



ISSN: 0067-2904

On Partially Ordered P_S -Dislocated Metric Spaces

Jihan Muhamad Shakir* , Zena Hussein Maibed

Department of Mathematics, College of Education for Pure Sciences/ Ibn-AL-Haithem, University of Baghdad, Baghdad, Iraq

Received: 7/1/2025

Accepted: 12/9/2025

Published: 30/5/2026

Abstract:

Dislocated metrics play an important role in logical programming. Moreover, they are pivotal in fields such as topology and electronic engineering. These spaces are significant because they have the property of modifying self-distance property. This feature made many authors undertake extensive investigations of this metric, where they examined the fixed points of maps that exist in this space that meet specific requirements and studied the characteristics that set it apart. Additionally, they looked into whether R-contractions have the best proximity in the framework of dislocated metric spaces, and specific requirements be established to ensure that a best proximity point for these contractions is unique. Researchers worked on generalizing the concept of dislocated metric space to include b-dislocated metric space, S-dislocated metric space, and other forms of metric structures. This paper introduces the concept of P_S -dislocated metric spaces and the concepts of P_S -proximal contraction map and generalized P_S -proximity contraction mapping. Also, we study the existence of a best proximity point of non-self-map via generalized α_{P_S} -proximity contraction R map and given the condition to be unique. After that, we used these results to derive the theorems' best proximity point on P_S -dislocated metric spaces endowed with a partial order, and we gave an example that cleared these concepts in this space.

Keywords: Partially Ordered Set, Best Proximity Point, Simulation Function, Approximately Compact

حول الفضاءات المترية المخلوعة – P_S المرتبة جزئياً

جيهان محمد شاكر* ، زينه حسين معيب

قسم الرياضيات ، كلية التربية ابن الهيثم للعلوم الصرفة ، جامعة بغداد ، العراق

الخلاصه:

تلعب المقاييس المخلوعة دوراً مهماً في البرمجة المنطقية. علاوة على ذلك، فهي محورية في مجالات مثل التكنولوجيا والهندسة الإلكترونية. تأتي أهمية هذه المساحة كونها تحتوي على خاصية تعديل قيمة المسافة الذاتية. هذه الميزة جعلت العديد من المؤلفين يجرون تحقيقات مكثفة في هذا المقياس، حيث قاموا بفحص النقاط الثابتة للدوال الموجودة في هذا الفضاء والتي تلبي متطلبات محددة، ودرسوا الخصائص التي تميزه. بالإضافة إلى ذلك، نظروا فيما إذا كانت الدوال الانكماشية نوع R تتمتع بأفضل قرب في إطار الفضاءات المترية المخلوعة، وقاموا بوضع متطلبات محددة لضمان أن أفضل نقطة قرب لهذه الانقباضات تكون وحيدة.

*Email: Jihan.Abd2203@ihcoedu.uobaghdad.edu.iq

كذلك عمل الباحثون على تعميم مفهوم الفضاء المترى المخلوع ليشمل الفضاء المترى المخلوع b ، والفضاء المترى المخلوع S ، وأنواع أخرى من البناءات المترية. تقدم هذه الورقة مفهوم الفضاء المترى المخلوع Ps ونوع من دوال القرب الانكماشية Ps وايضا نوع من دوال القرب الانكماشية المعممة Ps . أيضا، قمنا بدراسة وجود أفضل نقطة قرب للدوال الغير ذاتية باستعمال دوال القرب نوع R الانكماشية المعممة α_{Ps} وإعطاء الشروط اللازمة لتكون نقطة القرب وحيدة. بعد ذلك، استخدمنا هذه النتائج لاشتقاق نظريات أفضل نقطة قرب للفضاء المترى المخلوع Ps والمرتب ترتيبيا جزئيا، وقدمنا مثلا يوضح هذه المفاهيم في الفضاء المترى المخلوع Ps .

