew left $*$ - n -derivation and ξ_2 be a $*$ - n -derivation such that if $\xi_1(v_1, v_2, \dots, v_n)\xi_2(\gamma_1, \gamma_2, \dots, \gamma_n) + \xi_2(v_1, v_2, \dots, v_n)\xi_1(\gamma_1, \gamma_2, \dots, \gamma_n) = 0$ for all $v_1, v_2, \dots, v_n, \gamma_1, \gamma_2, \dots, \gamma_n \in \mathcal{R}$ then either $\xi_1=0$ or $\xi_2=0$.

Proof:

$$\text{Since } \xi_1(v_1, v_2, \dots, v_n)\xi_2(\gamma_1, \gamma_2, \dots, \gamma_n) + \xi_2(v_1, v_2, \dots, v_n)\xi_1(\gamma_1, \gamma_2, \dots, \gamma_n) = 0 \dots\dots\dots (1)$$

Replacing $v_1=v_1z$ in equation (1) to get

$$\begin{aligned} 0 &= \xi_1(v_1z, v_2, \dots, v_n)\xi_2(\gamma_1, \gamma_2, \dots, \gamma_n) + \xi_2(v_1z, v_2, \dots, v_n)\xi_1(\gamma_1, \gamma_2, \dots, \gamma_n) \\ &= z^*\xi_1(v_1, v_2, \dots, v_n)\xi_2(\gamma_1, \gamma_2, \dots, \gamma_n) + v_1\xi_1(z, v_2, \dots, v_n)\xi_2(\gamma_1, \gamma_2, \dots, \gamma_n) + \\ & z^*\xi_2(v_1, v_2, \dots, v_n)\xi_1(\gamma_1, \gamma_2, \dots, \gamma_n) + v_1\xi_2(z, v_2, \dots, v_n)\xi_1(\gamma_1, \gamma_2, \dots, \gamma_n) \\ &= z^*\xi_1(v_1, v_2, \dots, v_n)\xi_2(\gamma_1, \gamma_2, \dots, \gamma_n) + \xi_2(v_1, v_2, \dots, v_n)z^*\xi_1(\gamma_1, \gamma_2, \dots, \gamma_n) \} + \\ & v_1\{\xi_1(z, v_2, \dots, v_n)\xi_2(\gamma_1, \gamma_2, \dots, \gamma_n) + \xi_2(z, v_2, \dots, v_n)\xi_1(\gamma_1, \gamma_2, \dots, \gamma_n)\} \dots\dots\dots (2) \end{aligned}$$

From equation (1) and equation (2)

$$z^*\xi_1(v_1, v_2, \dots, v_n)\xi_2(\gamma_1, \gamma_2, \dots, \gamma_n) + \xi_2(v_1, v_2, \dots, v_n)z^*\xi_1(\gamma_1, \gamma_2, \dots, \gamma_n) = 0$$

Let $z^*=z$ in above equation to obtain

$$z\xi_1(v_1, v_2, \dots, v_n)\xi_2(\gamma_1, \gamma_2, \dots, \gamma_n) + \xi_2(v_1, v_2, \dots, v_n)z\xi_1(\gamma_1, \gamma_2, \dots, \gamma_n) = 0 \dots\dots\dots (3)$$

Multiplying equation (3) from the right by $p\xi_1(r_1, r_2, \dots, r_n)$ to get

$$\begin{aligned} & z\xi_1(v_1, v_2, \dots, v_n)\xi_2(\gamma_1, \gamma_2, \dots, \gamma_n)p\xi_1(r_1, r_2, \dots, r_n) + \\ & \xi_2(v_1, v_2, \dots, v_n)z\xi_1(\gamma_1, \gamma_2, \dots, \gamma_n)p\xi_1(r_1, r_2, \dots, r_n) = 0, \text{ for all } v_1, v_2, \dots, v_n, \gamma_1, \gamma_2, \dots, \gamma_n, r_1, r_2, \dots, r_n \in \mathcal{R} \end{aligned} \dots\dots\dots (4)$$

Equation (3) gives us

$$z\xi_1(v_1, v_2, \dots, v_n)\xi_2(\gamma_1, \gamma_2, \dots, \gamma_n) = -\xi_2(v_1, v_2, \dots, v_n)z\xi_1(\gamma_1, \gamma_2, \dots, \gamma_n)$$

