Alzaiadi and Shaheen

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# Involutive Gamma Derivations on n-Gamma Lie Algebra and 3- Pre Gamma -Lie Algebra

Ali Abd H Alzaiadi , Rajaa C. Shaheen

Mathematics Department, College of Education, Al-Qadisiya University, Iraq.

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#### Abstract

paper, In this the structure of  $n - \Gamma$  – Lie Algebra and  $3 - \Gamma - Pre Lie Algebra$  have been introduced and studied. We also obtain that a  $\Gamma$  – Lie algebra V is one  $\lambda$  – dimentional extension of a  $\Gamma$  – Lie algebra if and only if there exists an *involutive*  $\lambda$  – *derivation*  $D_{\lambda}$  on V such that  $dimV_1$  = 1 or  $dimV_{-1} = 1$ . In addition, we obtain that  $two - \lambda - dimensional extension$ of  $\Gamma$  – Lie algebras if and only if there is an involutive –  $\lambda$  – derivation  $D_{\lambda}$  on  $U = U_1$ ,  $U = U_{-1}$  such that  $U_1 = 2 \text{ or } \dim U_{-1} = 2$ , where  $U_1 \text{ and } U_{-1}$  are subspaces of U with eigenvalues 1 and -1, respectively. We also find t that the existence of *involutive*  $-\lambda$  - derivation  $D_{\lambda}$  on  $3 - \Gamma$  - Lie algebra implies that there exists a compatible  $3 - \Gamma - Pre Lie algebra$  under appropriate condition.

Keywords: Algebra, Lie Algebra , Derivation , Gamma Lie algebra.

اشتقاقات كاما اللاارادية علىn -كاما جبر لي و3-كاما جبر لي العكسي

علي عبد حمادي الزيادي ، رجاء جفات شاهين قسم الرياضيات، كلية التربية، جامعة القادسية ،العراق

الخلاصة

في هذا البحث ،قدمت ودرست بنية n –كاما- جبر لي و و3-كاما- جبر لي العكسي واستنتج ان كاما -جبر لي V هو توسيع اول ذو بعد  $\chi$  ل كاما- جبر لي اذا وفقط اذا وجد  $\chi$ –اشتقاق لا ارادي  $D_{\lambda}$  على V حيث بعد  $V_{1}=1$ او بعد  $1=V_{1}$ . وكذلك استنتج توسيع ثاني ذو بعد  $\chi$  ل كاما- جبور لي اذا وفقط اذا وجد  $\chi$ –اشتقاق لا ارادي  $D_{\lambda}$  على  $D_{1}=U_{1}$  ,  $U=U_{1}$  ,  $U=U_{1}$  ,  $U=U_{1}$  ,  $U=U_{1}$  ,  $D_{2}=U_{1}$  بحيث بعد 2= $U_{1}$  وجود  $U_{1}$  المتقاق لا ارادي  $U_{1}$  مع قيم ذاتية 1 و -1 ،على التوالي .واستنتج ان وجود  $\chi$ –اشتقاق لا ارادي  $D_{1}$  عندما  $U_{1}=U_{1}$  فضاءات جزئية من U مع قيم ذاتية 1 و -1 ،على التوالي .واستنتج ان وجود  $\chi$ –اشتقاق لا ارادي  $D_{2}$  على 3-كاما- جبر لي يؤدي الى وجود 3-كاما جبر لي العكسي تحت شروط مناسبة .

<sup>\*</sup>Email: math.post10@qu.edu.iq

### Introduction

The notion of  $n - Lie \ algebra$  was introduced by Filippov [1]. Derivation have also a relation with the extensions of  $n - Lie \ algebra$ . The concept of  $3 - Lie \ classical \ Yang$ Baxter equations was introduce in [2], as well as Involutive Derivation is an important concept in  $3 - Lie \ algebra$ . In[3] authors investigated the existence of involutive derivations and studied its properties on  $n - Lie \ algebra$ . They also investigated a class of  $3 - Lie \ algebra$  with involutive derivations which are two - dimensional extension of Lie \ algebra and  $\Gamma$  - lie \ admissible \ algebras. The concept of compatible with 3 - pre Lie \ algebra (A, {,,,}<sub>D</sub>) such that A is adjacent  $3 - Lie \ algebra$  in particular is introduced in [5]. For more results on Gamma - derivations can be found in [6,7].

We study the structure of n-Gamma Lie Algebra and 3-Gamma Pre-Algebra, and the algebra  $D_{\lambda}(V)$  is a Lie  $\lambda$  – subalgebra of  $gl_{\lambda}(V)$  has been obtained. We also show that if n = 2r  $r \ge 1$  then there is an *involutive*  $\lambda$  – *derivation* D on V if and only if V is abelian. Furthermore, if  $n = 2r + 1, r \ge 1$  then there is an *involutive*  $\lambda$  – *derivation* on V if and only if V has the *decomposition* V = A + B, so that  $A = V_1$  and  $= V_{-1}$  as well as if  $V \ 3 - \lambda - Lie$  Algebras then V is one dimensional extension of a  $\lambda$  – Lie Algebras  $(V, [, ]_{\lambda})$  if and only if the exists an *involutive*  $\lambda$  – *derivation*  $D_{\lambda}$  on V such that  $dimV_1 = 1$ , or  $dimV_{-1} = 1$ . Moreover if (U, [, , ]) is a  $3 - \lambda$  – Lie Algebras then U has a two dimensional extension

 $3 - \lambda - Lie \ Algebras \ of \lambda - Lie \ Algebras \ if and only eif there is an involutive <math>-\lambda - derivation \ D$  on U such that  $dimU_1 = 2 \ or \ dimU_{-1} = 2$ , where  $U_1$  and  $U_{-1}$  are subspaces of U with eigenvalues 1 and -1, respectively. The existence of involutive  $\lambda - derivation \ D_{\lambda}$  on  $3 - \Gamma - Lie \ algebra$  is obtained, it implies that there exists a compatible  $3 - Pre - \Gamma - Lie \ algebra \ (V, \{, , \}_{\lambda D})$  where  $\{u_1, u_2, u_3\}_{\lambda D} = [Du_1, Du_2, u_3]_{\lambda}, \forall u_1 , u_2, u_3 \in V$ . This is done under appropriate condition.

### **1-Prelimainaries**

In this section, we introduce the basic definitions and examples which are used throughout this paper.

**Definition 1.1**:- [4] Let  $\Gamma$  be a groupoid and V be a *vector space* over a field F. Then V is called a  $\Gamma$  – *algebra* over the field F if there exists a mapping  $V \times \Gamma \times V \rightarrow V$  (the image is denoted by  $u_1 \lambda u_2$ , for  $u_1, u_2, u_3 \in V$  and  $\lambda \in \Gamma$ ) such that the following conditions hold:

 $\begin{array}{rcl} (1)(u_1+u_2)\lambda u_3 &= u_1\lambda u_3 + u_2\lambda u_3 &, \ u_1\lambda (u_2+u_3) &= u_1\lambda u_2 + u_1\lambda u_3 \\ (2)\,u_1(\lambda+\beta)u_2 &= u_1\lambda u_2 + u_1\beta u_2 \end{array}$ 

(3)  $(cu_1)\lambda u_2 = c(u_1\lambda u_2) = u_1\lambda(cu_2)$ , for all  $u_1, u_2, u_3 \in V$ ,  $c \in F$  and  $\lambda, \beta \in \Gamma$ . Moreover,  $\Gamma - algebr$  is called associative if

 $(4) (u_1 \lambda u_2) \beta u_3 = u_1 \lambda (u_2 \beta u_3)$ 

**Example 1.2 :-** Let *V* be the set of 2×3 matrices over the field of real numbers *R* and  $\begin{cases} \Gamma = \begin{bmatrix} \alpha & 0 \\ 0 & \beta \end{bmatrix} & \alpha, \beta \in R \end{cases}$ . Then *V* is an associative  $\Gamma - algebra$ .