1-Introduction and Preliminaries

In light of the importance of metric spaces in mathematical analysis, researchers have undertaken extensive studies of them. They have developed new types of metric spaces. One of these spaces is dislocated metric space, and the most distinguishing feature is that self-distance does not always equal zero. This hallmark of this space made it, since Seda and Hitzler [1] introduced it in 2000, very important in topology, electronics engineering, and many other important fields [2]. This has motivated many researchers to explore the subject in depth [3-5].

Another space is the S-metric space. This space was introduced in 2012 [6] by Shaban Sedghi, who gave it some properties of a multivalued map. Many researchers have been interested in this space [7-13]. Also, a b-metric space was proposed by Bakhtin [14] and refined by Czerwik [15], and others have worked around it, see [16-18]. For example, in 2019, Parvaneh and Hosseini [19] introduced the notion of p-metric space, an extension of the b-metric space. Another concept that plays a very important role in the mathematical analysis is the concept of a fixed point, which began in 1922 [20] when Banach advertised his famous theorem about the contraction principle. Since then, many authors have worked on the expansion of this theorem; see [21-32]. The work of researchers has led to expanding the concept of the fixed point, and they have obtained a new concept, which is a best proximity point. In this work, we generalize the results in [33] to a new space called the dislocated metric space and examine some findings that have been investigated in other spaces, see [34-45].

Now, we give the following concepts

Definition 1.1: Let $D \neq \emptyset$. A map $d_{Ps}: D \times D \times D \rightarrow [0, \infty)$ is called Ps -dislocated (dis) metric if $\exists \Omega: [0, \infty) \rightarrow [0, \infty)$ continuous such that $\Omega(s) \leq s, \forall s \in [0, \infty)$ and $\Omega(0) = 0, \forall u, v, w \in D$, we have

- 1) If $d_{Ps}(u, v, w) = 0$ then $u = v = w$,
- 2) $d_{Ps}(u, u, v) = d_{Ps}(v, v, u)$,
- 3) $d_{Ps}(u, v, w) \leq \Omega(d_{Ps}(u, u, e) + d_{Ps}(v, v, e) + d_{Ps}(w, w, e)), e \in D$.

Then (D, d_{Ps}) is Ps -dis metric space.

Definition 1.2: A map $L: (D, d_{Ps}) \rightarrow (D, d_{Ps})$ is Ps -continuous if $\forall \langle u_n \rangle$ convergence to $u \in D$, implies that $\lim_{n \rightarrow \infty} d_{Ps}(Lu_n, Lu_n, Lu) = d_{Ps}(Lu, Lu, Lu)$.

Definition 1.3: Let $\emptyset \neq U$, and S be subsets of Ps -dis metric space (D, d_{Ps}) and $L: U \rightarrow S$ be a map. An element $u \in U$ is called a best proximity (prox) point of L if

$d_{Ps}(u, u, Lu) = d_{Ps}(U, U, S)$. And:

$d_{Ps}(U, U, S) = \inf \{d_{Ps}(u, u, s): u \in U, s \in S\}$.

$u \in U, d_{Ps}(u, u, S) = \inf \{d_{Ps}(u, u, s): s \in S\}$.

$U_\circ = \{u \in U: d_{Ps}(u, u, s) = d_{Ps}(U, U, S), \text{for some } s \in S\}$.

$S_\circ = \{s \in S: d_{Ps}(u, u, s) = d_{Ps}(U, U, S), \text{for some } u \in U\}$.

Definition 1.4: [33] A map $Z: [0, \infty) \times [0, \infty) \rightarrow \mathbb{R}$ is called a simulation if:

- 1- $Z(0,0) = 0$.
- 2- $Z(v, h) < h - v$ that for all $v, h > 0$.
- 3- If $\langle v_n \rangle, \langle h_n \rangle$ are sequences in $(0, \infty)$ such that $\lim_{n \rightarrow \infty} v_n = \lim_{n \rightarrow \infty} h_n > 0 \Rightarrow \lim_{n \rightarrow \infty} \sup Z(v_n, h_n) < 0$.