Since \mathcal{R} is a 2-torsion, then equation (4) becomes

$$\xi_2(v_1, v_2, \dots, v_n)\mathcal{R}\xi_1(\gamma_1, \gamma_2, \dots, \gamma_n)\mathcal{R}\xi_1(r_1, r_2, \dots, r_n) = 0$$

By $*$ -primeness of \mathcal{R} , either

$\xi_2(v_1, v_2, \dots, v_n) = 0$ or $\xi_1(r_1, r_2, \dots, r_n) = 0$, for all $v_1, v_2, \dots, v_n, r_1, r_2, \dots, r_n \in \mathcal{R}$. That is, either $\xi_1=0$ or $\xi_2=0$.

Theorem (3.3): Let \mathcal{R} be a semiprime $*$ -ring admitting a non-zero skew left $*$ - n -derivation ξ . Then $\xi(\mathcal{R}, \mathcal{R}, \dots, \mathcal{R}) \subseteq \mathcal{Z}$.

Proof:

Replacing v_1 by $\xi(v_1, v_2, \dots, v_n)r$ in equation (3) of theorem (3.1), to get

$$z\xi(v_1, v_2, \dots, v_n)r\xi(\gamma, v_2, \dots, v_n) = \xi(v_1, v_2, \dots, v_n)r z\xi(\gamma, v_2, \dots, v_n)$$

That is,

$$\begin{aligned} 0 &= z\xi(v_1, v_2, \dots, v_n)r\xi(\gamma, v_2, \dots, v_n) - \xi(v_1, v_2, \dots, v_n)r z\xi(\gamma, v_2, \dots, v_n) \\ &= [z, \xi(v_1, v_2, \dots, v_n)r]\xi(\gamma, v_2, \dots, v_n) \\ &= [z, \xi(v_1, v_2, \dots, v_n)]r\xi(\gamma, v_2, \dots, v_n) + \xi(v_1, v_2, \dots, v_n)[z, r]\xi(\gamma, v_2, \dots, v_n) \end{aligned}$$

By using equation (4) of theorem (3.1) in the last equation to get

$$[z, \xi(v_1, v_2, \dots, v_n)]r\xi(\gamma, v_2, \dots, v_n) = 0 \dots (1)$$

Multiply equation (1) from the right by z , to get

$$[z, \xi(v_1, v_2, \dots, v_n)]r\xi(\gamma, v_2, \dots, v_n)z = 0 \dots (2)$$

Replacing $r=rz$ in equation (1) where $r, z \in \mathcal{R}$, to get

$$[z, \xi(v_1, v_2, \dots, v_n)]r z\xi(\gamma, v_2, \dots, v_n)z = 0 \dots (3)$$

Comparing equation (2) and (3) to obtain

$$[z, \xi(v_1, v_2, \dots, v_n)]r\xi(\gamma, v_2, \dots, v_n)z = [z, \xi(v_1, v_2, \dots, v_n)]r z\xi(\gamma, v_2, \dots, v_n)$$

This means that

$$[z, \xi(v_1, v_2, \dots, v_n)]r[z, \xi(\gamma, v_2, \dots, v_n)] = 0, \text{ for all } z, \gamma, r, v_1, v_2, \dots, v_n \in \mathcal{R}. \text{ Now put } \gamma=v_1 \text{ to get}$$

$$[z, \xi(v_1, v_2, \dots, v_n)]\mathcal{R}[z, \xi(v_1, v_2, \dots, v_n)] = 0$$

This gives

$$[z, \xi(v_1, v_2, \dots, v_n)]^* \mathcal{R} [z, \xi(v_1, v_2, \dots, v_n)]^* = 0$$

By the *-semiprime of \mathcal{R} , yields that

$$[z, \xi(v_1, v_2, \dots, v_n)] = 0 \text{ and this means that, } \xi(\mathcal{R}, \mathcal{R}, \dots, \mathcal{R}) \subseteq \mathcal{Z}.$$

Recall that an additive mapping $\xi : \mathcal{R} \rightarrow \mathcal{R}$ is called a left multiplier if $\xi(v\gamma) = \xi(v)\gamma$ [12].

