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Generalized Commuting Mapping in Prime and Semiprime Rings

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Abstract

Let R be an associative ring. The essential purpose of the present paper is to introduce the concept of generalized commuting mapping of R . Let U be a non-empty subset of R , a mapping $\mathcal{F}: R \rightarrow R$ is called a generalized commuting mapping on U if there exist a mapping $\mathcal{G}: R \rightarrow R$ such that $[\mathcal{F}(\omega), \mathcal{G}(\omega)] = 0$, holds for all $\omega \in U$. Some results concerning the new concept are presented.

Key words and phrases: Derivation, Semiderivations, Commuting mapping, Prime ring, Semiprime rings.

الدوال الأبدالية المعممة على الحلقات الأولية وشبه الأولية

عدي حكمت محمود

قسم الرياضيات، كلية التربية، الجامعة المستنصرية، بغداد، العراق

الخلاصة

لتكن R حلقة تجميعية. الغاية الأساسية من هذا البحث تقديم مفهوم الدوال الأبدالية المعممة على R . لتكن U مجموعة غير خالية من الحلقة R ، الدالة $\mathcal{F}: R \rightarrow R$ تسمى دالة أبدالية معممة إذا وجدت دالة $\mathcal{G}: R \rightarrow R$ تحقق أن $[\mathcal{F}(\omega), \mathcal{G}(\omega)] = 0$ ولكل $\omega \in U$. بعض النتائج المرتبطة بالمفهوم الجديد قدمت في هذا العمل.

1-Introduction

Throughout this paper, R will represent to an associative ring with center $Z(R)$. By \mathcal{Q}_R we will denote the Martindale ring of quotient of R . The extended centroid of R is refer to the center of \mathcal{Q}_R , which denote by \mathcal{C} , and the extended centroid is a field, furthermore $Z(R) \subseteq \mathcal{C}$ [1]. Given $n \geq 2$, a ring R in which $nt = 0$ implies that $t = 0$ is called an n -torsion free ring [2]. We denote by $[\omega, t]$ to the commutator $\omega t - t\omega$. The commutator identities $[\omega t, s] = [\omega, s] t + \omega [t, s]$ and $[\omega, ts] = [\omega, t] s + t[\omega, s]$ are frequently used [3]. Recall that a ring R with a property that whenever $\omega R t = \{0\}$ implies either $\omega = 0$ or $t = 0$ is said to be a prime ring and is semiprime if whenever $\omega R \omega = (0)$ implies $\omega = 0$ [4]. An equivalent definition of this concept is given as follows: A ring R is said to be semiprime if whenever U is an ideal of R satisfies $U^k = (0)$ implies $U = (0)$ [5].

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An additive mapping $\delta: R \rightarrow R$ in which $[\delta(\tau), \tau] \in Z(R)$ whenever $\tau \in R$ is said to be centralizing on R . In a special case, δ is called commuting on R if $[\delta(\tau), \tau] = 0$, whenever $\tau \in R$ [6]. A mapping $d: R \rightarrow R$ is called a derivation of R if for any $\tau, t \in R$ we have $d(\tau + t) = d(\tau) + d(t)$ and $d(\tau t) = d(\tau)t + \tau d(t)$ [7]. By a semi derivation mapping of a ring R , we shall mean a mapping $\mathcal{D}: R \rightarrow R$ with additive property together with a mapping $\mathcal{G}: R \rightarrow R$ such that $\mathcal{D}(\tau t) = \mathcal{D}(\tau)\mathcal{G}(t) + \tau\mathcal{D}(t) = \mathcal{D}(\tau)t + \mathcal{G}(\tau)\mathcal{D}(t)$ and $\mathcal{D}(\mathcal{G}(\tau)) = \mathcal{G}(\mathcal{D}(\tau))$ [8].

In this work, the notions of generalized commuting mapping are introduced. Furthermore, we investigate some necessary conditions that make every \mathcal{G} -commuting mapping a commuting mapping on R .