Definition 1.5: [34] Let $U \subseteq \mathbb{R}$. A function $R: U \times U \rightarrow \mathbb{R}$ is an R-function if it satisfies

- 1- If $\langle u_n \rangle \subset (0, \infty) \cap U$ such that $R(u_{n+1}, u_n) > 0 \forall n \in N$, then $\langle u_n \rangle \rightarrow 0$.
 - 2- If $\langle u_n \rangle, \langle v_n \rangle \subset (0, \infty) \cap U$ are two sequences converging to the same limit.
 - $b \geq 0$ and $b < u_n$ and $R(u_n, v_n) > 0, \forall n \in N$, then $b = 0$.
- The set of all R-function R denoted by R_c .
 A function $R \in R_c$ is called a strong R-function if:
 3- If $\langle u_n \rangle, \langle v_n \rangle \subset (0, \infty) \cap U$ such that $\langle v_n \rangle \rightarrow 0$ and $R(u_n, v_n) > 0 \forall n \in N$ then $\langle u_n \rangle \rightarrow 0$.
 Let R_c^s denote the set of all strong R-function R.

Definition 1.6: Let $\alpha_{Ps}: U \times U \times U \rightarrow [0, \infty)$. A map $L: U \rightarrow S$ is called α_{Ps} -prox admissible if $\forall u_1, u_2, w_1, w_2 \in U$:

$$\begin{cases} \alpha_{Ps}(u_1, u_1, u_2) \geq 1; \\ d_{Ps}(w_1, w_1, Lu_1) = d_{Ps}(U, U, S) \Rightarrow \alpha_{Ps}(w_1, w_1, w_2) \geq 1; \\ d_{Ps}(w_2, w_2, Lu_2) = d_{Ps}(U, U, S). \end{cases}$$

It is called a triangular α_{Ps} -admissible (trian α_{Ps} -admis) map if $u, s, v \in U, \alpha_{Ps}(u, u, s) \geq 1$ and $\alpha_{Ps}(s, s, v) \geq 1 \Rightarrow \alpha_{Ps}(u, u, v) \geq 1$.

Definition 1.7: Let $\alpha_{Ps}: U \times U \times U \rightarrow [0, \infty)$. A map $L: U \rightarrow S$ is called α_{Ps} -prox R-contraction (cont) if $\forall u, v, w_1, w_2 \in U$:

$$\begin{cases} \alpha_{Ps}(u, u, v) \geq 1; \\ d_{Ps}(w_1, w_1, Lu) = d_{Ps}(U, U, S) \Rightarrow R(d_{Ps}(w_1, w_1, w_2), d_{Ps}(u, u, v)) > 0; \\ d_{Ps}(w_2, w_2, Lv) = d_{Ps}(U, U, S). \end{cases}$$

Definition 1.8: A map $L: U \rightarrow S$ is called generalized α_{Ps} -prox con R-cont if $\forall u, v, w_1, w_2 \in U$, where $\alpha_{Ps}: U \times U \times U \rightarrow [0, \infty)$ we have

$$\begin{cases} \alpha_{Ps}(u, u, v) \geq 1; \\ d_{Ps}(w_1, w_1, Lu) = d_{Ps}(U, U, S) \Rightarrow R(d_{Ps}(w_1, w_1, w_2), M(u, u, v)) > 0; \\ d_{Ps}(w_2, w_2, Lv) = d_{Ps}(U, U, S). \end{cases}$$

Where $R \in R_c$ and $M(u, u, v) = \max\{d_{Ps}(u, u, w_1), d_{Ps}(v, v, w_2), d_{Ps}(u, u, v)\}$.

Definition 1.9: The set S is said to be approximately compact if $\forall \langle u_n \rangle$ of C has a convergent subsequence, where C denotes all sequence $\langle u_n \rangle$ of S satisfying $d_{Ps}(u, u, u_n) = d_{Ps}(u, u, S)$.