 $\begin{cases} \Gamma = \begin{bmatrix} 0 & \beta \\ 0 & 0 \end{bmatrix} & \alpha, \beta \in R \\ \end{cases}. \text{ Then } V \text{ is an associative } \Gamma - algebra. \\ \textbf{Definition 1.3:-} [4] \text{ Let } V \text{ be an associative } \Gamma - algebra \text{ over a field} \end{cases}$ 

**Definition 1.3:-** [4] Let *V* be an *associative*  $\Gamma$  – *algebra* over a field *F*. Then, for every  $\lambda \in \Gamma$  one can construct an  $\lambda$  – *Lie algebra*  $L_{\lambda}(V)$  as a vector space,  $L_{\lambda}(V)$ , which is the same as *V*. The Lie bracket of two elements of  $L_{\lambda}(V)$  is defined to be their commutator in *V*,  $[u, v]_{\lambda} = u\lambda v - v\lambda u$ . Note that  $[u, v]_{\lambda} = -[v, u]_{\lambda}$  for every  $u, v \in V$  and  $\lambda \in \Gamma$ . Also,  $L_{\lambda}(V)$  is abelian if either char (F) = 2 or char  $(F) \neq 2$  then  $[u, v]_{\lambda} = 0$  for every  $v \in V$ .

**Example 1.4:** Let *V* be the set of all real  $3 \times 5$  matrices of the form

$$\begin{pmatrix} 0 & a & 0 & 0 & 0 \\ 0 & b & 0 & 0 & 0 \\ 0 & c & 0 & 0 & 0 \end{pmatrix}$$
  
and  $\Gamma$  b is the set of all real 5× 3 matrices. Then,  $\forall \lambda \in \Gamma$  of the shape  
$$\begin{pmatrix} \alpha & \beta & \delta \\ 0 & 0 & 0 \\ \mu & \rho & \sigma \\ \theta & \vartheta & \tau \\ 0 & 0 & 0 \end{pmatrix}$$

Thus for every  $A, B \in V$ , we have  $[A, B]_{\lambda} = 0$ , so that  $L_{\lambda}(V)$  is abelian and the  $\lambda$  – dimension of V is zero.

**Definition 1.5:-** [4] Let V and U be two associative  $\Gamma$  – algebras over a field F and  $\lambda \in \Gamma$ . A linear transformation  $\varphi^{\lambda} : V \to U$  is called an  $\lambda$ -homomorphism if  $\varphi^{\lambda}([v,u]_{\lambda}) = [\varphi^{\lambda}(v), \varphi^{\lambda}(u)]_{\lambda}$  for all  $v, u \in V$ , and if  $Ker(\varphi^{\lambda}) = 0$ , then  $\varphi^{\lambda}$  is called an  $\lambda$  – monomorphism, while it is called  $\lambda$  – epimorphism if  $Im(\varphi^{\lambda}) = U$ .  $\varphi^{\lambda}$  is called an  $\lambda$  – isomorphism if both  $\lambda$  – monomorphism and  $\lambda$  – epimorphism are satisfied. If  $\varphi^{\lambda}(v) = 0$ , then  $Ker(\varphi^{\lambda})$  is an  $\lambda$  – ideal of  $L_{\lambda}(V)$  certainly, and if  $u \in V$  is arbitrary, then  $\varphi^{\lambda}([v u]_{\lambda}) = [\varphi^{\lambda}(v), \varphi^{\lambda}(u)]_{\lambda} = 0$ . It is also apparent that  $Im(\varphi^{\lambda})$  is an  $\lambda$  – Lie subalgebra of  $L_{\lambda}(U)$ .

**Definition 1.6:-** [1] An n - Lie algebra is a vector space V over a field F endowed with a linear multiplication  $[, \ldots, ]: \wedge^n V \to V$  satisfying for all  $v_1, \ldots, v_n, u_2, \ldots, u_n \in V$   $[[v_1, \ldots, v_n], u_2, \ldots, u_n] = \sum_{i=1}^n [v_1, \ldots, [v_i, u_2, \ldots, u_n], \ldots, v_n]$ . This equation is usually called the generalized Jacobi identity, or Filippov identity. The Lie sub algebra generated by the vectors  $[v_1, \ldots, v_n]$  for any  $v_1, \ldots, v_n \in V$  is called the derived algebra of V, which is denoted by  $V^1$ . If  $V^1 = 0$ , V is called an abelian algebra.

**Definition 1.7:-** [1] The derived algebra of an n - Lie algebra V is a subalgebra of V generated by  $[v_1, \dots, v_n]$  for all  $v_1, \dots, v_n \in V$  and is a linear transformation

 $D: V \to V$ . Satisfying,  $D([v_1, ..., v_n]) = \sum_{i=1}^n [v_1 ..., D(v_i), ..., v_n]$  for all  $v_1, ..., v_n \in V$ and the set of all *derivation* is denoted by Der(V) for all  $v_1, ..., v_n \in V$ . The map  $ad(v_1, ..., v_{n-1}): V \to V$  is given by  $ad(v_1, ..., v_{n-1})(u) = [v_1, ..., v_{n-1}, u]$  for all  $u \in V$ .

### 2-Involutive Gamma Derivation on n – Gamma Lie algebra

In this section, we study *involutive*  $\lambda$  – *derivations* on  $n - \lambda$  – *Lie algebras* 

**Definition 2.1:-** Let *V* be an *associative*  $\Gamma$  – *algebra* over a field *F*, then for all  $\lambda \in \Gamma, n - \lambda - Lie \ algebra \ L_{\lambda}(V)$  can be defined with a linear multiplication  $[, \dots, ]_{\lambda}: \wedge^{n} V \to V$  satisfies for all  $v_{1}, \dots, v_{n}, u_{2}, \dots, u_{n} \in V$ .  $[[v_{1}, \dots, v_{n}]_{\lambda}, u_{2}, \dots, u_{n}]_{\lambda} = \sum_{i=1}^{n} [v_{1} \dots, [v_{i}, u_{2}, \dots, u_{n}]_{\lambda}, \dots, v_{n}]_{\lambda}$ , then *A* is an  $n - \lambda - Lie \ subalgebra$  of  $(V, [, \dots, ]_{\lambda})$  if it is closed under the bracket, that means if  $[A, A, \dots, A, A, ]_{\lambda} \subseteq A$ , and subspace  $\mathcal{I}$  of *V* is called an *ideal* if  $[\mathcal{I}, V, V, \dots, V, V]_{\lambda} ) \subseteq \mathcal{I}$ , and the center of  $(V, [, \dots, ]_{\lambda})$  is denoted by  $Z(V) = \{v \in V: [v, v_{1}, \dots, v_{n}]_{\lambda} = 0$  for all  $v_{1}, \dots, v_{n} \in V\}$ , Z(V) is an *abelian ideal* of *V*.

**Definition 2.2:** Let V be an  $n - \lambda - Lie$  algabra over F, a transformation linear  $D: V \rightarrow V$  satisfies  $D([v_1, ..., v_n]_{\lambda}) = \sum_{i=1}^n [v_1, ..., D(v_i), ..., v_n]_{\lambda}$  is  $\lambda - derivation$  of V for all  $v_1, ..., v_n \in V$ . The set of all  $\lambda - derivation D$  is defined by  $Der_{\lambda}(V)$ , and if a  $\lambda - derivation$  D satisfies  $D^2 = I_d$ , then D is called an involutive  $\lambda - derivation$  on V, and if V is a finite dimensional vector space over F, and D is an  $\lambda$ -endomorphism of V with  $D^2 = I_d$ , then V can be decomposed into the direct sum of

subspaces  $V = V_1 + V_{-1}$  (1) where  $V_1 = \{v \in V | Dv = v\}$ , and  $V_{-1} = \{v \in V | Dv = -v\}$ . And if *D* is an *involutive*  $\lambda$  - *derivation* on *V*.

Then  $D([v_1, ..., v_n]_{\lambda}) = \sum_{i=1}^{n} [v_1 ..., D(v_i), ..., v_n]_{\lambda} = n[v_1, ..., v_n]_{\lambda}, \forall v_1, ..., v_n \in V.$ **Example 2.3 :-** Let *V* be a 3 – *dimensional* 3 –  $\lambda$  – *Lie algebra* with the multiplication of *V* in the basis  $\{e_1, e_2, e_3\}$  be as follows,  $[e_1, e_2, e_3]_{\lambda} = e_1$ . A linear mapping  $D : V \to V$  defined by  $D(e_i) = e_i$  for  $1 \le i \le 2$ , and  $D(e_3) = -e_3$  is an *involutive*  $\lambda$  – *derivation* on *V*, and it satisfies  $e_1, e_2 \in V_1$  and  $e_3 \in V_{-1}$ .