Theorem (3.4): Let \mathcal{R} be a semiprime *-ring and ξ be a skew left *-n-derivation such that $\xi(v_1, v_2, \dots, v_n)\gamma_1 = v_1\xi(\gamma_1, \gamma_2, \dots, \gamma_n)$ for all $v_1, v_2, \dots, v_n, \gamma_1, \gamma_2, \dots, \gamma_n \in \mathcal{R}$. Then ξ is a left multiplier.

Proof:

By hypothesis,

$$\xi(v_1, v_2, \dots, v_n)\gamma_1 = v_1\xi(\gamma_1, \gamma_2, \dots, \gamma_n), \text{ for all } v_1, v_2, \dots, v_n, \gamma_1, \gamma_2, \dots, \gamma_n \in \mathcal{R}. \dots\dots\dots (1)$$

Replacing γ_1 by $\gamma_1 z$ in equation (1) and since ξ is a skew left *-n-derivation, then

$$\xi(v_1, v_2, \dots, v_n)\gamma_1 z = v_1 z^* \xi(\gamma_1, \gamma_2, \dots, \gamma_n) + v_1 \gamma_1 \xi(z, \gamma_2, \dots, \gamma_n)$$

Again by using equation (1) in the last equation

$$v_1 \xi(\gamma_1, \gamma_2, \dots, \gamma_n) z = v_1 z^* \xi(\gamma_1, \gamma_2, \dots, \gamma_n) + v_1 \gamma_1 \xi(z, \gamma_2, \dots, \gamma_n)$$

Using z instead of z^* to obtain

$$v_1 \xi(\gamma_1, \gamma_2, \dots, \gamma_n) z = v_1 z \xi(\gamma_1, \gamma_2, \dots, \gamma_n) + v_1 \gamma_1 \xi(z, \gamma_2, \dots, \gamma_n)$$

By applying equation (1) on left side of last equation to get

$$v_1 \gamma_1 \xi(z, \gamma_2, \dots, \gamma_n) = v_1 z \xi(\gamma_1, \gamma_2, \dots, \gamma_n) + v_1 \gamma_1 \xi(z, \gamma_2, \dots, \gamma_n) \text{ and this mean that}$$

$$v_1 z \xi(\gamma_1, \gamma_2, \dots, \gamma_n) = 0, \text{ for all } v_1, z, \gamma_1, \gamma_2, \dots, \gamma_n \in \mathcal{R} \dots\dots\dots (2)$$

Replacing v_1 by $\xi(\gamma_1, \gamma_2, \dots, \gamma_n)$ in equation (2) then

$$\xi(\gamma_1, \gamma_2, \dots, \gamma_n) z \xi(\gamma_1, \gamma_2, \dots, \gamma_n) = 0, \text{ for all } \gamma_1, \gamma_2, \dots, \gamma_n, z \in \mathcal{R} \text{ and this gives}$$

$$\xi(\gamma_1, \gamma_2, \dots, \gamma_n) \mathcal{R} \xi(\gamma_1, \gamma_2, \dots, \gamma_n) = 0, \text{ for all } \gamma_1, \gamma_2, \dots, \gamma_n \in \mathcal{R}$$

This implies that

$$\xi(\gamma_1, \gamma_2, \dots, \gamma_n)^* \mathcal{R} \xi(\gamma_1, \gamma_2, \dots, \gamma_n)^* = 0$$

Using *-semiprimeness leads to ξ is a left multiplier.

Theorem (3.5): Let \mathcal{R} be a semiprime *-ring and If \mathcal{R} admits a skew left *-n-derivation ξ of \mathcal{R}^n , then ξ a maps from \mathcal{R}^n to $\mathcal{Z}(\mathcal{R})$.