2. Preliminary results:

We begin this section by introducing the concept of generalized commuting mapping.

Definition 2.1:

Let R be a ring and U be a non-trivial subset of R . An additive mapping $\mathfrak{F}: R \rightarrow R$ is said to be a generalized commuting mapping (or \mathcal{G} -commuting mapping) on U if there exist a mapping $\mathcal{G}: R \rightarrow R$ such that $[\mathfrak{F}(\omega), \mathcal{G}(\omega)] = 0$, fulfilled for all $\omega \in U$.

Remark 2.2:

Every commuting mapping ρ is a generalized commuting mapping \mathcal{I} -commuting mapping, where \mathcal{I} is the identity mapping, but the converse is not true in general as we see in the following illustrative example:

Example 2.3:

Let R be a ring having a nilpotent $0 \neq a \in R$ with $a^2 = 0$ and let U be the right ideal of R generated by a . Define mappings $\mathfrak{F}, \mathcal{G}: R \rightarrow R$ by $\mathcal{G}(t) = [a, t]$ and $\mathfrak{F}(t) = ta$. Then, \mathfrak{F} is \mathcal{G} -commuting mapping on U but not commuting.

We list some remarks and Lemmas which will be needed throughout this paper.

Lemma 2.4: [9]

Let R be a 2-torsion free semiprime ring and let $a, b \in R$. then the following conditions are equivalent:

- i. $a u b = 0$, for all $u \in R$.
- ii. $b u a = 0$, for all $u \in R$.
- iii. $a u b + b u a = 0$, for all $u \in R$.

Furthermore, $ab = ba = 0$ whenever any one of these conditions is fulfilled.

Lemma 2.5: [10]

Let R be a prime ring and \mathcal{C} be the extended centroid of R . Let $a, b \in R$ be such that $axb = bxa$ fulfilled for all $x \in R$. If $a \neq 0$, then there exists $\lambda \in \mathcal{C}$ with $b = \lambda a$.

Lemma 2.6: [11]

Let \mathfrak{K} be a semiprime ring of characteristic $\neq 2$ and $\mathfrak{F}: R \rightarrow R$ be a non-trivial derivation satisfies $[[\mathfrak{F}(u), u], \mathfrak{F}(u)] = 0$, for any $u \in \mathfrak{K}$, then \mathfrak{F} is a commuting mapping on \mathfrak{K} .

3. Results on generalized commuting mapping:

Theorem 3.1: Let R be a prime ring of characteristic $\neq 2$ and $\mathcal{F}, \mathcal{G}: R \rightarrow R$ are nonzero derivations such that \mathcal{F} is a \mathcal{G} -commuting mapping on R . Then either \mathcal{F} or \mathcal{G} forced to be commuting mapping on R .

Proof: By our hypothesis, we have:

$$[\mathcal{F}(\sigma), \mathcal{G}(\sigma)] = 0, \text{ for all } \sigma \in R. \tag{1}$$

A linearization of the relation (1) leads to:

$$[\mathcal{F}(\sigma), \mathcal{G}(\tau)] + [\mathcal{F}(\tau), \mathcal{G}(\sigma)] = 0, \text{ whenever } \sigma, \tau \in R. \tag{2}$$

Taking $\tau\sigma$ instead of τ in (2), we obtain:

$$[\mathcal{F}(\sigma), \mathcal{G}(\tau)]\sigma + \mathcal{G}(\tau)[\mathcal{F}(\sigma), \sigma] + [\mathcal{F}(\sigma), \tau]\mathcal{G}(\sigma) + \tau[\mathcal{F}(\sigma), \mathcal{G}(\sigma)] + [\mathcal{F}(\tau), \mathcal{G}(\sigma)]\sigma + \mathcal{F}(\tau)[\sigma, \mathcal{G}(\sigma)] + \tau[\mathcal{F}(\sigma), \mathcal{G}(\sigma)] + [\tau, \mathcal{G}(\sigma)]\mathcal{F}(\sigma) = 0, \text{ whenever } \sigma, \tau \in R.$$