**Theorem 2.4:-** For any  $n - \lambda - Lie \ algabra V$  the algebra  $D_{\lambda}(V)$  is a  $\lambda$ -Lie subalgebra of  $gl_{\lambda}(V)$ .

**Proof :** Since  $D([v_1, ..., v_n]_{\lambda}) = \sum_{i=1}^n [v_1, ..., D(v_i), ..., v_n]_{\lambda}$ , then for all  $D_1, D_2 \in D_{\lambda}(V)$  and  $v_1, ..., v_n \in V$  we have  $D_1 D_2([v_1, ..., v_n]_{\lambda}) = D_1(\sum_{i=1}^n [v_1, ..., D_2(v_i), ..., v_n]_{\lambda}) = \sum_{i=1}^n [v_1, ..., D_1 D_2(v_i), ..., v_n]_{\lambda} + \sum_{1 \le s \ne i \le n}^n [v_1, ..., D_1(v_s), ..., D_2(v_i), ..., v_n]_{\lambda}$ Similarly, we get  $D_2 D_1([v_1, ..., v_n]_{\lambda}) = D_2(\sum_{i=1}^n [v_1, ..., D_1(v_i), ..., v_n]_{\lambda}) = \sum_{i=1}^n [v_1, ..., D_2 D_1(v_i), ..., v_n]_{\lambda} + \sum_{1 \le s \ne i \le n}^n [v_1, ..., D_2(v_s), ..., D_1(v_i), ..., v_n]_{\lambda}$ Hence, it implies

$$\begin{array}{l} (D_1 D_2 - D_2 D_1)([v_1, \dots, v_n]_{\lambda}) = \sum_{i=1}^n [v_1, \dots, (D_1 D_2 - D_2 D_1)(v_i), \dots, v_n]_{\lambda} \\ = \sum_{i=1}^n [v_1, \dots, [D_1 D_2]_{\lambda}(v_i), \dots, v_n]_{\lambda} = [D_1 D_2]_{\lambda}([v_1, \dots, v_n]_{\lambda}). \\ \text{Therefore} \qquad \text{the} \qquad \text{result} \qquad \text{is} \qquad \text{obtained} \end{array}$$

**Lemma 2.5 :-** Let V be an  $n - \lambda$  – Lie algebra over F. If  $D \in D_{\lambda}(V)$  is an *involutive*  $\lambda$  – derivation then for all  $v_1, \ldots, v_n \in V$ 

$$[v_1, \dots, v_n]_{\lambda} = \frac{-2}{n-1} \sum_{i=1}^n [v_1, \dots, v_{i-1}, D(v_i), v_{i+1}, \dots, D(v_j), v_{j+1}, \dots, v_n]_{\lambda}$$

And

$$\begin{bmatrix} D(v_1), \dots, D(v_n) \end{bmatrix}_{\lambda} = \frac{-2}{n-1} \sum_{i=1}^{n} \left[ D(v_1), \dots, D(v_{i-1}), v_i, D(v_{i+1}), \dots, D(v_{j-1}), v_j, D(v_{j+1}), \dots, D(v_n) \right]_{\lambda}$$

**Proof:**-If *D* is an *involutive*  $\lambda$  – *derivation* on V then for all  $v_1, \dots, v_n \in V$  we have  $[v_1, \dots, v_n]_{\lambda} = D^2([v_1, \dots, v_n]_{\lambda}) = D(D([v_1, \dots, v_n]_{\lambda}))$   $= D(\sum_{i=1}^n [v_1, \dots, D(v_i), \dots, v_n]_{\lambda}) = \sum_{i=1}^n [v_1, \dots, D(D(v_i)), \dots, v_n]_{\lambda}$   $+ \sum_{i < j}^n [v_1, \dots, D(v_i), \dots, D(v_j), \dots, v_n]_{\lambda} + \sum_{j < n} [v_1, \dots, D(v_i), \dots, D(v_j), \dots, v_n]_{\lambda}$   $= \sum_{i=1}^n [v_1, \dots, v_i, \dots, v_n]_{\lambda} + 2n \sum_{1 \le i < j}^n [v_1, \dots, D(v_i), \dots, D(v_j), \dots, v_n]_{\lambda}$ Then  $(n-1)[v_1, \dots, v_n]_{\lambda} = -2n \sum_{1 \le i < j}^n [v_1, \dots, D(v_i), \dots, D(v_j), \dots, v_n]_{\lambda}$   $[v_1, \dots, v_n]_{\lambda} = \frac{-2}{n-1} \sum_{i=1}^n [v_1, \dots, v_{i-1}, D(v_i), \dots, v_{j-1}, D(v_j), \dots, v_n]_{\lambda}$ And  $[D(v_1), \dots, D(v_n)]_{\lambda} = \frac{-2}{n-1} \sum_{i=1}^n [D(v_1), \dots, D(v_{i-1}), v_i, D(v_{j-1}), v_j, D(v_{j+1}), \dots, D(v_n)]_{\lambda}$ 

**Theorem 2.6 :-** Let V be a finite dimensional  $n - \lambda - Lie \ algebra$  with  $n = 2r, r \ge 1$ . Then there is an *involutive*  $\lambda - derivation D \ on V$  if and only if V is *abelian*. **Proof:-** If *V* is abelian then  $[u_1, \ldots, u_i, v_1, \ldots, v_{n-i}]_{\lambda} = 0$ , hence *D* is an *involutive*  $\lambda$  – *derivation D* on *V*. Conversely, let *D* be an *involutive*  $\lambda$  – *derivation* on *V*, then *V* can be *decomposed* into the *direct sum* of *subspaces*  $V = V_1 + V_{-1}$ . Hence, for any  $i \in \mathbb{Z}$ ,  $1 \le i \le n$ ,  $u_1, \ldots, u_n \in V_1$ , and  $v_1, \ldots, v_n \in V_{-1}$  $D([u_1, \ldots, u_i, v_1, \ldots, v_{n-i}]_{\lambda}) = i[u_1, \ldots, u_i, v_1, \ldots, v_{n-i}]_{\lambda} - (n-i)[u_1, \ldots, u_i, v_1, \ldots, v_{n-i}]_{\lambda}$  $= (2i - 2r)[u_1, \ldots, u_i, v_1, \ldots, v_{n-i}]_{\lambda} \in V_{2i-2r}$ . Then  $D([u_1, \ldots, u_n]_{\lambda}) = 2r[u_1, \ldots, u_n]_{\lambda}$ , and  $D([v_1, \ldots, v_n]_{\lambda}) = -2r[v_1, \ldots, v_n]_{\lambda}$ . Then  $\pm 2r \ne 1$  and  $2i - 2r \ne \pm 1$ ,  $V_{2i-2r}$ ,  $V_{\pm 2r} = 0$ . Therefore *V* is .

**Theorem 2.7 :-** Let V be a finite dimensional  $n - \lambda - Lie \ algebra$  with n=2r+1,  $r \ge 1$ , and D be an *involutive*  $-\lambda - derivation$  on V, then  $V_1$  and  $V_{-1}$  are *abelian subalgebras*, and

$$\begin{bmatrix} \underbrace{V_1, \dots, V_1}_j, \underbrace{V_{-1}, \dots, V_{-1}}_{2r+1-j} \end{bmatrix}_{\lambda} = 0 \quad \forall 1 \le j \le 2r, j \ne r, r+1 \\ \begin{bmatrix} \underbrace{V_1, \dots, V_1}_{r+1}, \underbrace{V_{-1}, \dots, V_{-1}}_r \end{bmatrix}_{\lambda} \subseteq V_1, \qquad \begin{bmatrix} \underbrace{V_1, \dots, V_1}_r, \underbrace{V_{-1}, \dots, V_{-1}}_{r+1} \end{bmatrix}_{\lambda} \subseteq V_{-1} \end{bmatrix}$$

**proof.** Since  $D \in D_{\lambda}(V)$ 

$$\begin{bmatrix} V_{1}, \dots, V_{1}, V_{-1}, \dots, V_{-1} \\ j \end{bmatrix} \subseteq V_{2j-2r-1}, 0 \le j \le 2r+1$$
  