Proof:

$$\text{By hypothesis } \xi(v\gamma, v_2, \dots, v_n) = \gamma^* \xi(v, v_2, \dots, v_n) + v \xi(\gamma, v_2, \dots, v_n) \dots\dots\dots (1)$$

Let $\gamma = \gamma z$ in equation (1), to get

$$\begin{aligned} \xi(v\gamma z, v_2, \dots, v_n) &= (\gamma z)^* \xi(v, v_2, \dots, v_n) + v \xi(\gamma z, v_2, \dots, v_n) \\ &= z^* \gamma^* \xi(v, v_2, \dots, v_n) + z^* v \xi(\gamma, v_2, \dots, v_n) + v \gamma \xi(z, v_2, \dots, v_n), \text{ for all } v, \gamma, z, v_2, \dots, v_n \in \mathcal{R}. \dots\dots\dots (2) \end{aligned}$$

On the other hand

$$\begin{aligned} \xi(v\gamma z, v_2, \dots, v_n) &= z^* \xi(v\gamma, v_2, \dots, v_n) + v \gamma \xi(z, v_2, \dots, v_n) \\ &= z^* \gamma^* \xi(v, v_2, \dots, v_n) + z^* v \xi(\gamma, v_2, \dots, v_n) + v \gamma \xi(z, v_2, \dots, v_n) \dots\dots\dots (3) \end{aligned}$$

Comparing equations (2) and (3) to have

$$[v, z^*] \xi(\gamma, v_2, \dots, v_n) = 0$$

Replacing $z^* = z$ in last equation to obtain

$$[v, z] \xi(\gamma, v_2, \dots, v_n) = 0, \text{ for all } v, \gamma, z, v_2, \dots, v_n \in \mathcal{R} \dots\dots\dots (4)$$

Replacing $\xi(\gamma, v_2, \dots, v_n)v$ instead of v in equation (4) and using it then

$$[\xi(\gamma, v_2, \dots, v_n), z] v \xi(\gamma, v_2, \dots, v_n) = 0 \dots\dots\dots (5)$$

Let $v = v z$ in equation (5). Then

$$[\xi(\gamma, v_2, \dots, v_n), z] v z \xi(\gamma, v_2, \dots, v_n) = 0 \dots\dots\dots (6)$$

Now, multiplying equation (5) from the right side by z

$$[\xi(\gamma, v_2, \dots, v_n), z] v \xi(\gamma, v_2, \dots, v_n) z = 0 \dots\dots\dots (7)$$

Comparing equations (6) and (7) to get

$$[\xi(\gamma, v_2, \dots, v_n), z] v [\xi(\gamma, v_2, \dots, v_n), z] = 0, \text{ hence}$$

$[\xi(\gamma, v_2, \dots, v_n), z] \mathcal{R} [\xi(\gamma, v_2, \dots, v_n), z] = 0$. Since \mathcal{R} is semiprime *-ring $[\xi(\gamma, v_2, \dots, v_n), z] = 0$, for all $\gamma, z, v_2, \dots, v_n \in \mathcal{R}$. Hence ξ is a map \mathcal{R}^n into $\mathcal{Z}(\mathcal{R})$.

Theorem (3.6): Let \mathcal{R} be a prime *-ring. If \mathcal{R} admits a skew left *-n-derivation ξ of \mathcal{R}^n such that $\xi(v, v_2, \dots, v_n) \neq v$ and $\xi(v\gamma, v_2, \dots, v_n) = \xi(v, v_2, \dots, v_n)\xi(\gamma, v_2, \dots, v_n)$ for all $v, \gamma, v_2, \dots, v_n \in \mathcal{R}$, then $\xi = 0$.

Proof:

By hypothesis

$$\xi(v\gamma, v_2, \dots, v_n) = \gamma^* \xi(v, v_2, \dots, v_n) + v \xi(\gamma, v_2, \dots, v_n) = \xi(v, v_2, \dots, v_n) \xi(\gamma, v_2, \dots, v_n) \dots \dots \dots (1)$$

Let $v=vz$ in equation (1) to get

$$\gamma^* \xi(v, v_2, \dots, v_n) \xi(z, v_2, \dots, v_n) + vz \xi(\gamma, v_2, \dots, v_n) = \xi(v, v_2, \dots, v_n) \xi(z, v_2, \dots, v_n) \xi(\gamma, v_2, \dots, v_n) = \xi(v, v_2, \dots, v_n) \xi(z\gamma, v_2, \dots, v_n) = \xi(v, v_2, \dots, v_n) \{ \gamma^* \xi(z, v_2, \dots, v_n) + z \xi(\gamma, v_2, \dots, v_n) \}$$

This implies that

$$[\gamma^*, \xi(v, v_2, \dots, v_n)] \xi(z, v_2, \dots, v_n) + (v - \xi(v, v_2, \dots, v_n)) z \xi(\gamma, v_2, \dots, v_n) = 0$$

