



On the Embedding of an Arc Into a Cubic Curves in a Finite Projective Plane of Order Five

Najm A. M. AL-Seraji*, Raad I. K. AL-Humaidi

Department of Mathematics, College of Science, University of Mustansiriyah, Baghdad, Iraq

Abstract:

The main aims of this research is to find the stabilizer groups of a cubic curves over a finite field of order 5, studying the properties of their groups and then constructing the arcs of degree 2 which are embedding in a cubic curves of even size which are considering as the arcs of degree 3. Also drawing all these arcs.

Keywords: Stabilizer groups , arcs , cubic curves .

حول غمر القوس الى المنحنيات المكعبة في المستوى الإسقاطي المنتهي من الرتبة الخامسة

نجم عبد الزهرة مخرب السراجي* ، رعد ابراهيم خويط الحميدي

قسم الرياضيات، كلية العلوم، الجامعة المستنصرية ، بغداد، العراق

الخلاصة

الاهداف الرئيسية لهذا البحث هو ايجاد الزمر المثبتة للمنحنيات المكعبة حول الحقل المنتهي من الرتبة 5 ، ودراسة الخواص لهذه الزمر، وكذلك تشكيل الأقواس من الدرجة الثانية والتي تغمر في المنحنيات المكعبة ذات الحجم الزوجي والتي نفسها تعتبر كأقواس من الدرجة الثانية . كذلك رسم كل هذه الأقواس .

1 . Introduction

The subject of this research depends on themes of

- Projective geometry over a finite field ;
- Group theory ;
- Field theory ;
- Linear algebra .

The strategy to construct the stabilizer groups and also to embedded the arcs is given as following: Constructing the linear transformations group $PGL(3, q)$ of $PG(2, q)$, where $q = 5$. Which its elements are considering the non-singular matrices $A_n = [a_{ij}]$, a_{ij} in F_q , $i, j = 1, 2, 3$ for some n in \mathbb{N} and satisfying $K(tA_n) = K$ for all t in $F_q \setminus \{0\}$ and K be any arc. The set of all matrices A_n which construct the group, and according to the number of A_n and its order, we are doing comparison with the groups in [1], so we can find which one of them similar with it. In another hand, we have found the arcs which are embedding in a cubic curves which are splitted into two sets, one of them contains the inflection points and the other does not, the set which does not contain the inflection points is considering the arc of degree two.

The summary history of this theme is shown as follows

- The ideas and definitions of this research are taken from James Hirshfeld [2] ;

*Email: dr.najm@uomustansiriyah.edu.iq

- In 2010, Najm Al-Seraji [3] has been studied the cubic curves over a finite field of order 17;
- In 2011, Emad Al-Zangana [4] has been shown the cubic curves over a finite field of order 19;
- In 2013, Emad Al-Zangana [5] has been described the cubic curves over a finite field of orders 2 , 3 , 5 , 7;
- In 2013, Emad Al-Zangana [6] has been classified the cubic curves over a finite field of order 11 , 13. For more details and information see also [7-9].

Now, we introduce the definitions which are using in this research as follows:

Definition (1.1)[2]: Denote by S and S^* two subspaces of $P(n, K)$. A projectivity $\beta: S \rightarrow S^*$ is a bijection given by a matrix T , necessarily non-singular, where $P(X) = P(X)\beta$ if $tX^* = XT$, with $t \in K$. Write $T = M(T)$; then $\beta = M(\lambda T)$ for any λ in K . The group of projectivities of $PG(n, K)$ is denoted by $PGL(n + 1, K)$.

Definition (1.2)[2]: The stabilizer of x in Λ (any non-empty set) under the action of G is the group $G_x = \{g \in G | xg = x\}$.

Definition (1.3)[2]: An $(n; r)$ arc K or arc of degree r in $PG(k, q)$ with $n \geq r + 1$ is a set of points with property that every hyperplane meets K in at most r points of K and there is some hyperplane meeting K in exactly r points.

2. The classification of cubic curves over a finite field of order 5

The polynomial of degree three $g_3(x) = x^3 - 4x - 1$ is primitive in $F_5 = \{0,1,2,3,4\}$, since $g_3(0) = -1, g_3(1) = 1, g_3(2) = -1, g_3(3) = -1, g_3(4) = 2$, also $g_3(\alpha^{48}) = 0, g_3(\alpha^{84}) = 0, g_3(\alpha^{116}) = 0$, this means $\alpha^{48}, \alpha^{84}, \alpha^{116}$ are roots of g_3 in F_{5^3} .

The companion matrix of $g_3(x) = x^3 - 4x - 1$ in $F_5[x]$ generated the points and lines of $PG(2,5)$ as follows:

$$P(k) = [1,0,0]C(g)^k = [1,0,0] \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 4 & 0 \end{pmatrix}^k, k=0,1, \dots, 30.$$

With selecting the points in $PG(2,5)$ which are the third coordinate equal to zero, this means belong to $L_0 = v(z)$, that is $v(z) = tz = z$ for all t in $F_5 \setminus \{0\}$ and with $P(k) = k$, we obtain $L_0 = \{0,1,3,8,12, 18\}$, that is

$$L_k = L_0 C(g)^k = L_0 \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 4 & 0 \end{pmatrix}^k, k=0,1, \dots, 30.$$

The number of distinct cubic curves in $PG(2,5)$ is 16 see [4], one of them is given as follows: $\theta_1 = xyz - (x + y + z)^3$ (1)

The points of $PG(2,5)$ on θ_1 in equation (1) are $[4,1,0], [0,4,1], [4,0,1], [3,2,1], [2,3,1], [2,4,1], [4,2,1], [3,4,1], [4,3,1]$. To find the stabilizer group of θ_1 in equation (1), we are doing calculations by help the computer. Thus the transformation matrices which stabilizing of θ_1 with their orders are shown as follows:

$$\begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix} : 2, \begin{pmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix} : 3, \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix} : 3, \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} : 2, \\ \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} : 2, \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} : 1, \begin{pmatrix} 1 & 2 & 1 \\ 1 & 1 & 2 \\ 2 & 1 & 1 \end{pmatrix} : 2, \begin{pmatrix} 2 & 1 & 1 \\ 1 & 1 & 2 \\ 1 & 2 & 1 \end{pmatrix} : 6, \\ \begin{pmatrix} 0 & 1 & 0 \\ 1 & 2 & 1 \\ 1 & 1 & 2 \end{pmatrix} : 6, \begin{pmatrix} 0 & 0 & 1 \\ 1 & 2 & 1 \\ 2 & 1 & 1 \end{pmatrix} : 2, \begin{pmatrix} 2 & 1 & 1 \\ 1 & 3 & 3 \\ 3 & 1 & 3 \end{pmatrix} : 2, \begin{pmatrix} 1 & 2 & 1 \\ 1 & 3 & 3 \\ 3 & 3 & 1 \end{pmatrix} : 2.$$

Therefore, the stabilizer group of θ_1 in equation (1) which is denoted by G_{θ_1} which contains

- 7 matrices of order 2;
- 2 matrices of order 3;
- 2 matrices of order 6;
- The identity matrix.

Form [1], G_{θ_1} is isomorphic to D_6 , that is $G_{\theta_1} \cong D_6$. θ_1 in equation (1) is drawn in Figure-1:

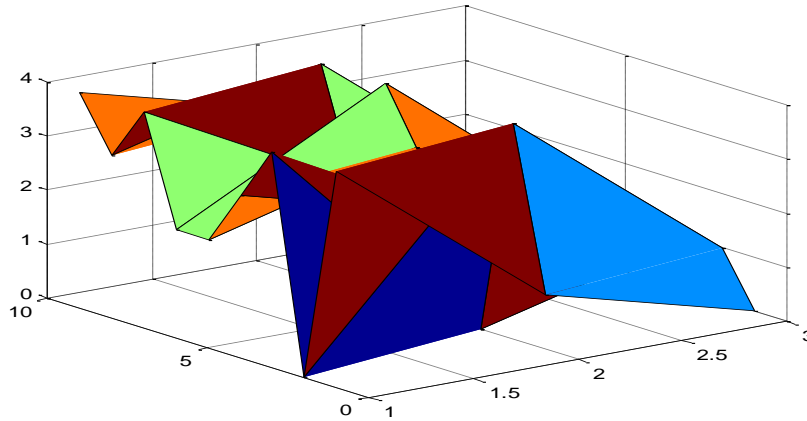


Figure 1-Drawing of θ_1

Another one of cubic curve which is given in [4] is:

$$\theta_2 = xyz + 2(x + y + z)^3 \dots(2)$$

The points of $PG(2,5)$ on θ_2 in equation (2) are $[4,1,0], [0,4,1], [4,0,1], [1,2,1], [3,3,1], [2,1,1], [1,1,1]$. To find the stabilizer group of θ_2 in equation (2), we are doing calculations by help the computer. Thus the transformation matrices which stabilizing of θ_2 with their orders are shown as follows:

$$\begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix} : 2, \begin{pmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix} : 3, \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix} : 3, \\ \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} : 2, \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} : 2, \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix} : 1.$$

Therefore, the stabilizer group of θ_2 in equation (2) which is denoted by G_{θ_2} which contains

- 3 matrices of order 2;
- 2 matrices of order 3;
- The identity matrix.