Definition 1.10: We say that (D, d_{Ps}, \leq) is regular if for every nondecreasing sequence $\langle u_n \rangle \subset D$ such that $u_n \rightarrow u \in D$, as $n \rightarrow \infty$, there exists a subsequence $\langle u_{n_k} \rangle$ of $\langle u_n \rangle$ such that $u_{n_k} \leq u$ for all k.

2-Main Results

will remember the following theorem and prove new theorems based on the order property.

Theorem 2.1: Let (D, d_{Ps}) be a Ps-complete Ps-dis metric space and let U and S be Ps - closed in D such that S is approximately compact with respect to U and $L: U \rightarrow S$ be a trian generalized α_{Ps} -prox cont admis R, with $L(U) \subseteq S$ such that:

- 1- $R(p, q) < q - p \forall p, q > 0$.
- 2- $\exists u_0, u_1 \in U_0$ such that $d_{PS}(u_1, u_1, Lu_0) = d_{PS}(U, U, S), \alpha_{PS}(u_0, u_0, u_1) \geq 1$.
- 3- L is PS -continuous or, if $\langle u_n \rangle$ is a sequence in U such that $\alpha_{PS}(u_n, u_n, u_{n+1}) \geq 1 \forall n \in N, u_n \rightarrow u$, when $n \rightarrow \infty$ for some $u \in U$. Then $\alpha_{PS}(u_n, u_n, u) \geq 1 \forall n \in N$. And, L has the best prox point $f \in U$ that $d_{PS}(f, f, Lf) = d_{PS}(U, U, S)$ also,
- 4- $d_{PS}(f, f, f) = 0 \forall (u, u, r) \in U_0 \times U_0 \times U_0 \exists h \in U_0$ s.t $\alpha_{PS}(u, u, h) \geq 1, \alpha_{PS}(r, r, h) \geq 1$, then L has a unique best prox point.

Proof: Let $u_0, u_1 \in U_0, d_{PS}(u_1, u_1, Lu_0) = d_{PS}(U, U, S)$ with $\alpha_{PS}(u_0, u_0, u_1) \geq 1$.

We construct $\langle u_n \rangle$ such that

$$d_{PS}(u_{n+1}, u_{n+1}, Lu_n) = d_{PS}(U, U, S) \text{ with } \alpha_{PS}(u_n, u_n, u_{n+1}) \geq 1, \text{ if } u_{n+1} = u_n \implies L \text{ has the best prox point. If not, then } u_{n+1} \neq u_n \forall n \in N_0. \tag{1}$$

By $\alpha_{PS}(u_n, u_n, u_{n+1}) \geq 1$

$$d_{PS}(u_n, u_n, Lu_{n-1}) = d_{PS}(u_{n+1}, u_{n+1}, Lu_n) = d_{PS}(U, U, S) \\ R(d_{PS}(u_n, u_n, u_{n+1}), M(u_{n-1}, u_{n-1}, u_n)) > 0. \tag{2}$$

When

$$M(u_{n-1}, u_{n-1}, u_n) = \max\{d_{PS}(u_{n-1}, u_{n-1}, u_n), d_{PS}(u_n, u_n, u_{n+1})\}. \tag{3}$$

If for some $n_0 \in N$ we have:

$$\text{If } \max\{d_{PS}(u_{n_0-1}, u_{n_0-1}, u_{n_0}), d_{PS}(u_{n_0}, u_{n_0}, u_{n_0+1})\} = d_{PS}(u_{n_0}, u_{n_0}, u_{n_0+1}).$$

$$\text{We get } R(d_{PS}(u_{n_0}, u_{n_0}, u_{n_0+1}), d_{PS}(u_{n_0}, u_{n_0}, u_{n_0+1})) > 0. \tag{4}$$

$$\text{Then } \max\{d_{PS}(u_{n-1}, u_{n-1}, u_n), d_{PS}(u_n, u_n, u_{n+1})\} = d_{PS}(u_{n-1}, u_{n-1}, u_n) \quad \forall n \in N$$

$$R(d_{PS}(u_n, u_n, u_{n+1}), d_{PS}(u_{n-1}, u_{n-1}, u_n)) > 0 \quad \forall n \\ \text{So, } \lim_{n \rightarrow \infty} d_{PS}(u_n, u_n, u_{n+1}) = 0. \tag{5}$$