By Theorem (3.5) the above equation becomes

$$(v - \xi(v, v_2, \dots, v_n)) z \xi(\gamma, v_2, \dots, v_n) = 0, \text{ for all } \gamma, z, v, v_2, \dots, v_n \in \mathcal{R}$$

That is, $(v - \xi(v, v_2, \dots, v_n)) \mathcal{R} \xi(\gamma, v_2, \dots, v_n) = 0$. Since \mathcal{R} is prime $*$ -ring then either $(v - \xi(v, v_2, \dots, v_n)) = 0$ or $\xi(\gamma, v_2, \dots, v_n) = 0$. But $\xi(v, v_2, \dots, v_n) \neq v$, then $\xi(\gamma, v_2, \dots, v_n) = 0$ for all $\gamma, v_2, \dots, v_n \in \mathcal{R}$.

Theorem (3.7): Let \mathcal{R} be a prime $*$ -ring and If \mathcal{R} admits a skew left $*$ - n -derivation ξ of \mathcal{R}^n such that $\xi(v, v_2, \dots, v_n) \neq v^*$ and $\xi(v\gamma, v_2, \dots, v_n) = \xi(\gamma, v_2, \dots, v_n) \xi(v, v_2, \dots, v_n)$ for all $v, \gamma, v_2, \dots, v_n \in \mathcal{R}$, then $\xi = 0$.

Proof:

By hypothesis

$$\xi(v\gamma, v_2, \dots, v_n) = \gamma^* \xi(v, v_2, \dots, v_n) + v \xi(\gamma, v_2, \dots, v_n) = \xi(\gamma, v_2, \dots, v_n) \xi(v, v_2, \dots, v_n) \dots (1)$$

Replacing $\gamma=v\gamma$ in equation (1) to get

$$\gamma^* v^* \xi(v, v_2, \dots, v_n) + v \xi(\gamma, v_2, \dots, v_n) \xi(v, v_2, \dots, v_n) = \xi(v\gamma, v_2, \dots, v_n) \xi(v, v_2, \dots, v_n) = \{ \gamma^* \xi(v, v_2, \dots, v_n) + v \xi(\gamma, v_2, \dots, v_n) \} \xi(v, v_2, \dots, v_n)$$

This implies that

$$\gamma^* v^* \xi(v, v_2, \dots, v_n) - \gamma^* \xi(v, v_2, \dots, v_n) \xi(v, v_2, \dots, v_n) = 0$$

$$\gamma^* (v^* - \xi(v, v_2, \dots, v_n)) \xi(v, v_2, \dots, v_n) = 0$$

Applying Theorem (3.5) to get

$$(v^* - \xi(v, v_2, \dots, v_n)) \gamma^* \xi(v, v_2, \dots, v_n) = 0$$

Hence, $(v^* - \xi(v, v_2, \dots, v_n)) \mathcal{R} \xi(v, v_2, \dots, v_n) = 0$. Since \mathcal{R} is prime $*$ -ring then $(v^* - \xi(v, v_2, \dots, v_n)) = 0$ or $\xi(v, v_2, \dots, v_n) = 0$. But $\xi(v, v_2, \dots, v_n) \neq v^*$, then $\xi(v, v_2, \dots, v_n) = 0$ for all $v, v_2, \dots, v_n \in \mathcal{R}$.

Theorem (3.8): Let \mathcal{R} be a prime $*$ -ring and $a \in \mathcal{R}$. If \mathcal{R} admits a skew left $*$ - n -derivation ξ of \mathcal{R}^n and $[\xi(v, v_2, \dots, v_n), a] = 0$, then either $\xi(a) = 0$ or $a \in Z(\mathcal{R})$.