Form [1], G_{θ_2} is isomorphic to S_3 , that is $G_{\theta_2} \cong S_3$. θ_2 in equation (2) is drawn in Figure-2:

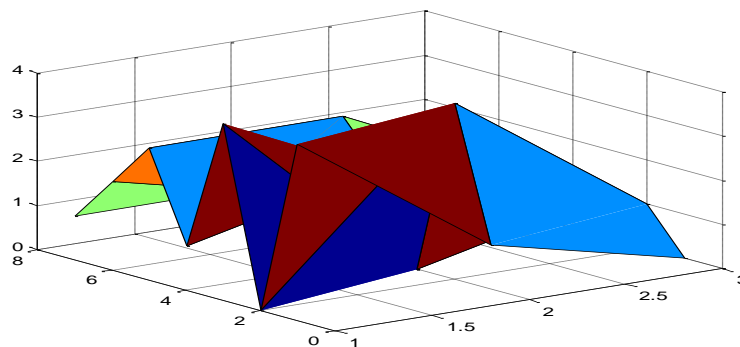


Figure 2-Drawing of θ_2

Another one of cubic curve which is given in [4] is :

$$\theta_3 = xy(x + y) + z^3 \dots(3)$$

The points of $PG(2,5)$ on θ_3 in equation (3) are $[1,0,0], [0,1,0], [4,1,0], [3,3,1], [3,4,1], [4,3,1]$. To find the stabilizer group of θ_3 in equation (3), we are doing calculations by help the computer. Thus the transformation matrices which stabilizing of θ_3 with their orders are shown as follows:

$$\begin{aligned}
 & \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} : 2, \begin{pmatrix} 0 & 1 & 0 \\ 2 & 2 & 4 \\ 3 & 1 & 3 \end{pmatrix} : 3, \begin{pmatrix} 0 & 1 & 0 \\ 3 & 4 & 1 \\ 2 & 4 & 2 \end{pmatrix} : 4, \begin{pmatrix} 0 & 1 & 0 \\ 4 & 1 & 0 \\ 0 & 0 & 4 \end{pmatrix} : 3, \\
 & \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix} : 1, \begin{pmatrix} 1 & 4 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 4 \end{pmatrix} : 2, \begin{pmatrix} 1 & 0 & 0 \\ 2 & 2 & 4 \\ 1 & 3 & 3 \end{pmatrix} : 2, \begin{pmatrix} 1 & 0 & 0 \\ 4 & 3 & 1 \\ 4 & 2 & 2 \end{pmatrix} : 2, \\
 & \begin{pmatrix} 1 & 1 & 2 \\ 0 & 3 & 0 \\ 4 & 3 & 4 \end{pmatrix} : 2, \begin{pmatrix} 1 & 1 & 2 \\ 1 & 3 & 2 \\ 1 & 2 & 1 \end{pmatrix} : 3, \begin{pmatrix} 1 & 1 & 2 \\ 3 & 0 & 0 \\ 3 & 4 & 4 \end{pmatrix} : 3, \begin{pmatrix} 1 & 1 & 2 \\ 3 & 1 & 2 \\ 2 & 1 & 1 \end{pmatrix} : 4, \\
 & \begin{pmatrix} 1 & 2 & 4 \\ 2 & 1 & 4 \\ 4 & 4 & 2 \end{pmatrix} : 2, \begin{pmatrix} 1 & 2 & 4 \\ 2 & 2 & 4 \\ 4 & 2 & 2 \end{pmatrix} : 3, \begin{pmatrix} 1 & 2 & 4 \\ 4 & 0 & 0 \\ 1 & 3 & 3 \end{pmatrix} : 4, \begin{pmatrix} 1 & 2 & 4 \\ 4 & 1 & 0 \\ 1 & 1 & 3 \end{pmatrix} : 3, \\
 & \begin{pmatrix} 1 & 3 & 2 \\ 0 & 2 & 0 \\ 4 & 3 & 4 \end{pmatrix} : 2, \begin{pmatrix} 1 & 3 & 2 \\ 1 & 1 & 2 \\ 1 & 3 & 2 \end{pmatrix} : 4, \begin{pmatrix} 1 & 3 & 2 \\ 3 & 1 & 2 \\ 2 & 2 & 1 \end{pmatrix} : 2, \begin{pmatrix} 1 & 3 & 2 \\ 3 & 2 & 0 \\ 3 & 3 & 4 \end{pmatrix} : 4, \\
 & \begin{pmatrix} 1 & 4 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 1 \end{pmatrix} : 2, \begin{pmatrix} 1 & 4 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 4 \end{pmatrix} : 3, \begin{pmatrix} 1 & 4 & 0 \\ 2 & 1 & 4 \\ 1 & 1 & 3 \end{pmatrix} : 3, \begin{pmatrix} 1 & 4 & 0 \\ 4 & 3 & 1 \\ 4 & 4 & 2 \end{pmatrix} : 4.
 \end{aligned}$$

Therefore, the stabilizer group of θ_3 in equation(3) which is denoted by G_{θ_3} which contains

- 9 matrices of order 2;
- 8 matrices of order 3;
- 6 matrices of order 4;
- The identity matrix.

Form [1], G_{θ_3} is isomorphic to S_4 , that is $G_{\theta_3} \cong S_4$. θ_3 in equation (3) is drawn in Figure-3:

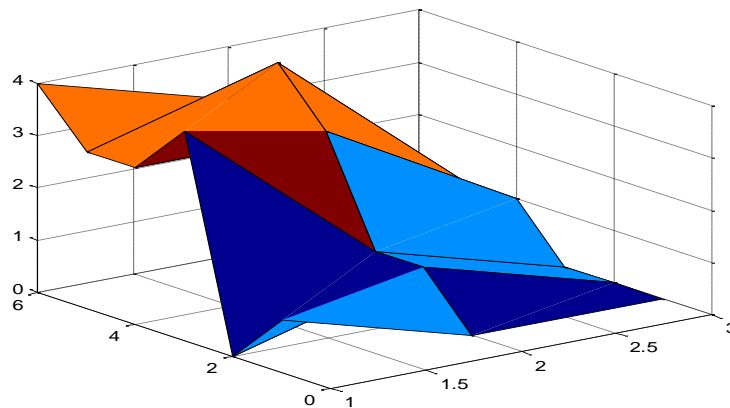


Figure 3-Drawing of θ_3

Let $\theta_3^* = \{[3,3,1], [3,4,1], [4,3,1]\}$ be a subset of θ_3 in equation (3) which is forming by partition the θ_3 into two sets such that θ_3^* does not contains the inflection points of θ_3 , so we note that θ_3^* represents an arc of degree two. After the calculation and help the computer, we are obtained that the number of matrices which are stabilizing of θ_3^* is 96, and we can not write them, because they are too much. Moreover, the stabilizer group of θ_3^* which is denoted by $G_{\theta_3^*}$ which contains

- 15 matrix of order 2;
- 32 matrix of order 3;
- 24 matrix of order 4;
- 24 matrix of order 8;
- The identity matrix.

Drawing of θ_3^* is given in Figure-4 as following:

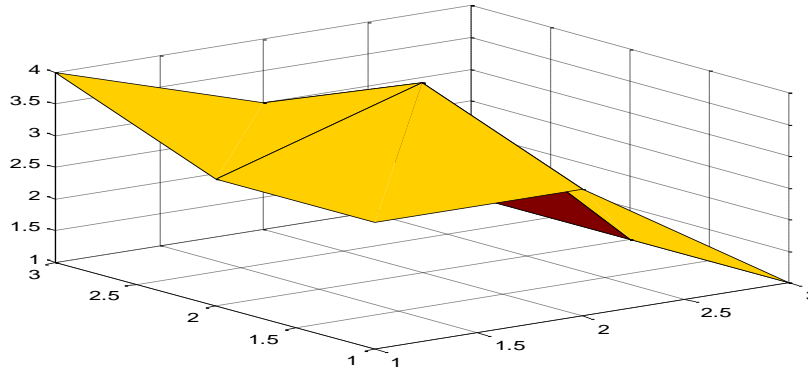


Figure 4-Drawing of θ_3^*

Another one of cubic curve which is given in [4] is:

$$\theta_4 = xyz + (x + y + z)^3 . \tag{4}$$

The points of $PG(2,5)$ on θ_4 in equation (4) are $[4,1,0], [0,4,1], [4,1,1], [1,4,1], [4,0,1], [4,4,1]$. To find the stabilizer group of θ_4 in equation (4), we are doing calculations by help the computer. Thus the transformation matrices which stabilizing of θ_4 with their orders are shown as follows:

$$\begin{aligned} & \begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix} : 2, \begin{pmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix} : 3, \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 1 & 3 \end{pmatrix} : 3, \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} : 2, \\ & \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} : 2, \begin{pmatrix} 0 & 1 & 0 \\ 0 & 1 & 0 \\ 3 & 4 & 1 \end{pmatrix} : 4, \begin{pmatrix} 1 & 1 & 3 \\ 4 & 3 & 1 \\ 3 & 4 & 1 \end{pmatrix} : 3, \\ & \begin{pmatrix} 0 & 1 & 0 \\ 1 & 2 & 2 \\ 2 & 1 & 3 \end{pmatrix} : 2, \begin{pmatrix} 0 & 0 & 1 \\ 1 & 2 & 2 \\ 2 & 3 & 1 \end{pmatrix} : 2, \begin{pmatrix} 4 & 3 & 1 \\ 1 & 2 & 3 \\ 2 & 1 & 2 \end{pmatrix} : 2, \begin{pmatrix} 3 & 2 & 1 \\ 1 & 2 & 3 \\ 3 & 2 & 1 \end{pmatrix} : 3, \\ & \begin{pmatrix} 2 & 3 & 1 \\ 1 & 2 & 4 \\ 2 & 1 & 4 \end{pmatrix} : 2, \begin{pmatrix} 2 & 1 & 3 \\ 1 & 2 & 4 \\ 4 & 4 & 2 \end{pmatrix} : 4, \begin{pmatrix} 3 & 2 & 1 \\ 1 & 3 & 1 \\ 3 & 1 & 4 \end{pmatrix} : 3, \begin{pmatrix} 1 & 2 & 1 \\ 1 & 3 & 1 \\ 4 & 1 & 3 \end{pmatrix} : 4, \\ & \begin{pmatrix} 4 & 4 & 2 \\ 1 & 3 & 2 \\ 2 & 2 & 1 \end{pmatrix} : 3, \begin{pmatrix} 2 & 1 & 4 \\ 1 & 3 & 2 \\ 3 & 1 & 2 \end{pmatrix} : 2, \begin{pmatrix} 4 & 3 & 1 \\ 1 & 3 & 4 \\ 1 & 4 & 3 \end{pmatrix} : 4, \begin{pmatrix} 3 & 1 & 4 \\ 3 & 1 & 1 \\ 1 & 4 & 3 \end{pmatrix} : 3, \\ & \begin{pmatrix} 3 & 1 & 2 \\ 1 & 4 & 2 \\ 2 & 4 & 1 \end{pmatrix} : 4, \begin{pmatrix} 2 & 2 & 1 \\ 1 & 4 & 2 \\ 4 & 2 & 4 \end{pmatrix} : 2, \begin{pmatrix} 3 & 1 & 1 \\ 1 & 4 & 3 \\ 1 & 3 & 4 \end{pmatrix} : 3, \begin{pmatrix} 1 & 4 & 3 \\ 3 & 1 & 1 \\ 1 & 3 & 4 \end{pmatrix} : 4 . \end{aligned}$$

Therefore, the stabilizer group of θ_4 in equation (4) which is denoted by G_{θ_4} which contains

- 9 matrices of order 2;
- 8 matrices of order 3;
- 6 matrices of order 4;
- The identity matrix.

Form [1], G_{θ_4} is isomorphic to S_4 , that is $G_{\theta_4} \cong S_4$. θ_4 in equation(4) is drawn in Figure-5:

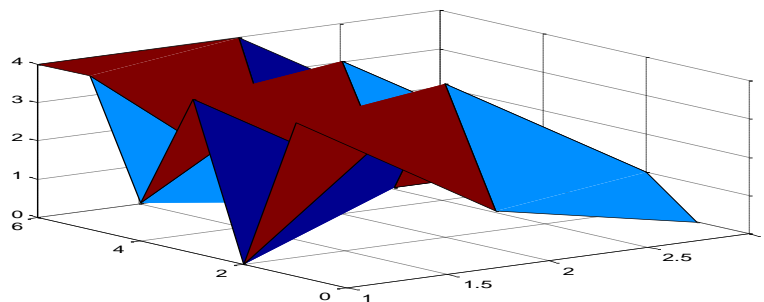


Figure 5-Drawing of θ_4

Let $\theta_4^* = \{[1,4,1], [4,0,1], [4,4,1]\}$ be a subset of θ_4 in equation (4) which is forming by partition θ_4 into two sets such that θ_4^* does not contains the inflection points of θ_4 , so we note that θ_4^* represents an arc of degree two. After the calculation and help the computer, we are obtained that the number of matrices which are stabilizing of θ_4^* is 96, and we can not write them, because they are too much. Moreover, the stabilizer group of θ_4^* which is denoted by $G_{\theta_4^*}$ which contains

- 15 matrix of order 2;
- 32 matrix of order 3;
- 24 matrix of order 4;
- 24 matrix of order 8;
- The identity matrix.

Drawing of θ_4^* is given in Figure-6 as following:

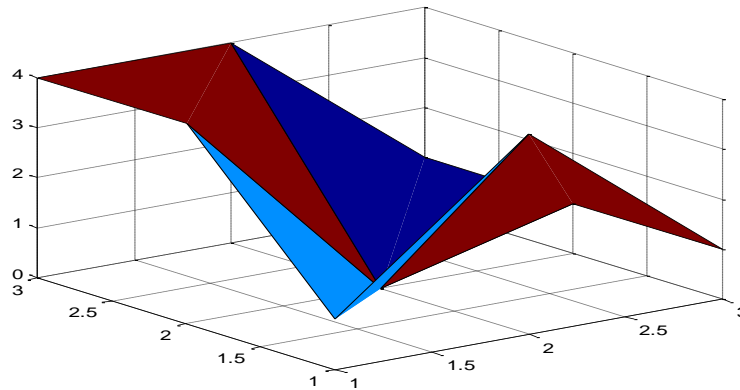


Figure 6 -Drawing of θ_4^*

Another one of cubic curve which is given in [4] is:

$$\theta_5 = yz^2 + x^3 - 2xy^2 - 2y^3. \tag{5}$$

The points of $PG(2,5)$ on θ_5 in equation (5) are $[0,0,1], [4,1,1], [1,4,1], [3,1,1], [2,4,1]$. To find the stabilizer group of θ_5 in equation (5), we are doing calculations by help the computer. Thus the transformation matrices which stabilizing of θ_5 with their orders are shown as follows:

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} : 1, \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 4 \end{pmatrix} : 2, \begin{pmatrix} 1 & 0 & 0 \\ 3 & 4 & 0 \\ 0 & 0 & 1 \end{pmatrix} : 2, \begin{pmatrix} 1 & 0 & 0 \\ 3 & 4 & 0 \\ 0 & 0 & 4 \end{pmatrix} : 2, \\ \begin{pmatrix} 1 & 1 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 2 \end{pmatrix} : 4, \begin{pmatrix} 1 & 1 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 3 \end{pmatrix} : 4, \begin{pmatrix} 1 & 1 & 0 \\ 3 & 4 & 0 \\ 0 & 0 & 2 \end{pmatrix} : 2, \begin{pmatrix} 1 & 1 & 0 \\ 3 & 4 & 0 \\ 0 & 0 & 3 \end{pmatrix} : 2.$$

Therefore, the stabilizer group of θ_5 in equation (5) which is denoted by G_{θ_5} which contains

- 5 matrices of order 2;
- 2 matrices of order 4;
- The identity matrix.

Form [1], G_{θ_5} is isomorphic to D_4 , that is $G_{\theta_5} \cong D_4$. θ_5 in equation (5) is drawn in Figure-7:

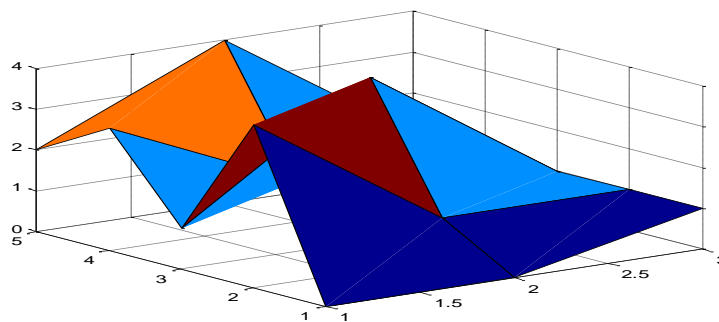


Figure 7-Drawing of θ_5

Another one of cubic curve which is given in [4] is:

$$\theta_6 = yz^2 + x^3 - xy^2 - y^3. \tag{6}$$

The points of $PG(2,5)$ on θ_6 in equation (6) are $[0,0,1], [0,4,1], [4,1,1], [0,1,1], [1,4,1], [2,1,0], [4,4,1], [1,1,1]$. To find the stabilizer group of θ_6 in equation (6), we are doing calculations by help the computer. Thus the transformation matrices which stabilizing of θ_6 with their orders are shown as follows:

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} : 1, \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 4 \end{pmatrix} : 2 .$$

Therefore, the stabilizer group of θ_6 in equation (6) which is denoted by G_{θ_6} which contains

- 1 matrices of order 2;
- The identity matrix.