Using (1) and (2), we get:

$$\mathcal{G}(\tau) [\mathcal{F}(\sigma), \sigma] + [\mathcal{F}(\sigma), \tau] \mathcal{G}(\sigma) + \mathcal{F}(\tau) [\sigma, \mathcal{G}(\sigma)] + [\sigma, \mathcal{G}(\sigma)] \mathcal{F}(\sigma) = 0, \text{ whenever } \sigma, \tau \in R \tag{3}$$

If we replace σ by $\sigma\tau$ in (3), then it implies that:

$$\mathcal{G}(\sigma) \tau [\mathcal{F}(\sigma), \sigma] + \sigma \mathcal{G}(\tau) [\mathcal{F}(\sigma), \sigma] + [\mathcal{F}(\sigma), \sigma] \tau \mathcal{G}(\sigma) + \sigma [\mathcal{F}(\sigma), \tau] \mathcal{G}(\sigma) + \mathcal{F}(\sigma) \tau [\sigma, \mathcal{G}(\sigma)] + \sigma \mathcal{F}(\tau) [\sigma, \mathcal{G}(\sigma)] + \sigma [\tau, \mathcal{G}(\sigma)] \mathcal{F}(\sigma) + [\sigma, \mathcal{G}(\sigma)] \tau \mathcal{F}(\sigma) = 0, \text{ whenever } \sigma, \tau \in R.$$

In view of (3), this relation reduces to:

$$\mathcal{G}(\sigma) \tau [\mathcal{F}(\sigma), \sigma] + [\mathcal{F}(\sigma), \sigma] \tau \mathcal{G}(\sigma) - \mathcal{F}(\sigma) \tau [\mathcal{G}(\sigma), \sigma] - [\mathcal{G}(\sigma), \sigma] \tau \mathcal{F}(\sigma) = 0, \text{ whenever } \sigma, \tau \in R. \tag{4}$$

The left multiplication of (4) by $\mathcal{F}(\sigma)$ gives:

$$\mathcal{F}(\sigma) \mathcal{G}(\sigma) \tau [\mathcal{F}(\sigma), \sigma] + \mathcal{F}(\sigma) [\mathcal{F}(\sigma), \sigma] \tau \mathcal{G}(\sigma) - \mathcal{F}(\sigma)^2 \tau [\mathcal{G}(\sigma), \sigma] - \mathcal{F}(\sigma) [\mathcal{G}(\sigma), \sigma] \tau \mathcal{F}(\sigma) = 0, \text{ whenever } \sigma, \tau \in R. \tag{5}$$

Putting $\mathcal{F}(\sigma) \tau$ instead of τ in (4) we get:

$$\mathcal{G}(\sigma) \mathcal{F}(\sigma) \tau [\mathcal{F}(\sigma), \sigma] + [\mathcal{F}(\sigma), \sigma] \mathcal{F}(\sigma) \tau \mathcal{G}(\sigma) - \mathcal{F}(\sigma)^2 \tau [\mathcal{G}(\sigma), \sigma] - [\mathcal{G}(\sigma), \sigma] \mathcal{F}(\sigma) \tau \mathcal{F}(\sigma) = 0, \text{ whenever } \sigma, \tau \in R. \tag{6}$$

The subtracting of (5) from (6) leads to:

$$\{\mathcal{G}(\sigma) \mathcal{F}(\sigma) \tau [\mathcal{F}(\sigma), \sigma] - \mathcal{F}(\sigma) \mathcal{G}(\sigma) \tau [\mathcal{F}(\sigma), \sigma]\} + \{[\mathcal{F}(\sigma), \sigma] \mathcal{F}(\sigma) \tau \mathcal{G}(\sigma) - \mathcal{F}(\sigma) [\mathcal{F}(\sigma), \sigma] \tau \mathcal{G}(\sigma)\} + \{\mathcal{F}(\sigma)^2 \tau [\mathcal{G}(\sigma), \sigma] - \mathcal{F}(\sigma)^2 \tau [\mathcal{G}(\sigma), \sigma]\} + \{\mathcal{F}(\sigma) [\mathcal{G}(\sigma), \sigma] \tau \mathcal{F}(\sigma) - [\mathcal{G}(\sigma), \sigma] \mathcal{F}(\sigma) \tau \mathcal{F}(\sigma)\}$$