Proof:

By hypothesis

$$0 = [\xi(v\gamma, v_2, \dots, v_n), a] = 0 = [\gamma^* \xi(v, v_2, \dots, v_n) + v \xi(\gamma, v_2, \dots, v_n), a] = 0, \text{ for all } v, \gamma, v_2, \dots, v_n \in \mathcal{R} \dots \dots \dots (1)$$

$$\text{Hence } [\gamma^*, a] \xi(v, v_2, \dots, v_n) + [v, a] \xi(\gamma, v_2, \dots, v_n) = 0 \dots \dots \dots (2)$$

Replacing v by a and γ^* by γ in equation (2) to get

$$[\gamma, a] \xi(a, v_2, \dots, v_n) = 0 \dots \dots \dots (3)$$

Replacing $\gamma=v\gamma$ in equation (3) and using it to get

$$[v, a] \gamma \xi(a, v_2, \dots, v_n) = 0, \text{ and this implies that } [v, a] \mathcal{R} \xi(a, v_2, \dots, v_n) = 0, \text{ since } \mathcal{R} \text{ is prime then either } a \in Z(\mathcal{R}) \text{ or } \xi(a, v_2, \dots, v_n) = 0 \text{ for all } a, v_2, \dots, v_n \in \mathcal{R}.$$

Theorem (3.9): Let \mathcal{R} be a semiprime $*$ -ring. If \mathcal{R} admits a skew left $*$ - n -derivation ξ of \mathcal{R} then $[\xi(v, v_2, \dots, v_n), z] = 0$ for all $v, z, v_2, \dots, v_n \in \mathcal{R}$.

Proof:

$$\text{By hypothesis } \xi(v\gamma, v_2, \dots, v_n) = \gamma^* \xi(v, v_2, \dots, v_n) + v \xi(\gamma, v_2, \dots, v_n) \dots \dots \dots (1)$$

Substituting $\gamma=\gamma z$ in equation (1) we get

$$\xi(v\gamma z, v_2, \dots, v_n) = (\gamma z)^* \xi(v, v_2, \dots, v_n) + v \xi(\gamma z, v_2, \dots, v_n) = z^* \gamma^* \xi(v, v_2, \dots, v_n) + v z^* \xi(\gamma, v_2, \dots, v_n) + v \gamma \xi(z, v_2, \dots, v_n) \dots \dots \dots (2)$$

Also we have

$$\xi(v\gamma z, v_2, \dots, v_n) = z^* \xi(v\gamma, v_2, \dots, v_n) + v \gamma \xi(z, v_2, \dots, v_n) = z^* \gamma^* \xi(v, v_2, \dots, v_n) + z^* v \xi(\gamma, v_2, \dots, v_n) + v \gamma \xi(z, v_2, \dots, v_n) \dots \dots \dots (3)$$

Comparing equations (2) and (3) to get $[v, z^*] \xi(\gamma, v_2, \dots, v_n) = 0$

Let $z^*=z$ in above equation to get

$$[v, z] \xi(\gamma, v_2, \dots, v_n) = 0 \dots \dots \dots (4)$$

Replacing v by $\xi(\gamma, v_2, \dots, v_n)v$ in equation (4) and using it to get

$$[\xi(\gamma, v_2, \dots, v_n), z]v\xi(\gamma, v_2, \dots, v_n)=0 \quad \dots\dots\dots (5)$$

Let $v=vz$ in equations (5) then

$$[\xi(\gamma, v_2, \dots, v_n), z]vz\xi(\gamma, v_2, \dots, v_n)=0 \quad \dots\dots\dots (6)$$

Now, multiplying equation (5) from the right side by z we have

$$[\xi(\gamma, v_2, \dots, v_n), z]\xi(\gamma, v_2, \dots, v_n)z=0 \quad \dots\dots\dots (7)$$

Comparing equations (6) and (7) to get $[\xi(\gamma, v_2, \dots, v_n), z]v[\xi(\gamma, v_2, \dots, v_n), z]=0$

Hence $[\xi(\gamma, v_2, \dots, v_n), z]\mathcal{R}[\xi(\gamma, v_2, \dots, v_n), z]=0$. Since \mathcal{R} is semiprime \ast -ring then $[\xi(\gamma, v_2, \dots, v_n), z]=0$ for all $\gamma, z, v_2, \dots, v_n \in \mathcal{R}$.

Theorem (3.10): Let \mathcal{R} be a prime \ast -ring. If \mathcal{R} admits a skew left \ast - n -derivation ξ of \mathcal{R}^n such that $\xi([v, \gamma], v_2, \dots, v_n)=0$ for all $v, \gamma, v_2, \dots, v_n \in \mathcal{R}$ then $\xi=0$ or \mathcal{R} is commutative.