If  $\begin{bmatrix} V_{1}, \dots, V_{1}, V_{-1}, \dots, V_{-1} \\ j \end{bmatrix}_{\lambda} \ne 0$  then  $2r+1-j = \mp 1$  that is  $r+1 = j$ . Therefore  $\begin{bmatrix} V_{1}, \dots, V_{1} \\ j \end{bmatrix}_{\lambda} = \begin{bmatrix} V_{-1}, \dots, V_{-1} \\ 2r+1-j \end{bmatrix}_{\lambda} = 0$ 

**Theorem 2.8 :-** Let *V* be an m – dimensional  $n - \lambda$  – Lie algebra with  $n = 2r + 1, r \ge 1$ . Then there is an involutive  $\lambda$  – derivation on *V* if and only if *V* has the decomposition V = A + B such that

$$\begin{bmatrix} \underline{A}, \dots, \underline{A}, \underline{B}, \dots, \underline{B} \end{bmatrix}_{\lambda} = 0 \ \forall 1 \le i \le 2r, i \ne r, r+1$$

$$\begin{bmatrix} \underline{A}, \dots, \underline{A}, \underline{B}, \dots, \underline{B} \end{bmatrix}_{\lambda} \subseteq B \quad , \quad \begin{bmatrix} \underline{A}, \dots, \underline{A}, \underline{B}, \dots, \underline{B} \end{bmatrix}_{\lambda} \subseteq A$$

$$(3)$$

**Proof**: If D is an *involutive*  $\lambda$  – *derivation* on V, then by Theorem 2.7 we have  $A = V_1$ , and  $B = V_{-1}$  satisfy

$$\begin{bmatrix} \underline{A}, \dots, \underline{A}, \underline{B}, \dots, \underline{B} \\ 2r+1-i \end{bmatrix}_{\lambda} = 0 \ \forall 1 \le i \le 2r, i \ne r, r+1$$
$$\begin{bmatrix} \underline{A}, \dots, \underline{A}, \underline{B}, \dots, \underline{B} \\ r+1 \end{bmatrix}_{\lambda} \subseteq B \quad , \quad \begin{bmatrix} \underline{A}, \dots, \underline{A}, \underline{B}, \dots, \underline{B} \\ r+1 \end{bmatrix}_{\lambda} \subseteq A$$
Now let D be some network here of V defined here.  $D(x) = x \cdot D(x)$ 

Now, let D be an endomorphism of V defined by D(u) = u, D(v) = -v, for all  $u \in A, v \in B$ . Then  $D^2 = Id$ ,  $A = V_1$ , and  $B = V_{-1}$  satisfy (2) and (3). Therefore D is an *involutive*  $\lambda$  – derivation on V.

**Corollary 2.9 :** Let A be a (2r + 1)-dimensional ,  $(2r + 1) - \lambda - Lie \ algebra$ 

with the multiplication  $[e_1, \dots, e_{2r+1}]_{\lambda} = e_1$ , where  $\{e_1, \dots, e_{2r+1}\}$  is a basis of V. Then the *linear mapping*  $D: V \to V$ . Now by  $D(e_i) = e_i$ ,  $1 \le i \le r+1$   $D(e_j) = -e_j$ ,  $(r+1) \le j \le (2r+1)$  is an *involutive*  $\lambda$  – *derivation* on V.

**Proof.** Since an *endomorphism* D of V defined by  $D(e_i) = e_i$ ,  $1 \le i \le r+1$ ,  $D(e_j) = -e_j$ , (r+1)  $j \le (2r+1)$ , however by Theorem 2.7 we get  $D^2 = Id$ , so that there is an *involutive*  $\lambda$  – *derivation* on V.

# 3- Involutive Gamma Derivations with $3 - \lambda - Lie Algebras$

In this section, we study *involutive*  $\lambda$  – *derivations* on 3 –  $\lambda$  – *Lie Algebras* 

**Definition 3.1:**- Let  $(V, [,]_{\lambda})$  be an *associative*  $\lambda - Lie$  algebra over F, such that  $\lambda \in \Gamma$  and k is an element which is not contained in V then  $U = V + F_k$  is a  $3 - \lambda - Lie$  Algebras in the multiplication.

$$[u, r, h]_{\lambda} = 0$$

(4)

 $[k, u, r]_{\lambda} = [u, r]_{\lambda}$ , for all  $u, r, h \in V$ . And the  $3 - \lambda$  – Lie Algebras

 $(U, [,,]_{\lambda})$  is called one-dimensional extension of V. For example let V be an abelian  $\lambda$  – Lie algebra with the basis $\{e_1, e_2, e_3\}$ , and let  $U = V + F_k$ ,  $F_k \subseteq Z(U)$ , then  $[e_1, e_2, e_3]_{\lambda} = 0$ , and for all  $k \in F_k$ ,  $[k, e_i, e_j]_{\lambda} = [e_i, e_j]_{\lambda}$ ,  $1 \le i, j \le 3$ ,  $i \le j$ . Therefore  $(U, [,,]_{\lambda})$  is one-dimensional extension of V.

**Theorem 3.2 :-** Let V be  $3 - \lambda - Lie$  Algebras then U is one dimensional extension of a  $\lambda - Lie$  Algebras  $(V, [,]_{\lambda})$  if and only if the exists an *involutive*  $\lambda - derivation D_{\lambda}$  on V such that either  $dimV_1 = 1$ , or  $dimV_{-1} = 1$ .

**Proof**:- If *U* is one-dimensional extension of a  $\lambda$  -Lie algebra V then  $U_{\lambda} = V_{\lambda} + F_k$ . Since  $D_{\lambda}: U \to U$  is endomorphism which is defined by  $D_{\lambda}(k) = k$ , (or(-k)) with  $D_{\lambda}(r) = r(or(-r) r \in V)$ .  $D_{\lambda}^2(k) = D_{\lambda}(D_{\lambda}(k)) = D_{\lambda}(k) = k$ , and  $D_{\lambda}^2(-k) = -k$  then  $D_{\lambda}^2 = Id$ 

 $D_{\lambda} ([u, r, h]_{\lambda}) = [D_{\lambda}(u), r, h]_{\lambda} + [u, D_{\lambda}(r), h]_{\lambda} + [u, r, D_{\lambda}(h)]_{\lambda} = 0$ 

 $\begin{array}{l} D_{\lambda} \ ([k,u,r]_{\lambda}) = [D_{\lambda}(k),u,r]_{\lambda} + [k,D_{\lambda}(u),r]_{\lambda} + \ [k,u,D_{\lambda}(r)]_{\lambda} = \ [k,u,r]_{\lambda} = \ [u,r]_{\lambda}, \ \text{for all} \\ u,r \in V \text{.Therefore} \ D_{\lambda} \ \text{is an involutive} \ \lambda - derivation \ \text{on} \ V \ \text{such that} \ dim V_1 = 1 \ \text{, or} \\ dim V_{-1} = 1 \ \text{. Conversely, let} \ D_{\lambda} \ \text{be an involutive} - \lambda - derivation \ \text{on} \ V \ \text{such that} \\ dim V_1 = 1 \ \text{, or} \ dim V_{-1} = 1 \ \text{. Let} \ U_{-1} = F_K \ \text{, and} \ U_1 = V \ (\text{or} \ U_{-1} = V, \ \text{and} \ U_1 = F_K) \\ \text{,where} \ k \in U - V \ \text{. Then by Theorem 2.6} \ \text{,} \ V \ \text{is an} \ \lambda - Lie \ algebra \ \text{with} \ \text{the} \\ \text{multiplication} \ [u,r]_{\lambda} = [k,u,r]_{\lambda} \ \text{for all} \ u,r \in V, \ \text{and} \ U \ \text{is one} \ - \ dimensional \ extension} \\ \text{of} \ V \ \text{.} \end{array}$ 

Let  $(V, [,]_{1\lambda})$  and  $(V, [,]_{2\lambda})$  be  $\lambda$  – *Lie algebras*, and  $\{v_1, \ldots, v_n\}$  is a basis of V. It is easy to define  $\lambda$  – *Lie algebras*  $(V, [,]_{\lambda})$  be  $V_m$ , m = 1,2, and let  $k_1, k_2$  are two distinct elements which are not contained in V, and  $3 - \lambda$  – *Lie Algebras*  $(U_1, [,]_{1\lambda})$  and  $(U_2, [,]_{2\lambda})$  are one – dimentional extension of  $\lambda$  – *Lie algebras*  $V_1$ , and  $V_2$ , respectively such that  $U_1 = V_1 + F_{K1}$ ,  $U_2 = V_2 + F_{K2}$ , then  $D_{\lambda}(V_1)$  and  $D_{\lambda}(V_2)$  are sub algebras of  $gl_{\lambda}(V)$ .