In view of (1), the last relation reduces to:

$$[[\mathcal{F}(\sigma), \sigma], \mathcal{F}(\sigma)] \mathcal{G}(\sigma) + [\mathcal{F}(\sigma), [\mathcal{G}(\sigma), \sigma]] \tau \mathcal{F}(\sigma) = 0, \text{ whenever } \sigma, \tau \in R.$$

Now, in the above relation, the substitution $[\mathcal{F}(\sigma), \sigma]$ instead of τ ones and right multiplication by $[\mathcal{F}(\sigma), \sigma]$ in another gives:

$$[[\mathcal{F}(\sigma), \sigma], \mathcal{F}(\sigma)] \tau [\mathcal{F}(\sigma), \sigma] \mathcal{G}(\sigma) + [\mathcal{F}(\sigma), [\mathcal{G}(\sigma), \sigma]] \tau [\mathcal{F}(\sigma), \sigma] \mathcal{F}(\sigma) = 0, \text{ whenever } \sigma, \tau \in R.$$

$$[[\mathcal{F}(\sigma), \sigma], \mathcal{F}(\sigma)] \mathcal{G}(\sigma) [\mathcal{F}(\sigma), \sigma] + [\mathcal{F}(\sigma), [\mathcal{G}(\sigma), \sigma]] \tau \mathcal{F}(\sigma) [\mathcal{F}(\sigma), \sigma] = 0, \text{ whenever } \sigma, \tau \in R.$$

Comparing the above expressions, we get:

$$[[\mathcal{F}(\sigma), \sigma], \mathcal{F}(\sigma)] [[\mathcal{F}(\sigma), \sigma], \mathcal{G}(\sigma)] + [[\mathcal{G}(\sigma), \sigma], \mathcal{F}(\sigma)] \tau [[\mathcal{F}(\sigma), \sigma], \mathcal{F}(\sigma)] = 0, \text{ for all } \sigma, \tau \in R.$$

According to Jacobi identity and the commutator properties, the last relation can be written as:

$$[[\mathcal{F}(\sigma), \sigma], \mathcal{F}(\sigma)] [[\mathcal{F}(\sigma), \sigma], \mathcal{G}(\sigma)] + [[\mathcal{F}(\sigma), \sigma], \mathcal{G}(\sigma)] \tau [[\mathcal{F}(\sigma), \sigma], \mathcal{F}(\sigma)] = 0, \text{ whenever } \sigma, \tau \in R.$$

An application of lemma (2.4) it follows that:

$$[[\mathcal{F}(\sigma), \sigma], \mathcal{F}(\sigma)] [[\mathcal{F}(\sigma), \sigma], \mathcal{G}(\sigma)] = 0, \text{ whenever } \sigma, \tau \in R.$$

However, since R is a ring having primeness property, we get either $[[\mathcal{F}(\sigma), \sigma], \mathcal{F}(\sigma)] = 0$, whenever $\sigma \in R$, consequently \mathcal{F} is a commuting mapping on R, or

$$[[\mathcal{F}(\sigma), \sigma], \mathcal{G}(\sigma)] = 0, \text{ whenever } \sigma \in R. \tag{7}$$

Taking $z + \sigma$ instead of σ in (7), we see that

$$[[\mathcal{F}(\sigma), \sigma], \mathcal{G}(z)] + [[\mathcal{F}(\sigma), z], \mathcal{G}(\sigma)] + [[\mathcal{F}(z), \sigma], \mathcal{G}(\sigma)] + [[\mathcal{F}(\sigma), z], \mathcal{G}(z)] + [[\mathcal{F}(z), \sigma], \mathcal{G}(z)] + [[\mathcal{F}(z), z], \mathcal{G}(\sigma)] = 0, \text{ whenever } \sigma, z \in R.$$