Proof:

$$\text{By hypothesis } \xi([v, \gamma], v_2, \dots, v_n)=0 \quad \dots\dots\dots (1)$$

Let $v=v\gamma$ in equation (1) and using it to get

$$[v, \gamma]\xi(\gamma, v_2, \dots, v_n)=0 \quad \dots\dots\dots (2)$$

Replacing $v=vz$ in equation (2) then

$$[v, \gamma]z\xi(\gamma, v_2, \dots, v_n)+v[z, \gamma]\xi(\gamma, v_2, \dots, v_n)=0$$

By using equation (2) the last equation to get

$[v, \gamma]z\xi(\gamma, v_2, \dots, v_n)=0$ and this implies that $[v, \gamma]\mathcal{R}\xi(\gamma, v_2, \dots, v_n)=0$. Since \mathcal{R} is prime then $[v, \gamma]=0$ and this means that \mathcal{R} is commutative, or $\xi(\gamma, v_2, \dots, v_n)=0$ for all $\gamma, v_2, \dots, v_n \in \mathcal{R}$.

Theorem (3.11): Let \mathcal{R} be a prime \ast -ring. If \mathcal{R} admits a skew left \ast - n -derivation ξ of \mathcal{R}^n such that $[\xi(v, v_2, \dots, v_n), \gamma]=[v, \gamma]$ for all $v, \gamma, v_2, \dots, v_n \in \mathcal{R}$ then $\xi=0$ or \mathcal{R} is commutative.

Proof:

$$\text{By hypothesis } [\xi(v, v_2, \dots, v_n), \gamma]=[v, \gamma] \quad \dots\dots\dots (1)$$

Let $v=vz$ in equation (1) to get

$$[\xi(vz, v_2, \dots, v_n), \gamma]=[vz, \gamma] \\ [z^*, \gamma]\xi(v, v_2, \dots, v_n)+z^*[\xi(v, v_2, \dots, v_n), \gamma]+[v, \gamma]\xi(z, v_2, \dots, v_n)+v[\xi(z, v_2, \dots, v_n), \gamma]=[v, \gamma]z+v[z, \gamma]$$

By using equation (1), the last equation can be reduced to

$$[z^*, \gamma]\xi(v, v_2, \dots, v_n)+z^*[v, \gamma]+[v, \gamma]\xi(z, v_2, \dots, v_n)+v[z, \gamma]=[v, \gamma]z+v[z, \gamma] \quad \dots\dots\dots (2)$$

Replacing $v=\gamma$ and $z^*=z$ in equation (2) to get

$$[z, \gamma]\xi(\gamma, v_2, \dots, v_n)=0 \quad \dots\dots\dots(3)$$

Replacing z by zr in equation (3) and using it to get

$$[z, \gamma]r\xi(\gamma, v_2, \dots, v_n)=0 \text{ for all } \gamma, r, z, v_2, \dots, v_n \in \mathcal{R}.$$

This implies that $[z, \gamma]\mathcal{R}\xi(\gamma, v_2, \dots, v_n)=0$. Since \mathcal{R} is prime then $\xi(\gamma, v_2, \dots, v_n)=0$ for all $\gamma, v_2, \dots, v_n \in \mathcal{R}$, or \mathcal{R} is commutative.

Theorem (3.12): Let \mathcal{R} be a prime \ast -ring. If \mathcal{R} admits a skew left \ast - n -derivation ξ of \mathcal{R}^n such that $\xi((v \circ \gamma), v_2, \dots, v_n)=0$ for all $v, \gamma, v_2, \dots, v_n \in \mathcal{R}$ then $\xi=0$ or \mathcal{R} is commutative.

Proof:

$$\text{By hypothesis } \xi((v \circ \gamma), v_2, \dots, v_n)=0 \quad \dots\dots\dots(1)$$

Let $v=v\gamma$ in equation (1) and using it to get

$$(v \circ \gamma)\xi(\gamma, v_2, \dots, v_n)=0 \quad \dots\dots\dots(2)$$

Replacing $v=sv$ in equation (2) then $(s \circ \gamma)v\xi(\gamma, v_2, \dots, v_n)=0$

Hence $(s \circ \gamma)\mathcal{R}\xi(\gamma, v_2, \dots, v_n)=0$. Since \mathcal{R} is prime \ast -ring then $(s \circ \gamma)=0$, replace $s=sz$ we get $s[z, \gamma]=0$. Now let $s=vs$ then we have $vs[z, \gamma]=0$, that $v\mathcal{R}[z, \gamma]=0$ for $0 \neq v \in \mathcal{R}$ and since \mathcal{R} is prime \ast -ring then \mathcal{R} is commutative, or $\xi(\gamma, v_2, \dots, v_n)=0$ for all $\gamma, v_2, \dots, v_n \in \mathcal{R}$.