Thus, $\forall \varepsilon > 0$ and subsequence $\langle u_{n_k} \rangle$ and $\langle u_{m_k} \rangle$ let $m_k > n_k > k$ with

$$d_{PS}(u_{n_k}, u_{n_k}, u_{m_k-1}) < \varepsilon \leq d_{PS}(u_{n_k}, u_{n_k}, u_{m_k}) \quad \forall k \in N.$$

Then, triangle inequality implies

$$\langle u_k \rangle = \langle d_{PS}(u_{n_k}, u_{n_k}, u_{m_k}) \rangle \rightarrow \varepsilon \text{ and } \langle v_k \rangle = \langle d_{PS}(u_{n_k-1}, u_{n_k-1}, u_{m_k-1}) \rangle \rightarrow \varepsilon.$$

Also, from trian α_{PS} -admis we get $\alpha_{PS}(u_n, u_n, u_m) \geq 1, \forall n \geq m$. So,

$$R(u_k, v_k) = R(d_{PS}(u_{n_k}, u_{n_k}, u_{m_k}), d_{PS}(u_{n_k-1}, u_{n_k-1}, u_{m_k-1})) > 0$$

$\forall k \in N$, since $\varepsilon < u_k \implies \varepsilon = 0$, which contradicts. Then $\langle u_n \rangle \subset U$ is a PS -Cauchy sequence.

There exists $c, f \in U$ such that by (5) we get

$$d_{PS}(c, c, f) = \lim_{n \rightarrow \infty} d_{PS}(u_n, u_n, f) = \lim_{\substack{n \rightarrow \infty \\ m \rightarrow \infty}} d_{PS}(u_n, u_n, u_m) = 0. \tag{6}$$

If L is PS -continuous we have

$$d_{PS}(Lc, Lc, Lf) = \lim_{n \rightarrow \infty} d_{PS}(Lu_n, Lu_n, Lf) = \lim_{\substack{n \rightarrow \infty \\ m \rightarrow \infty}} d_{PS}(Lu_n, Lu_n, Lu_m) = 0$$

$$d_{PS}(U, U, S) = \lim_{n \rightarrow \infty} d_{PS}(u_{n+1}, u_{n+1}, Lu_n) = d_{PS}(c, c, Lf). \text{ That is, } f \in U \text{ is a best prox point of}$$

L . Next,

$$d_{PS}(c, c, S) \leq d_{PS}(c, c, Lu_n) \\ \leq \Omega(d_{PS}(c, c, u_{n+1}) + d_{PS}(c, c, u_{n+1}) + d_{PS}(Lu_n, Lu_n, u_{n+1})) \\ = 2d_{PS}(c, c, u_{n+1}) + d_{PS}(U, U, S) \\ \leq 2d_{PS}(c, c, u_{n+1}) + d_{PS}(c, c, S).$$

When $n \rightarrow \infty$ then, $\lim_{n \rightarrow \infty} d_{PS}(c, c, u_{n+1}) = 0$. And

$$d_{PS}(c, c, S) \leq \lim_{n \rightarrow \infty} d_{PS}(c, c, Lu_n) \leq d_{PS}(c, c, S) \implies \lim_{n \rightarrow \infty} d_{PS}(c, c, Lu_n) = d_{PS}(c, c, S).$$

Therefore, $\langle Lu_n \rangle$ has a subsequence $\langle Lu_{n_i} \rangle$ such that

$$\lim_{n \rightarrow \infty} Lu_{n_i} = h \text{ for some } h \in S. \text{ Then}$$

$$d_{PS}(c, c, h) = \lim_{n \rightarrow \infty} d_{PS}(u_{n_i}, u_{n_i}, Lu_{n_i}) = d_{PS}(U, U, S). \text{ We obtain } d_{PS}(w, w, Lf) = d_{PS}(U, U, S),$$

$w \in U$.