Form[1], G_{θ_6} is isomorphic to \mathbf{Z}_2 , that is $G_{\theta_6} \cong \mathbf{Z}_2$. θ_6 in equation (6) is drawn in Figure-8:

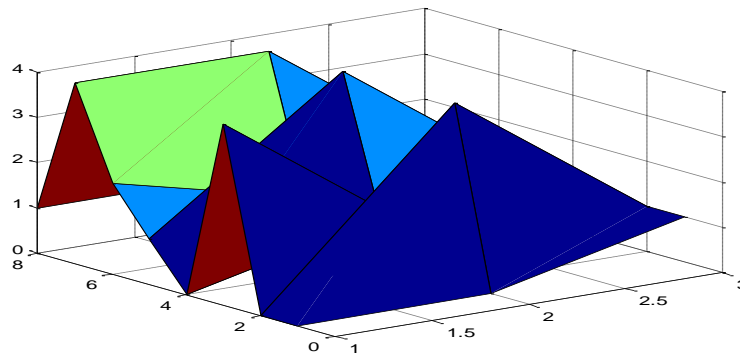


Figure 8-Drawing of θ_6

Let $\theta_6^* = \{[1,4,1], [2,1,0], [4,4,1], [1,1,1]\}$ be a subset of θ_6 in equation (6) which is forming by partition θ_6 into two sets such that θ_6^* does not contains the inflection points of θ_6 , so we note that θ_6^* represents an arc of degree two. Also, to find the stabilizer group of θ_6^* , by some calculation, we obtain

$$\begin{aligned} & \begin{pmatrix} 0 & 0 & 1 \\ 4 & 1 & 2 \\ 3 & 0 & 2 \end{pmatrix} : 4, \begin{pmatrix} 0 & 0 & 1 \\ 4 & 2 & 3 \\ 3 & 1 & 3 \end{pmatrix} : 3, \begin{pmatrix} 0 & 1 & 3 \\ 4 & 2 & 3 \\ 3 & 0 & 1 \end{pmatrix} : 4, \begin{pmatrix} 0 & 1 & 3 \\ 4 & 4 & 3 \\ 3 & 2 & 1 \end{pmatrix} : 3, \\ & \begin{pmatrix} 0 & 1 & 4 \\ 1 & 1 & 2 \\ 2 & 1 & 2 \end{pmatrix} : 2, \begin{pmatrix} 0 & 1 & 4 \\ 1 & 4 & 3 \\ 2 & 4 & 3 \end{pmatrix} : 2, \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} : 1, \begin{pmatrix} 1 & 0 & 0 \\ 0 & 2 & 2 \\ 0 & 1 & 3 \end{pmatrix} : 3, \\ & \begin{pmatrix} 1 & 0 & 2 \\ 0 & 2 & 4 \\ 2 & 1 & 2 \end{pmatrix} : 3, \begin{pmatrix} 1 & 0 & 2 \\ 4 & 1 & 2 \\ 1 & 0 & 4 \end{pmatrix} : 4, \begin{pmatrix} 1 & 0 & 4 \\ 0 & 2 & 0 \\ 2 & 0 & 4 \end{pmatrix} : 2, \begin{pmatrix} 1 & 0 & 4 \\ 4 & 4 & 3 \\ 1 & 2 & 2 \end{pmatrix} : 4, \\ & \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 2 \\ 0 & 1 & 3 \end{pmatrix} : 3, \begin{pmatrix} 1 & 1 & 0 \\ 0 & 4 & 0 \\ 0 & 4 & 1 \end{pmatrix} : 2, \begin{pmatrix} 1 & 2 & 1 \\ 0 & 1 & 3 \\ 2 & 4 & 3 \end{pmatrix} : 4, \begin{pmatrix} 1 & 2 & 1 \\ 4 & 4 & 3 \\ 1 & 2 & 1 \end{pmatrix} : 3, \\ & \begin{pmatrix} 0 & 1 & 3 \\ 1 & 2 & 2 \\ 0 & 3 & 3 \end{pmatrix} : 3, \begin{pmatrix} 0 & 4 & 1 \\ 1 & 2 & 2 \\ 0 & 4 & 2 \end{pmatrix} : 2, \begin{pmatrix} 1 & 2 & 4 \\ 0 & 3 & 0 \\ 2 & 3 & 4 \end{pmatrix} : 2, \begin{pmatrix} 1 & 2 & 4 \\ 4 & 2 & 3 \\ 1 & 0 & 0 \end{pmatrix} : 3, \\ & \begin{pmatrix} 0 & 4 & 1 \\ 1 & 3 & 1 \\ 0 & 1 & 1 \end{pmatrix} : 3, \begin{pmatrix} 0 & 0 & 1 \\ 4 & 2 & 3 \\ 1 & 3 & 1 \end{pmatrix} : 2, \begin{pmatrix} 2 & 3 & 4 \\ 0 & 0 & 4 \\ 1 & 4 & 2 \end{pmatrix} : 4, \begin{pmatrix} 1 & 4 & 2 \\ 4 & 1 & 2 \\ 1 & 1 & 0 \end{pmatrix} : 2 . \end{aligned}$$

Therefore, the stabilizer group of θ_6^* which is denoted by $G_{\theta_6^*}$ which contains

- 9 matrices of order 2;
- 8 matrices of order 3;
- 6 matrices of order 4;
- The identity matrix.

Form[1], $G_{\theta_6^*}$ is isomorphic to \mathbf{S}_4 , that is $G_{\theta_6^*} \cong \mathbf{S}_4$. Drawing of θ_6^* is given in Figure-9:

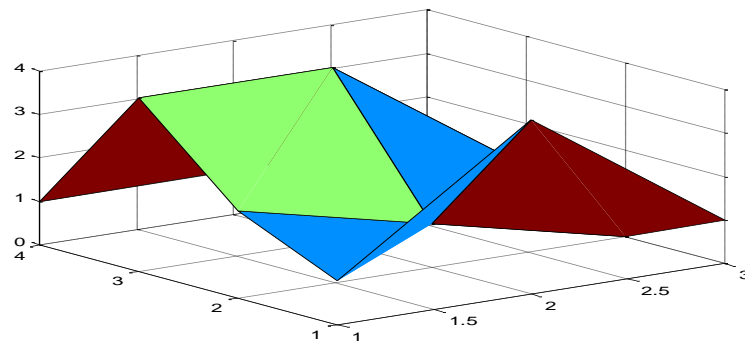


Figure 9-Drawing of θ_6^*

Another one of cubic curve which is given in [4] is:

$$\theta_7 = yz^2 + x^3 + xy^2 - 2y^3. \tag{7}$$

The points of $PG(2,5)$ on θ_7 in equation (7) are $[0,0,1], [1,1,0], [3,2,1], [2,3,1]$. To find the stabilizer group of θ_7 in equation(7), we are doing calculations by help the computer. Thus the transformation matrices which stabilizing of θ_7 with their orders are shown as follows:

$$\begin{aligned} & \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} : 2, \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 4 \end{pmatrix} : 2, \begin{pmatrix} 0 & 1 & 2 \\ 1 & 0 & 3 \\ 2 & 3 & 1 \end{pmatrix} : 4, \begin{pmatrix} 0 & 1 & 2 \\ 1 & 0 & 3 \\ 3 & 2 & 4 \end{pmatrix} : 12, \\ & \begin{pmatrix} 0 & 1 & 3 \\ 1 & 0 & 2 \\ 2 & 3 & 4 \end{pmatrix} : 12, \begin{pmatrix} 0 & 1 & 3 \\ 1 & 0 & 2 \\ 3 & 2 & 1 \end{pmatrix} : 4, \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} : 1, \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 4 \end{pmatrix} : 2, \\ & \begin{pmatrix} 1 & 0 & 2 \\ 0 & 1 & 3 \\ 2 & 3 & 4 \end{pmatrix} : 4, \begin{pmatrix} 1 & 0 & 2 \\ 0 & 1 & 3 \\ 3 & 2 & 1 \end{pmatrix} : 12, \begin{pmatrix} 1 & 0 & 3 \\ 0 & 1 & 2 \\ 2 & 3 & 1 \end{pmatrix} : 12, \begin{pmatrix} 1 & 0 & 3 \\ 0 & 1 & 2 \\ 3 & 2 & 4 \end{pmatrix} : 4, \\ & \begin{pmatrix} 1 & 2 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} : 4, \begin{pmatrix} 1 & 2 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 4 \end{pmatrix} : 4, \begin{pmatrix} 1 & 2 & 2 \\ 2 & 1 & 3 \\ 2 & 3 & 1 \end{pmatrix} : 2, \begin{pmatrix} 1 & 2 & 2 \\ 2 & 1 & 3 \\ 3 & 2 & 4 \end{pmatrix} : 6, \\ & \begin{pmatrix} 1 & 2 & 3 \\ 2 & 1 & 2 \\ 2 & 3 & 4 \end{pmatrix} : 6, \begin{pmatrix} 1 & 2 & 3 \\ 2 & 1 & 2 \\ 3 & 2 & 1 \end{pmatrix} : 2, \begin{pmatrix} 1 & 3 & 0 \\ 3 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix} : 4, \begin{pmatrix} 1 & 3 & 0 \\ 3 & 1 & 0 \\ 0 & 0 & 3 \end{pmatrix} : 4, \\ & \begin{pmatrix} 1 & 3 & 1 \\ 3 & 1 & 4 \\ 1 & 4 & 2 \end{pmatrix} : 2, \begin{pmatrix} 1 & 3 & 1 \\ 3 & 1 & 4 \\ 3 & 1 & 1 \end{pmatrix} : 3, \begin{pmatrix} 1 & 3 & 4 \\ 3 & 1 & 1 \\ 1 & 4 & 3 \end{pmatrix} : 3, \begin{pmatrix} 1 & 3 & 4 \\ 3 & 1 & 1 \\ 4 & 1 & 2 \end{pmatrix} : 2. \end{aligned}$$