**Definition 3.3 :** Let  $U_1 = (V, [, ]_{1\lambda})$ , and  $U_2 = (V, [, ]_{2\lambda})$  be two  $\lambda$  – *Lie algebras*, and  $k_1, k_2$  are two special elements that are not present in V such that  $U = V + F_{K1} + F_{K2}$ . Then  $3 - \lambda$  – *Lie Algebras*  $(U, [, , ]_{\lambda})$  is called a *two* – *dimensional extension* of  $\lambda$  – *Lie Algebras*  $V_m, m = 1, 2$  such that  $[, , ]_{\lambda} : U \wedge U \wedge U \rightarrow U$  defined by  $[u, r, k_1]_{\lambda} = [u, r]_{1\lambda}$ ,  $[u, r, k_2]_{\lambda} = [u, r]_{2\lambda}$ ,  $[u, r, h]_{\lambda} = 0$  (5)

 $[k_1, k_2, u]_{\lambda} = \alpha_u k_1 + \beta_u k_2 \quad \forall u, r, h \in V, and \alpha_u, \beta_u \in F$ If U is an  $3 - \lambda$  – Lie Algebras then U is called a two-dimensional extension  $3 - \lambda$  – Lie Algebras of  $\lambda$  – Lie Algebras  $V_m$ , m = 1,2Let  $U = V_m + R$  be a two – dimensional extension of  $\lambda$  – Lie Algebras  $V_m$ , m = 1,2And  $R = F_{K1} + F_{K2}$ . Define linear mappings  $3 - \lambda$  – Lie Algebras as follows  $D_{1\lambda}(u)=ad(k_1,u)$ ,  $D_{2\lambda}(u)=ad(k_2,u)$ , (6) $D_{\lambda}(u) = ad(k_1, k_2)(u) \forall u \in V$  that is, for all  $\forall r \in V$  $D_{1\lambda}(u)(r) = [u, r, k_1]_{\lambda} = [u, r]_{1\lambda}$ , (7) $D_{2\lambda}(u)(r) = [u, r, k_2]_{\lambda} = [u, r]_{2\lambda}$ , and,  $D_{\lambda}(u) = [k_1, k_2, u]_{\lambda}$ **Theorem 3.4 :-** Let  $3 - \lambda - Algebras U$  be a two-dimensional extension of  $\lambda - Lie$ Algebras  $V_m$ , m = 1,2 then U is a  $3 - \lambda$  – Lie Algebras if and only if linear mappings  $D_{1\lambda}, D_{2\lambda}, \text{ and } D_{\lambda} \text{ where } D_{1\lambda}: V_1 \to Der_{\lambda}(V_1), D_{2\lambda}: V_2 \to Der_{\lambda}(V_2) \text{ are } \lambda - Lie$ homomorphisms, and  $D_{1\lambda}(u_3)[u_1, u_2]_{2\lambda} = [D_{1\lambda}(u_3)(u_1), u_2]_{2\lambda} + [(u_1), D_{1\lambda}(u_3)u_2]_{2\lambda}$ (8)  $-\alpha_{u_3}[u_1, u_2]_{1\lambda} - \beta_{u_3}[u_1, u_2]_{2\lambda}$  $D_{2\lambda}(u_3)[u_1, u_2]_{1\lambda} = [D_{2\lambda}(u_3)(u_1), u_2]_{1\lambda} + [(u_1), D_{2\lambda}(u_3)u_2]_{1\lambda}$ (9)  $+\alpha_{u_3}[u_1, u_2]_{1\lambda} + \beta_{u_3}[u_1, u_2]_{2\lambda}$  $D_{\lambda}([u_1, u_2]_{1\lambda}) = (\beta_{u_1} \alpha_{u_2} - \alpha_{u_1} \beta_{u_2})k_1$ (10) $D_{\lambda}([u_1, u_2]_{2\lambda}) = (\beta_{u_1} \alpha_{u_2} - \alpha_{u_1} \beta_{u_2}) k_2$ (11) $D_{i\lambda}(u_1), (u_2) = -D_{i\lambda}(u_2), (u_1)$ (12)for all  $u_1, u_2 \in V$ , i = 1, 2Where  $u_1, u_2, u_3 \in V$ ,  $D_{\lambda}(u_i) = \alpha_{ui}k_1 + \beta_{ui}k_2$  i = 1, 2, 3**Proof** : If U is two – dimensional extension  $3 - \lambda$  – Lie Algebras then, by definition 3.3 linear mappings  $D_{i\lambda}$  satisfy  $D_{i\lambda}(V_i) \subseteq Der_{\lambda}(V_i)$ , and  $D_{i\lambda}$  are  $\lambda$  – Lie homomorphisms i = 1,2 by (5) we have  $D_{1\lambda}(u_3)[u_1, u_2]_{2\lambda} = [k_1, u_3, [u_1, u_2]_{2\lambda}]_{\lambda} = [k_1, u_3[k_2, u_1, u_2]_{2\lambda}]_{\lambda}$  $= [k_2, [k_1, u_3, u_1]_{\lambda}, u_2]_{\lambda} + [k_2, u_1, [k_1, u_3, u_2]_{\lambda}]_{\lambda} + [[k_1, u_3, k_2]_{\lambda}, u_1, u_2]_{\lambda}$  $= [k_2, D_{1\lambda}(u_3)(u_1), u_2]_{\lambda} + [k_2, u_1, D_{1\lambda}(u_3)(u_2)]_{\lambda} - [[k_1, k_2, u_3]_{\lambda}, u_1, u_2]_{\lambda}$  $= [D_{1\lambda}(u_3)(u_1), u_2]_{2\lambda} + [u_1, D_{1\lambda}(u_3)(u_2)]_{2\lambda} - \alpha_{u_3}[u_1, u_2]_{1\lambda} - \beta_{u_3}[u_1, u_2]_{2\lambda}$ Then for all  $u_1, u_2, u_3 \in V$  the equation (8) holds, The same way can be found (9) Now if  $D_{\lambda}([u_1, u_2]_{1\lambda}) = ad(k_1, k_2)[u_1, u_2]_{1\lambda} = [k_1, k_2, [u_1, u_2]_{1\lambda}]_{\lambda}$  $= [k_1, k_2, [k_1, u_1, u_2]_{\lambda}]_{\lambda} =$  $[k_1, [k_1, k_2, u_1]_{\lambda}, u_2]_{\lambda} + [k_1, u_1, [k_1, k_2, u_2]_{\lambda}]_{\lambda} + [[k_1, k_2, k_1]_{\lambda}, u_1, u_2]_{\lambda}$  $= -[[k_1, k_2, u_1]_{\lambda}, k_1, u_2]_{\lambda} + [[k_1, k_2, u_2]_{\lambda}, k_1, u_1]_{\lambda}$  $= (-\alpha_{u_1}[k_1, u_2]_{\lambda} k_1 - \beta_{u_1}[k_1, u_2]_{\lambda} k_2) + (\alpha_{u_2}[k_1, u_1]_{\lambda} k_1 - \beta_{u_2}[k_1, u_1]_{\lambda} k_2)$  $= -\alpha_{u_1} D_{\lambda 1}(u_2)(k_1) - \beta_{u_1} D_{\lambda 1}(u_2)(k_2) + \alpha_{u_2} D_{\lambda 1}(u_1) k_1 \beta_{u_2} D_{\lambda 1}(u_1) (k_2)$  $= -\alpha_{u_1}[k_1, u_2, k_1]_{\lambda} - \beta_{u_1}[k_1, u_2, k_2]_{\lambda} + \alpha_{u_2}[k_1, u_1, k_1]_{\lambda} + \beta_{u_2}[k_1, u_1, k_2]_{\lambda}$  $= \beta_{u_1}[k_1, k_2, u_2]_{\lambda} - \beta_{u_2}[k_1, k_2, u_1]_{\lambda} = \beta_{u_1}(\alpha_{u_1}k_1 + \beta_{u_2}k_2) - \beta_{u_2}(\alpha_{u_1}k_1 + \beta_{u_1}k_2)$  $=\beta_{u_1}\alpha_{u_1}k_1 + \beta_{u_1}\beta_{u_2}k_2 - \beta_{u_2}\alpha_{u_1}k_1 - \beta_{u_2}\beta_{u_1}k_2 = \beta_{u_2}\alpha_{u_1}k_1 - \beta_{u_2}\alpha_{u_1}k_1$  $D_{\lambda}([u_1, u_2]_{1\lambda}) = (\beta_{u_1}\alpha_{u_2} - \beta_{u_2}\alpha_{u_1})k_1$ 