The substitution $2z$ instead of z in above relation and comparing the new relation with the above, we get by 2-torsionity free of R:

$$[[\mathcal{F}(\sigma), z], \mathcal{G}(z)] + [[\mathcal{F}(z), \sigma], \mathcal{G}(z)] + [[\mathcal{F}(z), z], \mathcal{G}(\sigma)] = 0, \text{ whenever } \sigma, z \in R. \tag{8}$$

Now, we use a same procedure that used to get (4) from (2), we arrive at:

$$2[\mathcal{F}(z), z] \sigma [z, \mathcal{G}(z)] + [z, \mathcal{G}(z)] \sigma [\mathcal{F}(z), z] + \mathcal{F}(z) [\sigma, z] [z, \mathcal{G}(z)] + \mathcal{G}(z) \sigma [[\mathcal{F}(z), z], z] + [[\mathcal{F}(z), z], z] \sigma \mathcal{G}(z) = 0, \text{ whenever } \sigma, z \in R.$$

Putting $\mathcal{G}(z) \sigma$ instead of σ in the last relation, we obtain:

$$2[\mathcal{F}(z), z] \mathcal{G}(z) \sigma [z, \mathcal{G}(z)] + [z, \mathcal{G}(z)] \mathcal{G}(z) \sigma [\mathcal{F}(z), z] + \mathcal{F}(z)\mathcal{G}(z)[\sigma, z] [z, \mathcal{G}(z)] + \mathcal{F}(z) [\mathcal{G}(z), z] \sigma [z, \mathcal{G}(z)] + \mathcal{G}(z)^2 \sigma [[\mathcal{F}(z), z], z] + [[\mathcal{F}(z), z], z] \mathcal{G}(z) \sigma \mathcal{G}(z) = 0, \text{ whenever } \sigma, z \in R. \tag{9}$$

Multiply (9) from the left by $\mathcal{G}(z)$, we see

$$2 \mathcal{G}(z)[\mathcal{F}(z), z] \sigma [z, \mathcal{G}(z)] + \mathcal{G}(z)[z, \mathcal{G}(z)] \sigma [\mathcal{F}(z), z] + \mathcal{G}(z)\mathcal{F}(z)[\sigma, z] [z, \mathcal{G}(z)] + \mathcal{G}(z)^2 \sigma [[\mathcal{F}(z), z], z] + \mathcal{G}(z)[[\mathcal{F}(z), z], z] \sigma \mathcal{G}(z) = 0, \text{ whenever } \sigma, z \in R. \tag{10}$$

Subtracting (10) from (9) leads to:

$$2[[\mathcal{F}(z), z], \mathcal{G}(z)] \sigma [z, \mathcal{G}(z)] + [[z, \mathcal{G}(z)], \mathcal{G}(z)] \sigma [\mathcal{F}(z), z] + [\mathcal{F}(z), \mathcal{G}(z)][\sigma, z] [z, \mathcal{G}(z)] + [[[\mathcal{F}(z), z], z], \mathcal{G}(z)] \sigma \mathcal{G}(z) + \mathcal{F}(z) [\mathcal{G}(z), z] \sigma [z, \mathcal{G}(z)] = 0, \text{ whenever } \sigma, z \in R.$$

By (7) and (1) the first and the third term are zeros respectively. So for any $\sigma, z \in R$, we have

$$[[z, \mathcal{G}(z)], \mathcal{G}(z)] \sigma [\mathcal{F}(z), z] + [[[\mathcal{F}(z), z], z], \mathcal{G}(z)] \sigma \mathcal{G}(z) + \mathcal{F}(z) [\mathcal{G}(z), z] \sigma [z, \mathcal{G}(z)] = 0.$$