Therefore, the stabilizer group of θ_7 in equation (7) which is denoted by G_{θ_7} which contains

- 7 matrices of order 2;
- 2 matrices of order 3;
- 8 matrices of order 4;
- 2 matrices of order 6;
- 4 matrices of order 12;
- The identity matrix.

Form[1], G_{θ_7} is isomorphic to $S_3 \times Z_4$, that is $G_{\theta_7} \cong S_3 \times Z_4$. θ_7 in equation (7) is drawn in Figure-10:

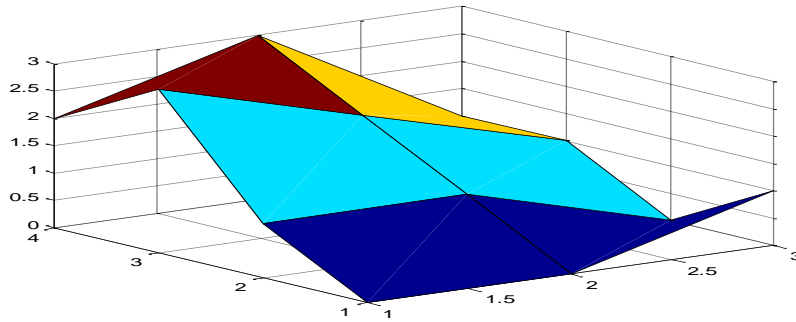


Figure 10-Drawing of θ_7

Let $\theta_7^* = \{[3,2,1], [2,3,1]\}$ be a subset of θ_7 in equation (7) which is forming by partition θ_7 into two sets such that θ_7^* does not contains the inflection points of θ_7 , so we note that θ_7^* represents an arc of degree two. After the calculation and help the computer, we are obtained that the number of matrices which are stabilizing of θ_7^* is 800, and we can not write them, because they are too much. Moreover, the stabilizer group of θ_7^* which is denoted by $G_{\theta_7^*}$ which contains

- 55 matrix of order 2;
- 320 matrix of order 4;
- 24 matrix of order 5;
- 200 matrix of order 8;
- 120 matrix of order 10;
- 80 matrix of order 20;
- The identity matrix.

Drawing of θ_7^* is given in Figure-11 as following:

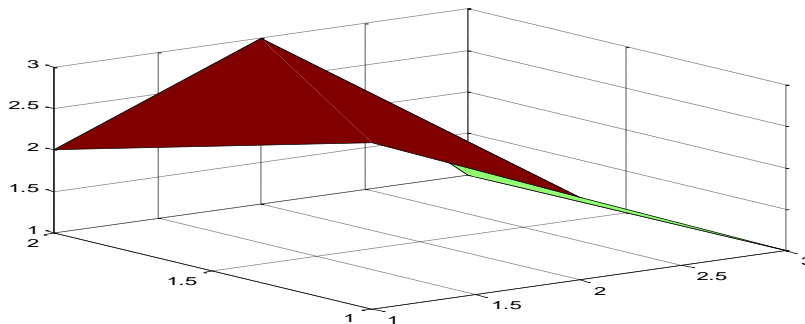


Figure 11-Drawing of θ_7^*

Another one of cubic curve which is given in [4] is:

$$\theta_8 = yz^2 + x^3 + 2xy^2 - y^3. \tag{8}$$

The points of $PG(2,5)$ on θ_8 in equation (8) are $[0,0,1], [0,4,1], [1,3,1], [0,1,1], [3,2,1], [2,3,1], [4,2,1]$. To find the stabilizer group of θ_8 in equation (8), we are doing calculations by help the computer. Thus the transformation matrices which stabilizing of θ_8 with their orders are shown as follows:

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} : 1, \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 4 \end{pmatrix} : 2, \begin{pmatrix} 1 & 1 & 0 \\ 3 & 4 & 0 \\ 0 & 0 & 2 \end{pmatrix} : 2, \begin{pmatrix} 1 & 1 & 0 \\ 3 & 4 & 0 \\ 0 & 0 & 3 \end{pmatrix} : 2.$$

Therefore, the stabilizer group of θ_8 in equation (8) which is denoted by G_{θ_8} which contains

- 3 matrices of order 2;
- The identity matrix.

Form[1], G_{θ_8} is isomorphic to $\mathbf{Z}_2 \times \mathbf{Z}_2$, that is $G_{\theta_8} \cong \mathbf{Z}_2 \times \mathbf{Z}_2$. θ_8 in equation (8) is drawn in Figure-12:

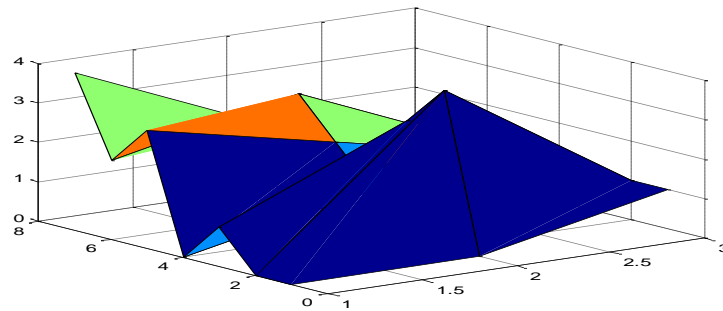


Figure 12-Drawing of θ_8

Another one of cubic curve which is given in [4] is:
 $\theta_9 = yz^2 + x^3 + xy^2$. (9)

The points of $PG(2,5)$ on θ_9 in equation (9) are $[0,1,0], [0,0,1], [2,1,0], [3,1,0]$. To find the stabilizer group of θ_9 in equation(9), we are doing calculations by help the computer. Thus the transformation matrices which stabilizing of θ_9 with their orders are shown as follows:

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} : 1, \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix} : 4, \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 3 \end{pmatrix} : 4, \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 4 \end{pmatrix} : 2, \\ \begin{pmatrix} 1 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 0 \end{pmatrix} : 2, \begin{pmatrix} 1 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 2 \end{pmatrix} : 4, \begin{pmatrix} 1 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 3 \end{pmatrix} : 4, \begin{pmatrix} 1 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 4 \end{pmatrix} : 2, \\ \begin{pmatrix} 1 & 1 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} : 12, \begin{pmatrix} 1 & 1 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix} : 6, \begin{pmatrix} 1 & 1 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 3 \end{pmatrix} : 3, \begin{pmatrix} 1 & 1 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 4 \end{pmatrix} : 12, \\ \begin{pmatrix} 1 & 1 & 0 \\ 3 & 4 & 0 \\ 0 & 0 & 1 \end{pmatrix} : 4, \begin{pmatrix} 1 & 1 & 0 \\ 3 & 4 & 0 \\ 0 & 0 & 2 \end{pmatrix} : 2, \begin{pmatrix} 1 & 1 & 0 \\ 3 & 4 & 0 \\ 0 & 0 & 3 \end{pmatrix} : 2, \begin{pmatrix} 1 & 1 & 0 \\ 3 & 4 & 0 \\ 0 & 0 & 4 \end{pmatrix} : 4, \\ \begin{pmatrix} 1 & 4 & 0 \\ 2 & 4 & 0 \\ 0 & 0 & 1 \end{pmatrix} : 4, \begin{pmatrix} 1 & 4 & 0 \\ 2 & 4 & 0 \\ 0 & 0 & 2 \end{pmatrix} : 2, \begin{pmatrix} 1 & 4 & 0 \\ 2 & 4 & 0 \\ 0 & 0 & 3 \end{pmatrix} : 2, \begin{pmatrix} 1 & 4 & 0 \\ 2 & 4 & 0 \\ 0 & 0 & 4 \end{pmatrix} : 4, \\ \begin{pmatrix} 1 & 4 & 0 \\ 3 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} : 12, \begin{pmatrix} 1 & 4 & 0 \\ 3 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix} : 6, \begin{pmatrix} 1 & 4 & 0 \\ 3 & 1 & 0 \\ 0 & 0 & 3 \end{pmatrix} : 3, \begin{pmatrix} 1 & 4 & 0 \\ 3 & 1 & 0 \\ 0 & 0 & 4 \end{pmatrix} : 12 .$$

Therefore, the stabilizer group of θ_9 in equation (9) which is denoted by G_{θ_9} which contains

- 7 matrices of order 2;
- 2 matrices of order 3;
- 8 matrices of order 4;
- 2 matrices of order 6;
- 4 matrices of order 12;
- The identity matrix.