Now,

$$\begin{cases} \alpha_{Ps}(u_n, u_n, f) \geq 1; \\ d_{Ps}(u_{n+1}, u_{n+1}, Lu_n) = d_{Ps}(U, U, S) \implies R(d_{Ps}(u_{n+1}, u_{n+1}, w), M(u_n, u_n, f)) > 0; \\ d_{Ps}(w, w, Lf) = d_{Ps}(U, U, S). \end{cases}$$

$$M(u_n, u_n, f) > d_{Ps}(u_{n+1}, u_{n+1}, w). \\ \text{As } n \rightarrow \infty \implies d_{Ps}(f, f, w) < M(f, f, f) < \max\{d_{Ps}(f, f, f), d_{Ps}(f, f, w)\}.$$

As $n \rightarrow \infty$, we have $f = w$. Then, L has the best prox point f . Finally, to prove the uniqueness.

Let $f_1 \neq f_2 \in U$ are two best prox points of L . So,

$$d_{Ps}(f_1, f_1, Lf_1) = d_{Ps}(f_2, f_2, Lf_2) = d_{Ps}(U, U, S).$$

If $d_{Ps}(f_1, f_1, f_2) \neq 0$, then we have two cases:

1- If $\alpha_{Ps}(f_1, f_1, f_2) \geq 1 \implies R(d_{Ps}(f_1, f_1, f_2), d_{Ps}(f_1, f_1, f_2)) > 0$. That is a contradiction.

2- Or $\alpha_{Ps}(f_1, f_1, f_2) < 1 \implies \exists \{c_n\} \in U_\circ$ such that

$$\alpha_{Ps}(f_1, f_1, c_n) \geq 1;$$

$$\alpha_{Ps}(f_2, f_2, c_n) \geq 1.$$

Since $L(U_\circ) \subseteq S_\circ \rightarrow Lc_n \subset S_\circ$, then by Definition 1.7:

$$d_{Ps}(f_1, f_1, Lf_1) = d_{Ps}(c_{n+1}, c_{n+1}, Lc_n) = d_{Ps}(U, U, S) \quad \forall n \in N_\circ.$$

By R-cont $\rightarrow R(d_{Ps}(f_1, f_1, c_{n+1}), d_{Ps}(f_1, f_1, c_n)) > 0$, by Definition 1.5:

$$\lim_{n \rightarrow \infty} d_{Ps}(f_1, f_1, c_n) = 0. \text{ Similar, } \lim_{n \rightarrow \infty} d_{Ps}(f_2, f_2, c_n) = 0.$$

$$\text{Then } d_{Ps}(f_1, f_1, f_2) \leq \Omega(d_{Ps}(f_1, f_1, c_n) + d_{Ps}(f_1, f_1, c_n) + d_{Ps}(f_2, f_2, c_n)).$$

$$\text{When } n \rightarrow \infty \text{ we get } d_{Ps}(f_1, f_1, f_2) \leq \Omega(0) = 0 \implies d_{Ps}(f_1, f_1, f_2) = 0.$$

Then L has a unique best proximity point. ■

Definition 2.2: Let (D, d_{Ps}, \leq) be a Ps-dis ordered metric space. A map $L: U \rightarrow S$ is prox ordered $\iff \forall u_1, u_2, r_1, r_2 \in U$ we have

$$\begin{cases} r_1 \leq r_2; \\ d_{Ps}(u_1, u_1, Lr_1) = d_{Ps}(U, U, S) \implies u_1 \leq u_2; \\ d_{Ps}(u_2, u_2, Lr_2) = d_{Ps}(U, U, S). \end{cases}$$

Theorem 2.3: Let U be Ps-closed, S approximate compact respect to U lies in (D, d_{Ps}, \leq) , and L be a prox ordered with $L(U_\circ) \subseteq S_\circ$. If

1- $R(p, q) < q - p \quad \forall p, q > 0$.