Then for all  $u_1, u_2 \in V$ , and  $\alpha_{ui}, \beta_{ui} \in F$ , i = 1,2 equation (10) holds. The same way can be found (11)  $D_{i\lambda}(u_1)(u_2) = ab(k_i, (u_1)(u_2)) = [k_i, u_1, u_2]_{i\lambda} = -[k_i, u_2, u_1]_{i\lambda}$  $D_{i\lambda}(u_1)(u_2) = -D_{i\lambda}(u_2), (u_1), \forall u_1, u_2 \in V, i = 1, 2$ . Then for all  $u_1, u_2 \in V, i = 1, 2$ equation (12) hold Conversely, by equation (5), for all  $u_1, u_2, u_3, u \in V$  $[u_1,u_2,u_3]_{\lambda}=0$  ,  $[k_1$  ,  $u_1,u_2]_{\lambda}=D_{1\lambda}\left(u_1\right)(u_2)=[u_1,u_2]_{1\lambda}$  $[k_2, u_1, u_2]_{\lambda} = D_{2\lambda}(u_1)(u_2) = [u_1, u_2]_{2\lambda} \quad , \quad [k_1, k_2, u]_{\lambda} = D_{\lambda}(u) = \alpha_u k_1 + \beta_u k_2$ (13)Since  $D_{i\lambda}(V_i) \subseteq D_{\lambda}(V_i)$ , and  $D_{i\lambda}$  are  $\lambda$  – Lie homomorphisms,  $i = 1, 2, U_1 = V_1 + F_{K1}$ ,  $U_2 = V_2 + F_{K2}$  are  $3 - \lambda$  – Lie Algebras which are one – dimensional extension 3 –  $\lambda$  – Lie Algebras of  $\lambda$  – Lie Algebras  $V_i$ , i = 1,2, respectively. Next it suffices to prove that the multiplication on U defined by equation (5) satisfies fulfills of the definition 1.6 for all  $u_i \in V$  such that  $1 \le i \le 5$ , and the products  $[u_1, u_2, [u_3, u_4, u_5]_{\lambda}]_{\lambda} = [[u_1, u_2, u_3]_{\lambda}, u_4, u_5]_{\lambda} + [u_3, [u_1, u_2, u_4]_{\lambda}, u_5]_{\lambda}$ +  $[u_3, u_4[u_1, u_2, u_5]_{\lambda}]_{\lambda}$ (14) $\left[\left[k_{j}, u_{2}, u_{3}\right]_{\lambda}, u_{4}, u_{5}\right]_{\lambda}, \left[\left[u_{1}, u_{2}, u_{3}\right]_{\lambda}, u_{4}, k_{j}\right]_{\lambda} \text{ and } \left[\left[u_{1}, u_{2}, k_{j}\right]_{\lambda}, u_{4}, k_{j}\right]_{\lambda}\right]_{\lambda}$ and the products with definition 1.6, j = 1,2. Therefore  $U_1 = V_1 + F_{K1}$ , and  $U_2 = V_2 + F_{K2}$  are one – dimensional extension  $3 - \lambda$  – Lie Algebras of  $V_i$ , i = 1,2 and equation (5) is directly obtained from equation (8), and equation (9). It follows that the products  $[[k_i, u_1, u_2]_{\lambda}, k_j, u_3]_{\lambda}$   $1 \le i \ne j \le 2$  fulfill definition 1.6. It follows from equation (10) – (12) that the products  $[k_1, k_2, [k_i, u_1, u_2]_{\lambda}]_{\lambda}$ ,  $[u_1, u_2[k_i, k_2, u_3]_{\lambda}]_{\lambda}$ , and  $[k_i u_1, [k_1, k_2, u_2]_{\lambda}]_{\lambda}$ , i = 1,2 fulfill the conditions of definition 1.6. **Theorem3.5:-** Let (U, [,,]) be a  $3 - \lambda$  – Lie Algebras. Then U is a two dimensional extension  $3 - \lambda$  – Lie Algebras of  $\lambda$  – Lie Algebras if and only if there is an *involutive*  $-\lambda$  *derivation* D on U such that  $dimU_1 = 2$  or  $dimU_{-1} = 2$ . **Proof**. If U is a two-dimensional extension  $3 - \lambda$  - Lie Algebras of  $\lambda$  -*Lie Algebras* then by Theorem 3.2 there are  $\lambda$  – *Lie Algebras*  $V_1 = (V, [, ]_{1\lambda}) \text{ and } V_2 = (V, [, ]_{2\lambda})$ such that U = V + R, and the multiplication of U is defined by equation (5) where  $R = F_{K1} + F_{K1}$ 

*F*<sub>K2</sub>. Now define the endomorphism D of U by D(u) = u,  $D(K_1) = -K_1$ ,  $D(K_2) = -K_2$ , or D(u) = -u,  $D(K_1) = K_1$ ,  $D(K_2) = K_2$ ,  $\forall u \in V$  then  $D^2 = Id$ , and  $U_1 = V$ ,  $U_{-1} = R$ , or  $U_{-1} = V$ ,  $U_1 = R$ . Thus by equation (4), and equations (8) - (12), involutive  $-\lambda$  − derivation D of U.

Conversely, if there is an *involutive*  $-\lambda - derivation D$  on the  $3 - \lambda - Lie Algebras U$  such that  $dimU_{-1} = 2$  (or  $dimU_1 = 2$ ) then by Theorem 2.8 we have  $[U_1, U_1, U_1] = 0$ ,  $[U_1, U_1, U_{-1}] \subseteq U_1$ ,  $[U_1, U_{-1}, U_{-1}] \subseteq U_{-1}$ . Let  $V = U_1$  and  $U_1 = F_{K1} + F_{K2}$ .

Therefore  $[V, V, K \ 1] \subseteq V$ ,  $[V, V, K_2] \subseteq V$  and  $(V, [,]_{1\lambda})$ , and  $(V, [,]_{2\lambda})$  are  $\lambda - Lie \ Algebras$ , where  $[u, r]_{1\lambda} = [u, r, k_1]_{\lambda}$ ,  $[u, r]_{2\lambda} = [u, r, k_2]_{\lambda}$ ,  $\forall u, r \in V$ . Hence by Theorem 3.4

the  $3 - \lambda$  – Lie Algebras U is a two – dimensional extension  $3 - \lambda$  – Lie Algebras of  $\lambda$  – Lie Algebras  $V_1, V_2$ .