Theorem (3.13): Let \mathcal{R} be a prime \ast -ring. If \mathcal{R} admits a skew left \ast - n -derivation ξ of \mathcal{R} such that $\xi(v, v_2, \dots, v_n) \circ \gamma=0$ for all $v, \gamma, v_2, \dots, v_n \in \mathcal{R}$ then $\xi=0$ or \mathcal{R} is commutative.

Proof:

$$\text{By hypothesis } \xi(v, v_2, \dots, v_n) \circ \gamma=0 \quad \dots\dots\dots (1)$$

Replacing $v=vz$ in equation (1) and using it to get

$$[\gamma, z^*]\xi(v, v_2, \dots, v_n) - [v, \gamma]\xi(z, v_2, \dots, v_n)=0 \quad \dots\dots\dots(2)$$

Let $v=\gamma$ and $z^*=z$ in equation (2) then

$$[\gamma, z]\xi(\gamma, v_2, \dots, v_n)=0 \quad \dots\dots\dots (3)$$

Replacing $z=vz$ in equation (3) and using it to get

$[\gamma, v]z\xi(\gamma, v_2, \dots, v_n)=0$ for all $v, \gamma, z, v_2, \dots, v_n \in \mathcal{R}$

This implies that $[\gamma, v]\mathcal{R}\xi(\gamma, v_2, \dots, v_n)=0$, since \mathcal{R} is prime then $\xi(\gamma, v_2, \dots, v_n)=0$ for all $\gamma, v_2, \dots, v_n \in \mathcal{R}$, or \mathcal{R} is commutative.

References

1. Herstein, I.N. **1969**. *Topics in Ring Theory*. The University of Chicago Press, Chicago.
2. Kim, K. H. and Lee, Y. H. **2017**. A Note on *-Derivation of Prime *-Rings. *International Mathematical Forum*, **12**(8): 391-398.
3. Sharma, U. K. and Kumar, S. **2017**. On Generalized *-n-Derivation in *-Ring. *Global Journal of Pure and Applied Math.*, **13**(10): 7561-7572.
4. Posner, E.C. **1957**. Derivations in Prime Rings. *Proc. Amer. Math.Soc*, **8**: 1093-1100.
5. Bresar, M. and Vukman, J. **1990**. On Left Derivations and Related Mappings. *Proc. Amer. Math. So.*, **110**(1): 7-16.
6. Park, K.H. **2009**. On Prime and Semiprime Rings with Symmetric n-Derivations. *J.Chungcheong Math.Soc.*, **22**(3): 451-458.
7. Bresar, M. and Vukman, J. **1989**. On Some Additive Mappings in Rings with involution. *Aequationes Math.*, **38**: 178-185.
8. Rehman, N., Ansari, A.Z. and Haetinger, C. **2013**. A Note on Homomorphisms and Anti-Homomorphisms on *-Ring. *Thai Journal of Mathematics*, **11**: 741-750.
9. Ashraf, M. and Rehman, N. **2001**. On Derivation and Commutativity in Prime Rings. *East West J.Math.*, **3**: 87-91.
10. Faraj, A. K. and Shareef, S. J. **2016**. Generalized Permuting 3-Derivations of Prime Rings. *Iraqi Journal of Science*, **57** (3C): 2312-2317.
11. Faraj, A. K. and Shareef, S. J. **2017**. On Generalized Permuting Left 3-Derivations of Prime Rings. *Engineering and Technology Journal*, **35 Part B** (1).
12. Ali, S. and Khan, M. S. **2011**. On *-Bimultipliers, Generalized *-Biderivations and Related Mappings. *Kyungpook Math. J.*, **51**(3):301-309.
13. Ashraf, M. and Siddeeqe, M.A. **2015**. On *-n-Derivations in Rings with involution. *Georgian Math. J.*, **22**(1): 9-18.