Now, in the above relation the substitution $\mathcal{F}(z)$ for t ones and right multiplication by $\mathcal{F}(z)$ in another gives:

$$[[z, \mathcal{G}(z)], \mathcal{G}(z)] \sigma \mathcal{F}(z)[\mathcal{F}(z), z] + [[[\mathcal{F}(z), z], z], \mathcal{G}(z)] \sigma \mathcal{F}(z) \mathcal{G}(z) + \mathcal{F}(z) [\mathcal{G}(z), z] \sigma \mathcal{F}(z) [z, \mathcal{G}(z)] = 0, \text{ whenever } t, z \in R. \tag{11}$$

$$[[z, \mathcal{G}(z)], \mathcal{G}(z)] \sigma [\mathcal{F}(z), z] \mathcal{F}(z) + [[[\mathcal{F}(z), z], z], \mathcal{G}(z)] \sigma \mathcal{G}(z) \mathcal{F}(z) + \mathcal{F}(z) [\mathcal{G}(z), z] \sigma [z, \mathcal{G}(z)] \mathcal{F}(z) = 0, \text{ whenever } \sigma, z \in R. \tag{12}$$

Again, Subtracting (11) from (12) we get because of (1) and the commutator identity that:

$$[[, \mathcal{G}(z), z], \mathcal{G}(z)] \sigma [[\mathcal{F}(z), z], \mathcal{F}(z)] + \mathcal{F}(z) [\mathcal{G}(z), z] \sigma [[\mathcal{G}(z), z], \mathcal{F}(z)] = 0, \text{ whenever } \sigma, z \in R.$$

The last relation can be written because of Jacobi identity as:

$$[[, \mathcal{G}(z), z], \mathcal{G}(z)] \sigma [[\mathcal{F}(z), z], \mathcal{F}(z)] + \mathcal{F}(z) [\mathcal{G}(z), z] \sigma [[\mathcal{F}(z), z], \mathcal{G}(z)] - \mathcal{F}(z) [\mathcal{G}(z), z] \sigma [z, [\mathcal{G}(z), \mathcal{F}(z)]] = 0, \text{ whenever } \sigma, z \in R.$$

In view of (7) and (1), the above relation reduces to:

$$[[, \mathcal{G}(z), z], \mathcal{G}(z)] \sigma [[\mathcal{F}(z), z], \mathcal{F}(z)] = 0, \text{ whenever } \sigma, z \in R.$$

Using the primeness of R , since $[[\mathcal{F}(z), z], \mathcal{F}(z)] \neq 0$, for all $z \in R$, then

$$[[, \mathcal{G}(z), z], \mathcal{G}(z)] = 0, \text{ whenever } z \in R.$$

Finally, an application of Lemma (2.6) forced \mathcal{G} to be commuting on R .

Theorem 3.2: Let R be a prime ring and $\mathcal{D}: R \rightarrow R$ be a nonzero semiderivations with associated homomorphism $\mathcal{G}: R \rightarrow R$. If \mathcal{D} is a \mathcal{G} -commuting mapping on R , then either \mathcal{D} or \mathcal{G} is a commuting mapping on R .

Proof :

For any $t \in R$, we have:

$$[\mathcal{D}(t), \mathcal{G}(t)] = 0 \tag{13}$$

Setting $t = t + \omega$ in (13) and using (13), we get:

$$[\mathcal{D}(t), \mathcal{G}(\omega)] + [\mathcal{D}(\omega), \mathcal{G}(t)] = 0, \forall \omega, t \in R. \tag{14}$$

Putting $t\omega$ instead of ω in above relation, we find:

$$[\mathcal{D}(t), \mathcal{G}(t)] \mathcal{G}(\omega) + \mathcal{G}(t)[\mathcal{D}(t), \mathcal{G}(\omega)] + [\mathcal{D}(t), \mathcal{G}(t)] \omega + \mathcal{D}(t) [\omega, \mathcal{G}(t)] + \mathcal{G}(t) [\mathcal{D}(\omega), \mathcal{G}(t)] + [\mathcal{D}(t), \mathcal{G}(t)] \mathcal{D}(\omega) = 0, \forall \omega, t \in R.$$