## 4 - *Involutive* $\lambda$ – *derivations* and compatible 3 – $\lambda$ – *pre Lie algebras*

In this section, we study *involutive*  $\lambda$  – *derivations* on compatible  $3 - \lambda - pre$  Lie algebras

**Definition 4. 1:-** A  $\lambda$  -representation of V (or an  $V - \lambda - module$ ) is a pair  $(U, \rho)$ , where V is a vector space,  $\rho^{\lambda} : V \wedge V \rightarrow End(U)$  is a linear map such that

$$\begin{split} \left[ \rho^{\lambda}(v_{1},v_{2})_{\lambda},\rho^{\lambda}(v_{3},v_{4})_{\lambda} \right]_{\lambda} &= \rho^{\lambda}(v_{1},v_{2})_{\lambda}\,\rho^{\lambda}(v_{3},v_{4})_{\lambda} - \rho^{\lambda}(v_{3},v_{4})_{\lambda}\,\rho^{\lambda}(v_{1},v_{2})_{\lambda} \\ &= \rho^{\lambda}([v_{1},v_{2},v_{3}]_{\lambda},v_{4})_{\lambda} - \rho^{\lambda}([v_{1},v_{2},v_{4}]_{\lambda},v_{3})_{\lambda} \\ \rho^{\lambda}([v_{1},v_{2},v_{3}]_{\lambda},v_{4})_{\lambda} &= \rho^{\lambda}(v_{1},v_{2})_{\lambda}\rho(v_{3},v_{4})_{\lambda} + \rho^{\lambda}(v_{2},v_{3})_{\lambda}\rho^{\lambda}(v_{1},v_{4})_{\lambda} \\ &+ \rho^{\lambda}(v_{1},v_{3})_{\lambda}\rho^{\lambda}(v_{2},v_{4})_{\lambda} \end{split}$$

for all  $v_i \in V$ ,  $1 \leq i \leq 4$ .

A linear mapping  $T^{\lambda}: U \to V$  is called an  $\lambda - \wp - operator$  which is associated to an  $V - \lambda - module (U, \rho)$  if T satisfies

$$\begin{bmatrix} T^{\lambda}u, T^{\lambda}v, T^{\lambda}w \end{bmatrix}_{\lambda} = T^{\lambda} \left( \rho^{\lambda} (T^{\lambda}u, T^{\lambda}v)w + \rho^{\lambda} (T^{\lambda}v, T^{\lambda}w)u + \rho^{\lambda} (T^{\lambda}w, T^{\lambda}u)v \right)_{\lambda}$$
(15)

for all  $u, v, w \in U$ , and (V, ad) is called the *adjoint*  $-\lambda$  – representation of V. **Theorem 4.2** : Let  $(V, [\cdot, \cdot, \cdot]_{\lambda})$  be a  $3 - \lambda$  – Lie algebr a with an involutive  $-\lambda$  –

derivation

 $D_{\lambda}$ . Then  $D_{\lambda}$  is an  $\lambda - \mathcal{D}$ -operator of V associated to the *adjoint*  $-\lambda$ -representation (V, ad), and D satisfies,  $\forall u_1, u_2, u_3 \in V$ 

$$[Du_{1}, Du_{2}, Du_{3}]_{\lambda} = D([Du_{1}, Du_{2}, u_{3}]_{\lambda} + [Du_{2}, Du_{3}, u_{1}]_{\lambda} + [Du_{3}, Du_{1}, u_{2}]_{\lambda}$$
  
**Proof**. By defined the a  $\lambda$  – derivation  $D_{\lambda}$ , and for all  $u_{1}, u_{2}, u_{3} \in V$ ,  
 $D(ad(Du_{1}, Du_{2})_{\lambda}u_{3} + ad(Du_{2}, Du_{3})_{\lambda}u_{1} + ad(Du_{3}, Du_{1})_{\lambda}u_{2})_{\lambda}$   
 $= D([Du_{1}, Du_{2}, u_{3}]_{\lambda} + [Du_{2}, Du_{3}, u_{1}]_{\lambda} + [Du_{3}, Du_{1}, u_{2}]_{\lambda})$   
 $= D([Du_{1}, Du_{2}, D^{2}u_{3}]_{\lambda} + [D^{2}u_{1}, Du_{2}, Du_{3}]_{\lambda} + [Du_{1}, D^{2}u_{2}, Du_{3}]_{\lambda})$   
 $= [Du_{1}, Du_{2}, Du_{3}]_{\lambda}$ . The proof is completed

**Definition 4.3 :** Let *V* be an associative  $\Gamma$  - algebra over a field with a  $\lambda$ -linear multiplication  $[, ,]_{\lambda}: V^{\Lambda 3} \to V, \forall u_1, u_2, u_3, u_4, u_5 \in V$ . The pair  $(V, \{,,\}_{\lambda})$  is called a  $3 - \lambda$  - preLie algebra if the next identities are correct

$$\{u_{1}, u_{2}, u_{3}\}_{\lambda} = -\{u_{2}, u_{1}, u_{3}\}_{\lambda}$$
(16)  

$$\{u_{1}, u_{2}, \{u_{3}, u_{4}, u_{5}\}_{\lambda}\}_{\lambda} = \{[u_{1}, u_{2}, u_{3}]_{\lambda c}, u_{4}, u_{5}\}_{\lambda} + \{u_{3}, [u_{1}, u_{2}, u_{4}]_{\lambda c}, u_{5}\}_{\lambda}$$
(17)  

$$\{[u_{1}, u_{2}, u_{3}]_{\lambda c}, u_{4}, u_{5}\}_{\lambda} = \{u_{1}, u_{2}, \{u_{3}, u_{4}, u_{5}\}_{\lambda}\}_{\lambda} + \{u_{2}, u_{3}, \{u_{1}, u_{4}, u_{5}\}_{\lambda}\}_{\lambda}$$
  

$$+ \{u_{3}, u_{1}, \{u_{2}, u_{4}, u_{5}\}_{\lambda}\}_{\lambda}$$

(18)

and [, ,]<sub> $\lambda$ C</sub> is defined by  $[u_1, u_2, u_3]_{\lambda C} = \{u_1, u_2, u_3\}_{\lambda} + \{u_2, u_3, u_1\}_{\lambda} + \{u_3, u_1, u_2\}_{\lambda}$  (19)

 $\begin{array}{l} \textbf{Proposition 4.4: Let } (V, \{, , \}_{\lambda}) \text{ be a } 3 - \lambda - pre \ Lie \ algebra \ .\text{Then the} \\ \{u_1, u_2, u_3\}_{\lambda c} \ defines \ a \ 3 - \lambda - Lie \ algebra \ \end{array}$   $\begin{array}{l} \textbf{Proof . By previous \ definition \ \{u_1, u_2, u_3\}_{\lambda c} \ is \ skew-symmetric \ for \ all \ u_i \in V \ , 1 \leq i \leq 5 \ \\ [u_1, u_2, [u_3, u_4, u_5]_{\lambda c}]_{\lambda c} \ -[[u_1, u_2, u_3]_{\lambda c}, u_4, u_5]_{\lambda c} -[u_3, [u_1, u_2, u_4]_{\lambda c}, u_5]_{\lambda c} \ \\ -[u_3, u_4, [\{u_1, u_2, u_5\}]_{\lambda c}]_{\lambda c} \ \\ -[u_3, u_4, [\{u_1, u_2, u_5\}]_{\lambda c}]_{\lambda c} \ \\ = \{u_1, u_2, \{u_3, u_4, u_5\}_{\lambda}\}_{\lambda} + \{u_1, u_2, \{u_4, u_5, u_3\}_{\lambda}\}_{\lambda} + \{u_1, u_2, \{u_5, u_3, u_4\}_{\lambda}\}_{\lambda} \ \\ + \{u_2, [u_3, u_4, u_5]_{\lambda c}, u_1\}_{\lambda} + \{[u_3, u_4, u_5]_{\lambda c}, u_1, u_2\}_{\lambda} \ \\ -\{u_4, u_5, \{u_1, u_2, u_3\}_{\lambda}\}_{\lambda} - \{u_4, u_5, \{u_2, u_3, u_1\}_{\lambda}\}_{\lambda} - \{u_4, u_5, \{u_3, u_1, u_2\}_{\lambda}\}_{\lambda} \ \\ -\{u_3, u_5, \{u_1, u_2, u_4\}_{\lambda}\}_{\lambda} - \{u_3, u_4, \{u_1, u_2, u_4\}_{\lambda}\}_{\lambda} - \{[u_1, u_2, u_3]_{\lambda c}, u_4, u_5, u_3, u_4\}_{\lambda} \ \\ -\{u_3, u_4, \{u_1, u_2, u_5\}_{\lambda}\}_{\lambda} - \{u_3, u_4, \{u_2, u_5, u_1\}_{\lambda}\}_{\lambda} - \{u_3, u_4, \{u_5, u_1, u_2\}_{\lambda}\}_{\lambda} \ \\ -\{u_4, [u_1, u_2, u_5]_{\lambda c}, u_3\}_{\lambda} - \{[u_1, u_2, u_5]_{\lambda c}, u_3, u_4\}_{\lambda} = 0 \end{array}$ 

(17). By applying the same previous discussion we get equation (18).