Form[1], G_{θ_9} is isomorphic to $\mathbf{S}_3 \times \mathbf{Z}_4$, that is $G_{\theta_9} \cong \mathbf{S}_3 \times \mathbf{Z}_4$. θ_9 in equation (9) is drawn in Figure-13:

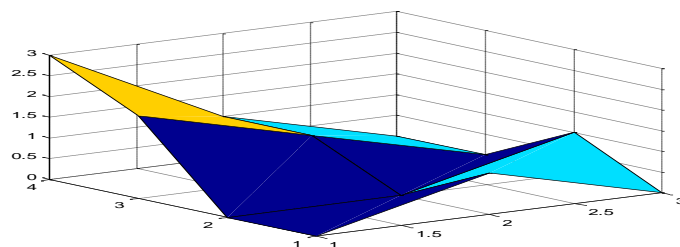


Figure 13 -Drawing of θ_9

Let $\theta_9^* = \{[2,1,0], [3,1,0]\}$ be a subset of θ_9 in equation (9) which is forming by partition θ_9 into two sets such that θ_9^* does not contains the inflection points of θ_9 , so we note that θ_9^* represents an arc of degree two. After the calculation and help the computer, we are obtained that the number of matrices which are stabilizing of θ_9^* is 800, and we can not write them, because they are too much. Moreover, the stabilizer group of θ_9^* which is denoted by $G_{\theta_9^*}$ which contains

- 55 matrix of order 2;
- 320 matrix of order 4;
- 24 matrix of order 5;
- 200 matrix of order 8;
- 120 matrix of order 10;
- 80 martrix of order 20;
- The identity matrix.

Drawing of θ_9^* is given in Figure-14 as following:

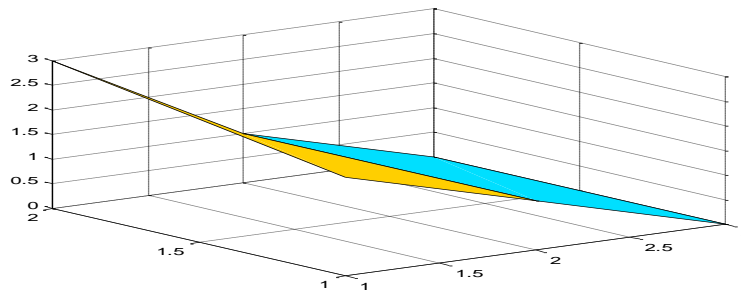


Figure 14-Drawing of θ_9^*

Another one of cubic curve which is given in [4] is:

$$\theta_{10} = yz^2 + x^3 + 2xy^2 . \tag{10}$$

The points of $PG(2,5)$ on θ_{10} in equation (10) are $[0,1,0], [0,0,1]$. After the calculation and help the computer, we are obtained that the number of matrices which are stabilizing of θ_{10} in equation (10) is 800, and we can not write them, because they are too much.

Moreover, the stabilizer group of θ_{10} in equation (26) which is denoted by $G_{\theta_{10}}$ which contains

- 55 matrix of order 2;
- 320 matrix of order 4;
- 24 matrix of order 5;
- 200 matrix of order 8;
- 120 matrix of order 10;
- 80 martrix of order 20;
- The identity matrix.

The set of points on θ_{10} represents the arc of degree two and size 2.

Drawing of θ_{10} in equation (10) is given in Figure-15 as following:

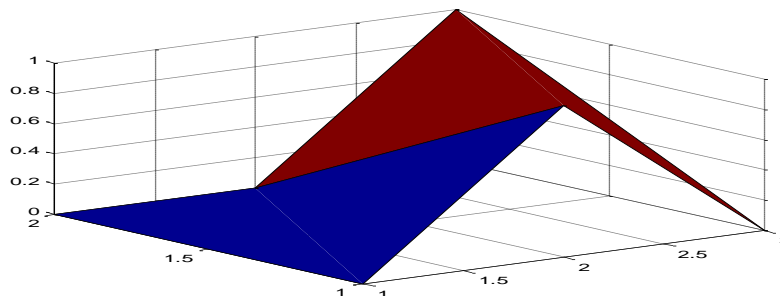


Figure 15 -Drawing of θ_{10}

Another one of cubic curve which is given in [4] is:

$$\theta_{11} = yz^2 + x^3 - 2xy^2 . \tag{11}$$

The points of $PG(2,5)$ on θ_{11} in equation (11) are $[0,1,0], [0,0,1], [3,2,1], [1,2,1], [2,3,1], [4,4,1], [3,4,1], [4,3,1], [2,1,1], [1,1,1]$. To find the stabilizer group of θ_{11} in equation (11), we are doing calculations by help the computer. Thus the transformation matrices which stabilizing of θ_{11} with their orders are shown as follows:

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} : 1, \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 4 \end{pmatrix} : 2, \begin{pmatrix} 0 & 1 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 2 \end{pmatrix} : 4, \begin{pmatrix} 1 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 3 \end{pmatrix} : 4.$$

Therefore, the stabilizer group of θ_{11} in equation(11) which is denoted by $G_{\theta_{11}}$ which contains

- 1 matrices of order 2;
- 2 matrices of order 4;
- The identity matrix.

Form[1], $G_{\theta_{11}}$ is isomorphic to Z_4 , that is $G_{\theta_{11}} \cong Z_4$. θ_{11} in equation (11) is drawn in Figure-16

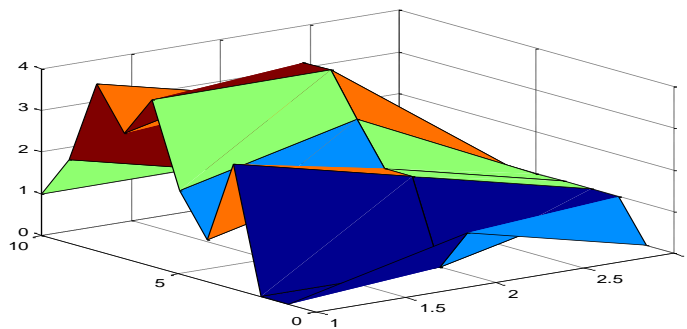


Figure 16-Drawing of θ_{11}

Let $\theta_{11}^* = \{[2,3,1], [4,4,1], [4,3,1], [2,1,1], [1,1,1]\}$ be a subset of θ_{11} in equation (11) which is forming by partition the θ_{11} into two sets such that θ_{11}^* does not contains the inflection points of θ_{11} , so we note that θ_{11}^* represents an arc of degree two. Also, to find the stabilizer group of θ_{11}^* , by some calculation, we obtain

$$\begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 4 \end{pmatrix} : 2, \begin{pmatrix} 0 & 1 & 0 \\ 1 & 1 & 2 \\ 0 & 1 & 1 \end{pmatrix} : 5, \begin{pmatrix} 0 & 1 & 3 \\ 0 & 2 & 3 \\ 2 & 4 & 2 \end{pmatrix} : 4, \begin{pmatrix} 0 & 1 & 3 \\ 1 & 0 & 2 \\ 3 & 2 & 1 \end{pmatrix} : 4, \\ \begin{pmatrix} 0 & 1 & 4 \\ 0 & 3 & 4 \\ 4 & 3 & 4 \end{pmatrix} : 4, \begin{pmatrix} 0 & 1 & 4 \\ 2 & 3 & 0 \\ 1 & 3 & 0 \end{pmatrix} : 4, \begin{pmatrix} 0 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} : 1, \begin{pmatrix} 1 & 0 & 0 \\ 1 & 1 & 3 \\ 1 & 0 & 4 \end{pmatrix} : 2, \\ \begin{pmatrix} 1 & 0 & 1 \\ 3 & 0 & 1 \\ 3 & 4 & 1 \end{pmatrix} : 4, \begin{pmatrix} 1 & 0 & 1 \\ 3 & 2 & 0 \\ 3 & 1 & 0 \end{pmatrix} : 4, \begin{pmatrix} 0 & 1 & 3 \\ 0 & 1 & 3 \\ 2 & 3 & 4 \end{pmatrix} : 4, \begin{pmatrix} 1 & 0 & 2 \\ 2 & 0 & 2 \\ 4 & 2 & 3 \end{pmatrix} : 4, \\ \begin{pmatrix} 0 & 1 & 0 \\ 0 & 1 & 0 \\ 1 & 1 & 2 \end{pmatrix} : 2, \begin{pmatrix} 1 & 4 & 4 \\ 1 & 4 & 4 \\ 1 & 1 & 2 \end{pmatrix} : 5, \begin{pmatrix} 1 & 0 & 0 \\ 1 & 0 & 0 \\ 1 & 1 & 3 \end{pmatrix} : 5, \begin{pmatrix} 4 & 1 & 1 \\ 4 & 1 & 1 \\ 1 & 1 & 3 \end{pmatrix} : 2, \\ \begin{pmatrix} 0 & 4 & 4 \\ 1 & 4 & 0 \\ 0 & 3 & 2 \end{pmatrix} : 4, \begin{pmatrix} 1 & 2 & 3 \\ 1 & 4 & 0 \\ 2 & 0 & 2 \end{pmatrix} : 4, \begin{pmatrix} 4 & 0 & 1 \\ 1 & 4 & 4 \\ 1 & 1 & 2 \end{pmatrix} : 2, \begin{pmatrix} 2 & 1 & 2 \\ 4 & 4 & 2 \\ 4 & 3 & 2 \end{pmatrix} : 5.$$