2- $\exists u_\circ, u_1 \in U_\circ$ s.t $d_{Ps}(u_1, u_1, Lu_\circ) = d_{Ps}(U, U, S)$.

3- $\forall u, r, w_1, w_2 \in U$,

$$\begin{cases} u \leq r, u \neq r; \\ d_{Ps}(w_1, w_1, Lu) = d_{Ps}(U, U, S) \implies R(d_{Ps}(w_1, w_1, w_2), M(u, u, r)) > 0; \\ d_{Ps}(w_2, w_2, Lr) = d_{Ps}(U, U, S), \end{cases}$$

where $M(u, u, r) = \max\{d_{Ps}(u, u, w_1), d_{Ps}(r, r, w_2), d_{Ps}(u, u, r)\}$.

4- L be Ps-continuous, or (D, d_{Ps}, \leq) is regular. Then L has the best prox point $f \in U$, that $d_{Ps}(f, f, Lf) = d_{Ps}(U, U, S)$.

5- If $d_{Ps}(f, f, f) = 0 \quad \forall (u, u, r) \in U_\circ \times U_\circ \times U_\circ, \exists h \in U_\circ$ s.t $u \leq h$, and $r \leq h$.

Then L has a unique best prox point.

Proof: Define $\alpha_{Ps}: U \times U \times U \rightarrow [0, \infty)$ as $\alpha_{Ps}(u, u, r) = \begin{cases} 1 & u \leq r; \\ 0 & \text{otherwise.} \end{cases}$

$$\begin{cases} \alpha_{Ps}(u, u, r) \geq 1; \\ d_{Ps}(w_1, w_1, Lu) = d_{Ps}(U, U, S); \\ d_{Ps}(w_2, w_2, Lr) = d_{Ps}(U, U, S). \end{cases}$$

$$\begin{cases} u \leq r; \\ d_{Ps}(w_1, w_1, Lu) = d_{Ps}(U, U, S); \\ d_{Ps}(w_2, w_2, Lr) = d_{Ps}(U, U, S). \end{cases}$$

So, $w_1 \leq w_2$ and $\alpha_{Ps}(w_1, w_1, w_2) \geq 1$. Then we derive L is generalized α_{Ps} -prox-cont R. Then, all conditions above Theorem 2.1 hold. So, L has a unique best prox point. ■

Example 2.4: Let $D = \{(0,2), (2,0), (0, -2), (-2,0)\}$.

Define \leq on D , by

$$(u_1, v_1, r_1) \leq (u_2, v_2, r_2) \Leftrightarrow u_1 \leq u_2, v_1 \leq v_2 \text{ and } r_1 \leq r_2$$

$$d_{Ps}: D \times D \times D \rightarrow [0, \infty)$$

$$d_{Ps}((u_1, v_1), (u_1, v_1), (u_2, v_2)) = \begin{cases} 0 & (u_1, v_1) = (u_2, v_2) \in \{(0,2), (2,0)\}; \\ \frac{1}{2} & u_1 + u_2 = v_1 + v_2 ; \\ 2 & \text{Otherwise.} \end{cases}$$

The (D, d_{Ps}, \leq) is a complete dis ordered metric space.

Let $U = \{(0,2), (0, -2)\}$, $S = \{(2,0), (-2,0)\}$. Then $d_{Ps}(U, U, S) = \frac{1}{2}$ and $U = U_0, S = S_0$.