In view of (13) and (14), the last relation reduces to:

$$\mathcal{D}(t) [\omega, \mathcal{G}(t)] = 0, \forall \omega, t \in R. \tag{15}$$

The substitution ωt for ω in (15) leads to:

$$\mathcal{D}(t) \omega [\mathcal{G}(t), t] = 0, \forall \omega, t \in R. \tag{16}$$

Now, in (16), the left multiplication by t ones and putting $t\omega$ instead of ω in another gives:

$$t \mathcal{D}(t) \omega [\mathcal{G}(t), t] = 0, \forall \omega, t \in R. \tag{17}$$

$$\mathcal{D}(t) t \omega [\mathcal{G}(t), t] = 0, \forall \omega, t \in R. \tag{18}$$

Subtracting (17) from (18) implies that:

$$[\mathcal{D}(t), t] \omega [\mathcal{G}(t), t] = 0, \forall \omega, t \in R.$$

Since R is prime, then we have either $[D(t), t] = 0$, for all $t \in R$, that is D is a commuting mapping on R or

$[G(t), t] = 0$, for all $t \in R$.

Hence, G is a commuting mapping on R .

Theorem 3.3: Let R be a prime ring of characteristic $\neq 2$ and $\mathcal{H}, \mathcal{K}: R \rightarrow R$ be a nonzero left centralizer such that \mathcal{H} is a \mathcal{K} -commuting mapping on R . Then, $[\mathcal{H}(t), t] = \lambda[\mathcal{K}(t), t]$, for all $t \in R$ and some $\lambda \in \mathcal{C}$.

Proof :

From our hypothesis, we have:

$$[\mathcal{H}(t), \mathcal{K}(t)] = 0, \text{ whenever } t \in R. \quad (19)$$

Taking $t+z$ instead of t in (19) gives

$$[\mathcal{H}(t), \mathcal{K}(z)] + [\mathcal{H}(z), \mathcal{K}(t)] = 0, \text{ whenever } t, z \in R.$$

Replacing z by zt in the last relation, we arrive because (19) that

$$\mathcal{K}(z) [\mathcal{H}(t), t] + \mathcal{H}(z) [t, \mathcal{K}(t)] = 0, \text{ whenever } t, z \in R. \quad (20)$$

Substituting tz for t in (20), we get:

$$\mathcal{K}(tz) [\mathcal{H}(t), t] + \mathcal{H}(tz) [t, \mathcal{K}(t)] = 0, \text{ whenever } t, z \in R. \quad (21)$$

Now, the left multiplication of (21) by z and putting instead of t in another gives

$$z \mathcal{K}(tz) [\mathcal{H}(t), t] + z \mathcal{H}(tz) [t, \mathcal{K}(t)] = 0, \text{ whenever } t, z \in R. \quad (22)$$

$$\mathcal{K}(t) tz [\mathcal{H}(t), t] + \mathcal{H}(t) tz [t, \mathcal{K}(t)] = 0, \text{ whenever } t, z \in R. \quad (23)$$

From relations (22) and (23), we obtain

$$[\mathcal{K}(t), t]z [\mathcal{H}(t), t] - [\mathcal{H}(t), t]z [\mathcal{K}(t), t] = 0, \text{ whenever } t, z \in R.$$

In view of Lemma (2.5), it follows that for some λ in the extended centroid of R , we have:

$$[\mathcal{H}(t), t] = \lambda[\mathcal{K}(t), t], \text{ whenever } t \in R.$$

Conclusions

In this article, we introduce the concept of generalized commuting mapping of a ring R . Some basic properties of this concept have been given and discussed. Furthermore, many results concerning with generalized commuting mapping have been investigated.

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