Therefore, the stabilizer group of θ_{11}^* which is denoted by $G_{\theta_{11}^*}$ which contains

- 5 matrices of order 2;
- 10 matrix of order 4;
- 4 matrices of order 5;
- The identity matrix.

Form[1], $G_{\theta_{11}^*}$ is isomorphic to $Z_5 \times Z_4$, that is $G_{\theta_{11}^*} \cong Z_5 \times Z_4$. Drawing of θ_{11}^* is given in Figure-17 as following:

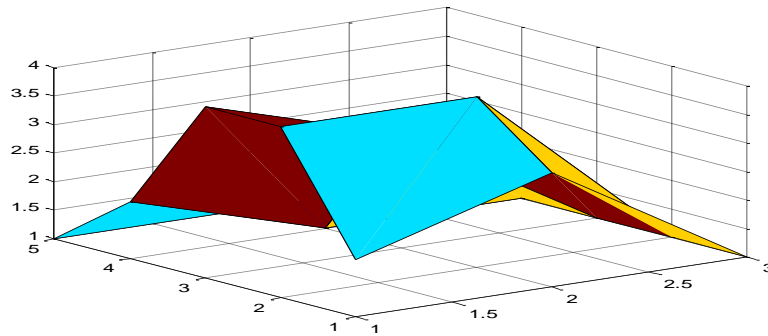


Figure 17-Drawing of θ_{11}^*

Another one of cubic curve which is given in [4] is:

$$\theta_{12} = yz^2 + x^3 - xy^2. \tag{12}$$

The points of $PG(2,5)$ on θ_{12} in equation (12) are $[0,1,0], [0,0,1], [4,1,0], [1,3,1], [1,1,0], [3,1,1], [2,4,1], [4,2,1]$. To find the stabilizer group of θ_{12} in equation (12), we are doing calculations by help the computer. Thus the transformation matrices which stabilizing of θ_{12} with their orders are shown as follows:

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} : 1, \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 4 \end{pmatrix} : 2, \begin{pmatrix} 0 & 1 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 2 \end{pmatrix} : 4, \begin{pmatrix} 1 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 3 \end{pmatrix} : 4.$$

Therefore, the stabilizer group of θ_{12} in equation (12) which is denoted by $G_{\theta_{12}}$ which contains

- 1 matrices of order 2;
- 2 matrices of order 4;
- The identity matrix.

Form[1], $G_{\theta_{12}}$ is isomorphic to Z_4 , that is $G_{\theta_{12}} \cong Z_4$. θ_{12} in equation (12) is drawn in Figure-18:

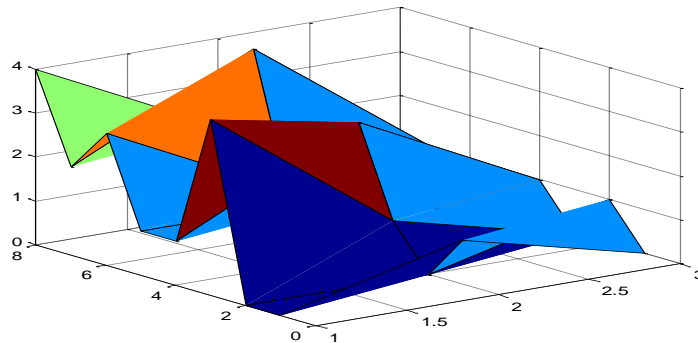


Figure 18-Drawing of θ_{12}

Let $\theta_{12}^* = \{[1,3,1], [3,1,1], [2,4,1], [4,2,1]\}$ be a subset of θ_{12} in equation (12) which is forming by partition θ_{12} into two sets such that θ_{12}^* does not contains the inflection points of θ_{12} , so we note that θ_{12}^* represents an arc of degree two. Also, to find the stabilizer group of θ_{12}^* , by some calculation, we obtain

$$\begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} : 2, \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 4 \end{pmatrix} : 2, \begin{pmatrix} 0 & 1 & 0 \\ 4 & 0 & 0 \\ 0 & 0 & 2 \end{pmatrix} : 2, \begin{pmatrix} 0 & 1 & 0 \\ 4 & 0 & 0 \\ 0 & 0 & 3 \end{pmatrix} : 2, \\ \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} : 1, \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 4 \end{pmatrix} : 2, \begin{pmatrix} 0 & 4 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 2 \end{pmatrix} : 4, \begin{pmatrix} 1 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 3 \end{pmatrix} : 4, \\ \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 4 \\ 2 & 3 & 0 \end{pmatrix} : 2, \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 4 \\ 3 & 2 & 0 \end{pmatrix} : 4, \begin{pmatrix} 1 & 1 & 1 \\ 4 & 4 & 1 \\ 1 & 4 & 0 \end{pmatrix} : 3, \begin{pmatrix} 1 & 1 & 1 \\ 4 & 4 & 1 \\ 4 & 1 & 0 \end{pmatrix} : 3,$$

$$\begin{pmatrix} 1 & 1 & 4 \\ 1 & 1 & 1 \end{pmatrix} : 4, \begin{pmatrix} 1 & 1 & 4 \\ 3 & 2 & 0 \end{pmatrix} : 2, \begin{pmatrix} 1 & 1 & 4 \\ 4 & 4 & 4 \end{pmatrix} : 3, \begin{pmatrix} 1 & 1 & 4 \\ 4 & 4 & 4 \end{pmatrix} : 3, \\ \begin{pmatrix} 1 & 4 & 2 \\ 1 & 4 & 2 \end{pmatrix} : 3, \begin{pmatrix} 1 & 4 & 2 \\ 1 & 4 & 2 \end{pmatrix} : 3, \begin{pmatrix} 1 & 4 & 2 \\ 4 & 1 & 2 \end{pmatrix} : 2, \begin{pmatrix} 1 & 4 & 2 \\ 4 & 1 & 2 \end{pmatrix} : 4, \\ \begin{pmatrix} 2 & 2 & 0 \\ 1 & 1 & 0 \end{pmatrix} : 3, \begin{pmatrix} 1 & 4 & 3 \\ 1 & 4 & 3 \end{pmatrix} : 3, \begin{pmatrix} 1 & 4 & 3 \\ 4 & 1 & 3 \end{pmatrix} : 4, \begin{pmatrix} 1 & 4 & 3 \\ 4 & 1 & 3 \end{pmatrix} : 2. \\ \begin{pmatrix} 1 & 4 & 2 \\ 2 & 2 & 0 \end{pmatrix} : 3, \begin{pmatrix} 1 & 4 & 2 \\ 2 & 2 & 0 \end{pmatrix} : 3, \begin{pmatrix} 1 & 4 & 3 \\ 1 & 1 & 0 \end{pmatrix} : 4, \begin{pmatrix} 1 & 4 & 3 \\ 4 & 4 & 0 \end{pmatrix} : 2.$$

Therefore, the stabilizer group of θ_{12}^* which is denoted by $G_{\theta_{12}^*}$ which contains

- 9 matrices of order 2;
- 8 matrices of order 3;
- 6 matrices of order 4;
- The identity matrix.