Therefore, *V* is a  $3 - \lambda - pre Lie algebra in the multiplication (20). The equation (21) follows from equation (1), and equation (23) a direct computation.$ 

**Theorem 4.6**: Let  $(V, [, ,]_{\lambda})$  be a  $3 - \lambda$  – Lie algebra,  $D_{\lambda}$  be an involutive –  $\lambda$  – derivation on V. Then  $D_{\lambda}$  is an  $\lambda$  – algebra isomorphism from the sub – adjacent 3 –  $\lambda$  – Lie algebra,  $(V, \{, ,\}_{\lambda Dc})$  of the  $3 - \lambda$  – pre Lie algebra  $(V, \{, ,\}_{\lambda D})$  to the  $3 - \lambda$  – Lie algebra  $(V, \{, ,\}_{\lambda D})$  to the  $3 - \lambda$  – Lie algebra  $(V, [, ,]_{\lambda})$ , and

$$\{u_1, u_2, u_3\}_{\lambda Dc} = \{u_1, u_2, u_3\}_{\lambda D} + \{u_2, u_3, u_1\}_{\lambda D} + \{u_3, u_1, u_2\}_{\lambda D}$$

$$= D[Du_1, Du_2, Du_3]_{\lambda}, u_1, u_2, u_3 \in V$$

$$(22)$$

Furthermore 
$$\{u_1, u_2, u_3\}_{\lambda Dc} = \begin{cases} 0, u_1, u_2, u_3 \in v_1 \text{ or } u_1, u_2, u_3 \in v_{-1} \\ -[u_1, u_2, u_3]_{\lambda} & u_1, u_2 \in v_1, u_3 \in v_{-1} \\ -[u_1, u_2, u_3]_{\lambda} & u_1, u_2 \in v_{-1}, u_3 \in v_1 \end{cases}$$
 (23)

**Proof**. By equation (20), the sub – adjacent  $3 - \lambda$  – Lie algebra,  $(V, \{, , \}_{\lambda Dc})$  with the multiplication

$$\{u_1, u_2, u_3\}_{\lambda Dc} = \{u_1, u_2, u_3\}_{\lambda D} + \{u_2, u_3, u_1\}_{\lambda D} + \{u_3, u_1, u_2\}_{\lambda D}$$

=  $[Du_1, Du_2, u_3]_{\lambda}$  +  $[Du_2, Du_3, u_1]_{\lambda}$  +  $[Du_3, Du_1, u_2]_{\lambda}$  =  $D[Du_1, Du_2, Du_3]_{\lambda}$ It follows Equation (22). Since

 $D(\{u_1, u_2, u_3\}_{\lambda Dc}) = D(D[Du_1, Du_2, Du_3]_{\lambda}) = D^2[Du_1, Du_2, Du_3]_{\lambda} = [Du_1, Du_2, Du_3]_{\lambda}$ for all  $u_1, u_2, u_3 \in V$ , the  $D_{\lambda}$  is an  $\lambda$  – algebra isomorphism . Hence equations(22), and equation (23) hold.

**Theorem 4.7**: Let  $(V, [, ,]_{\lambda})$  be a  $3 - \lambda$  – Lie algebra, and  $D_{\lambda}$  is an involutive –  $\lambda$  – derivation on V. Then there exists a compatible  $3 - \lambda$  – pre Lie algebra  $(V, \{, ,\}_{\lambda V})$  where  $\{u_1, u_2, u_3\}_{\lambda V} = D [u_1, u_2, Du_3]_{\lambda}$  (24)

**Proof.** By equation (24), we have  $\{u_1, u_2, u_3\}_{\lambda V} = D[u_1, u_2, Du_3]_{\lambda} = -D[u_2, u_1, Du_3]_{\lambda} = -\{u_2, u_1, u_3\}_{\lambda V}$  for all  $v_i \in V, 1 \le i \le 5$ , and  $\{u_1, u_2, \{u_5, u_3, u_4\}_{\lambda}\}_{\lambda} = D[u_1, u_2, D^2[u_3, u_4, Du_5]_{\lambda}]_{\lambda} = D[u_1, u_2, [u_3, u_4, Du_5]_{\lambda}]_{\lambda}$ 

we get equation (16) ,and  $D[u_3, u_4[u_1, u_2, Du_5]_{\lambda}]_{\lambda} = D([u_1, u_2, [u_3, u_4, Du_5]_{\lambda}]_{\lambda} - [[u_1, u_2, u_3]_{\lambda}, u_4, Du_5]_{\lambda} - [u_3, [u_1, u_2, u_4]_{\lambda}, Du_5]_{\lambda})$ 

Therefore

 $\{\{u_1, u_2, u_3\}_{\lambda V c}, u_4, u_5\}_{V\lambda} + \{u_3, \{u_1, u_2, u_4\}_{\lambda V c}, u_5\}_{V\lambda} + \{u_3, u_4, \{u_1, u_2, u_5\}_{\lambda V}\}_{V\lambda}$   $= D[\{u_1, u_2, u_3\}_{\lambda V c}, u_4, Du_5]_{\lambda} + D[u_3, \{u_1, u_2, u_4\}_{\lambda V c}, Du_5]_{\lambda} + D[u_3, u_4\{u_1, u_2, Du_5\}_{\lambda}]_{\lambda}$   $= D[D([u_1, u_2, Du_3]_{\lambda} + [u_2, u_3, Du_1]_{\lambda} + [u_3, u_1, Du_2]_{\lambda}), u_4, Du_5]_{\lambda}$   $+ D[u_3, D([u_1, u_2, Du_4]_{\lambda} + [u_2, u_4, Du_1]_{\lambda} + [u_4, u_1, Du_2]_{\lambda}), Du_5]_{\lambda}$   $+ D[u_3, u_4, [u_1, u_2, Du_5]_{\lambda}]_{\lambda}$ 

=

$$\begin{split} D([D(D[u_1, u_2, u_3]_{\lambda}), u_4, Du_5]_{\lambda} + \\ & [u_3, D(D[u_1, u_2, u_4]_{\lambda}), Du_5]_{\lambda} + [u_3, u_4, [u_1, u_2, Du_5]_{\lambda}]_{\lambda}) \\ & = D([D^2[u_1, u_2, u_3]_{\lambda}), u_4, Du_5]_{\lambda} + [u_3, D^2[u_1, u_2, u_4]_{\lambda}), Du_5]_{\lambda} + [u_3, u_4, [u_1, u_2, Du_5]_{\lambda}]_{\lambda}) \\ & = D([[u_1, u_2, u_3]_{\lambda}), u_4, Du_5]_{\lambda} + [u_3, [u_1, u_2, u_4]_{\lambda}), Du_5]_{\lambda} + [u_3, u_4[u_1, u_2, Du_5]_{\lambda}]_{\lambda}) \\ & = D([[u_1, u_2, u_3]_{\lambda}, u_4, Du_5]_{\lambda} + [u_3, [u_1, u_2, u_4]_{\lambda}, Du_5]_{\lambda} + [u_1, u_2, [u_3, u_4, Du_5]_{\lambda}]_{\lambda} \\ & \quad -[[u_1, u_2, u_3]_{\lambda}, u_4, Du_5]_{\lambda} - [u_3, [u_1, u_2, u_4]_{\lambda}, Du_5]_{\lambda}) \\ & = D[u_1, u_2, [u_3, u_4, Du_5]_{\lambda}]_{\lambda} = \{u_1, u_2, \{u_3, u_4, u_5\}_{\lambda V}\}_{V\lambda} \\ \\ \text{we get equation (17). By the same previous discussion we get equation (18). Hence} \\ & \{u_1, u_2, u_3\}_{\lambda V_C} = D([u_1, u_2, Du_3]_{\lambda} + [u_2, u_3, Du_1]_{\lambda} + [u_3, u_1, Du_2]_{\lambda}). \text{Hence } (V, \{ , , \}_{\lambda V}) \end{split}$$

is the compatible a  $3 - \lambda - pre$  Lie algebra of  $(V, [,,]_{\lambda})$ .

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