Form[1], $G_{\theta_{12}^*}$ is isomorphic to S_4 , that is $G_{\theta_{12}^*} \cong S_4$. Drawing of θ_{12}^* is given in Figure-19:

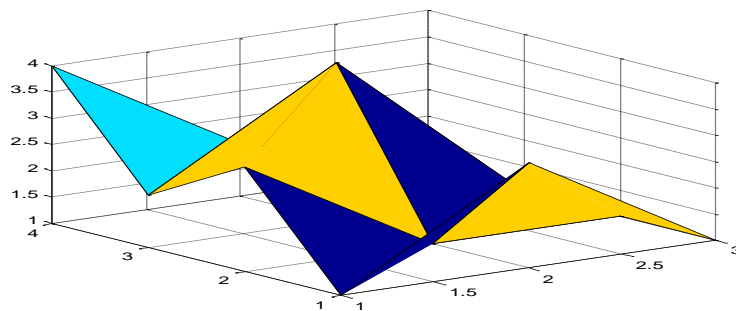


Figure 19-Drawing of θ_{12}^*

Another one of cubic curve which is given in [4] is:

$$\theta_{13} = z^3 - 3(x^2 - xy + y^2)z - (x^3 - 3xy^2 + y^3). \tag{13}$$

The points of $PG(2,5)$ on θ_{13} in equation (13) are $[1,4,1], [1,2,1], [3,4,1]$. After the calculation and help the computer, we are obtained that the number of matrices which are stabilizing of θ_{13} in equation (13) is 96, and we can not write them, because they are too much.

Moreover, the stabilizer group of θ_{13} in equation (13) which is denoted by $G_{\theta_{13}}$ which contains

- 15 matrix of order 2;
- 32 matrix of order 3;
- 24 matrix of order 4;
- 24 matrix of order 8;
- The identity matrix.

Drawing of θ_{13} in equation (13) is given in Figure-20 as following:

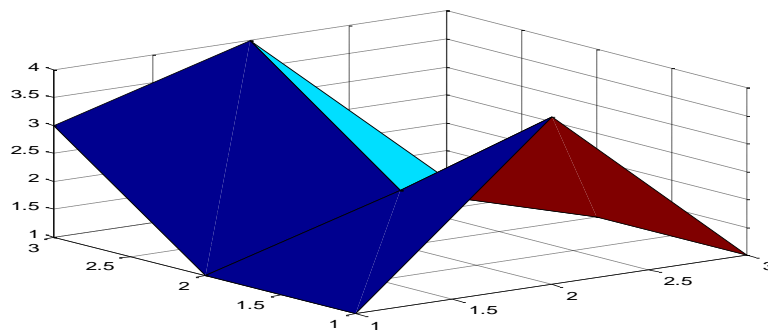


Figure 20-Drawing of θ_{13}

Another one of cubic curve which is given in [4] is:

$$\theta_{14} = z^3 - (x^2 - xy + y^2)z - (x^3 - 3xy^2 + y^3). \tag{14}$$

The points of $PG(2,5)$ on θ_{14} in equation (14) are $[4,1,1], [3,2,1], [3,1,1], [3,0,1], [0,3,1], [2,2,1]$. To find the stabilizer group of θ_{14} in equation (14), we are doing calculations by help the computer. Thus the transformation matrices which stabilizing of θ_{14} with their orders are shown as follows:

$$\begin{pmatrix} 0 & 1 & 0 \\ 4 & 4 & 0 \\ 0 & 0 & 1 \end{pmatrix} : 3, \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} : 1, \begin{pmatrix} 1 & 1 & 0 \\ 4 & 0 & 0 \\ 0 & 0 & 4 \end{pmatrix} : 3 .$$

Therefore, the stabilizer group of θ_{14} in equation (14) which is denoted by $G_{\theta_{14}}$ contains

- 2 matrices of order 3;
- The identity matrix.

Form[6], $G_{\theta_{14}}$ is isomorphic to \mathbf{Z}_3 , that is $G_{\theta_{14}} \cong \mathbf{Z}_3$. θ_{14} in equation(14) is drawn in Figure-21:

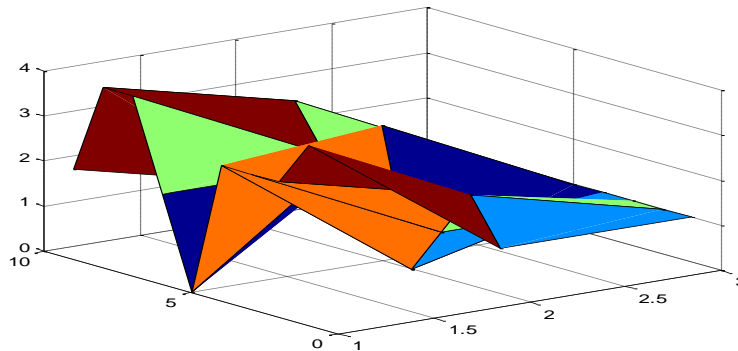


Figure 21-Drawing of θ_{14}

Another one of cubic curve which is given in [4] is:

$$\theta_{15} = z^3 - (x^3 - 3xy^2 + y^3) . \tag{15}$$

The points of $PG(2,5)$ on θ_{15} in equation (15) are $[1,3,1], [0,1,1], [2,3,1], [2,4,1], [4,4,1], [1,0,1]$. To find the stabilizer group of θ_{15} in equation (15), we are doing calculations by help the computer. Thus the transformation matrices which stabilizing of θ_{15} with their orders are shown as follows:

$$\begin{pmatrix} 0 & 1 & 0 \\ 4 & 4 & 0 \\ 0 & 0 & 1 \end{pmatrix} : 3, \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} : 1, \begin{pmatrix} 1 & 1 & 0 \\ 4 & 0 & 0 \\ 0 & 0 & 4 \end{pmatrix} : 3 .$$

Therefore, the stabilizer group of θ_{15} in equation (15) which is denoted by $G_{\theta_{15}}$ which contains

- 2 matrices of order 3;
- The identity matrix.

Form[1], $G_{\theta_{15}}$ is isomorphic to \mathbf{Z}_3 , that is $G_{\theta_{15}} \cong \mathbf{Z}_3$. θ_{15} in equation (15) is drawn in Figure-22:

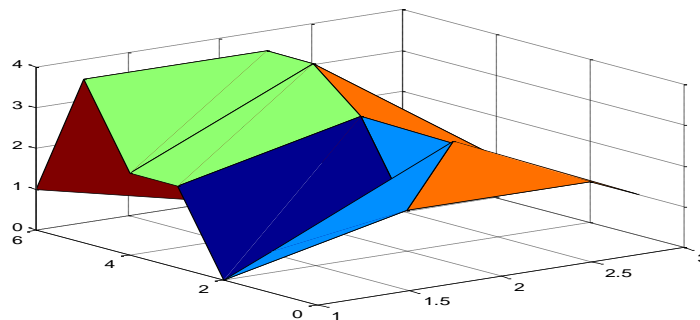


Figure 22-Drawing of θ_{15}

Another one of cubic curve which is given in [4] is:

$$\theta_{16} = z^3 + 3(x^2 - xy + y^2)z - (x^3 - 3xy^2 + y^3) . \tag{16}$$

The points of $PG(2,5)$ on θ_{16} in equation (16) are $[0,4,1], [2,0,1], [4,0,1], [0,2,1], [3,3,1], [1,1,1]$. To find the stabilizer group of θ_{16} in equation (16), we are doing calculations by help the computer. Thus the transformation matrices which stabilizing of θ_{16} with their orders are shown as follows:

$$\begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} : 2, \begin{pmatrix} 0 & 1 & 0 \\ 4 & 4 & 0 \\ 0 & 0 & 1 \end{pmatrix} : 3, \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} : 1, \\ \begin{pmatrix} 1 & 0 & 0 \\ 4 & 4 & 0 \\ 0 & 0 & 1 \end{pmatrix} : 2, \begin{pmatrix} 1 & 1 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 4 \end{pmatrix} : 2, \begin{pmatrix} 1 & 1 & 0 \\ 4 & 0 & 0 \\ 0 & 0 & 4 \end{pmatrix} : 3.$$

Therefore, the stabilizer group of θ_{16} in equation (16) which is denoted by $G_{\theta_{16}}$ which contains

- 3 matrices of order 2;
- 2 matrices of order 3;
- The identity matrix.

Form [1], $G_{\theta_{16}}$ is isomorphic to S_3 , that is $G_{\theta_{16}} \cong S_3$. θ_{16} in equation (16) is drawn in Figure-23:

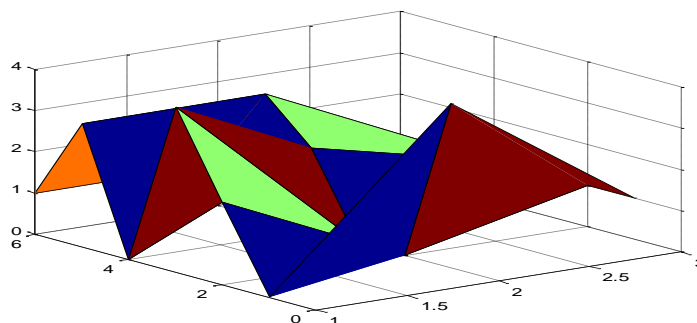


Figure 23-Drawing of θ_{16}

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