Let $L: U \rightarrow S$, such that $L(u, v) = (v, u)$. Also, $L(U_0) \subseteq S_0$. Then

$$\begin{cases} u \leq v, u \neq v; \\ d_{Ps}(w_1, w_1, Lu) = d_{Ps}(U, U, S) = \frac{1}{2} \Rightarrow R(d_{Ps}(w_1, w_1, w_2), M(u, u, v)) > 0; \\ d_{Ps}(w_2, w_2, Lv) = d_{Ps}(U, U, S) = \frac{1}{2}; \\ \begin{cases} (0, -2) < (0,2); \\ d_{Ps}(w_1, w_1, L(0, -2)) = d_{Ps}(U, U, S) = \frac{1}{2}; \\ d_{Ps}(w_2, w_2, L(0,2)) = d_{Ps}(U, U, S) = \frac{1}{2}; \end{cases} \\ \begin{cases} (0, -2) < (0,2) \\ d_{Ps}((0, -2), (0, -2), (-2,0)) = d_{Ps}(U, U, S) = \frac{1}{2}; \\ d_{Ps}((0,2), (0,2), (2,0)) = d_{Ps}(U, U, S) = \frac{1}{2}. \end{cases} \end{cases}$$

$$M(u, u, v)$$

$$\begin{aligned} &= \max\{d_{Ps}((0, -2), (0, -2), (0, -2)), d_{Ps}((0,2), (0,2), (0,2)), d_{Ps}((0, -2), (0, -2), (0,2))\} \\ &= \max\left\{2, 0, \frac{1}{2}\right\} = 2. \end{aligned}$$

Then $w_1 = (0, -2)$, $w_2 = (0,2)$ and $d_{Ps}(w_1, w_1, w_2) = \frac{1}{2}$ and $w_1 < w_2$

R: $[0, \infty) \times [0, \infty) \rightarrow \mathbb{R}$. By

$$R(p, q) = \begin{cases} \frac{1}{2}q - p, & p < q; \\ -1 & q = p = 0; \\ 0 & \text{o. w} \end{cases}$$

$$R\left(\frac{1}{2}, 2\right) = \frac{1}{2}q - p = \frac{1}{2}(2) - \frac{1}{2} = \frac{1}{2} > 0.$$

Thus $(0, -2), (0,2)$ are best proximity points of L.

Definition 2.5: [35] Let $L: D \rightarrow D$ be a map and $\alpha_{Ps}: D \times D \times D \rightarrow [0, \infty)$ be a function. We say L is an α_{Ps} -admis map if $u, r \in D, \alpha_{Ps}(u, u, r) \geq 1 \Rightarrow \alpha_{Ps}(Lu, Lu, Lr) \geq 1$.

Also, L is called α_{Ps} -orbital admi map if $u, r \in D$

$$\alpha_{Ps}(u, u, Lu) \geq 1 \implies \alpha_{Ps}(Lu, Lu, L^2u) \geq 1, \text{ when } L^2 = LoL.$$

Moreover, L is called trian α_{Ps} -orbital admis if L is α_{Ps} -orbital admis and $\alpha_{Ps}(u, u, r) \geq 1, \alpha_{Ps}(r, r, Lr) \geq 1 \implies \alpha_{Ps}(u, u, Lr) \geq 1$.

Theorem 2.6: Let (D, d_{Ps}) be a Ps -complete. If $L: D \rightarrow D$ is non-decreasing and trianr α_{Ps} -orbital admi such that:

$$1- R(p, q) < q - p \forall p, q > 0;$$

$$2- \exists u_0 \in D \text{ s.t } \alpha_{Ps}(u_0, u_0, Lu_0) \geq 1;$$

$$3- \forall u, r \in D \text{ such that } \alpha_{Ps}(u, u, r) \geq 1 \text{ we have } R(d_{Ps}(Lu, Lu, Lr), M(u, u, r)) > 0,$$

where $M(u, u, r) = \max\{d_{Ps}(u, u, r), d_{Ps}(u, u, Lu), d_{Ps}(r, r, Lr)\}$.

4- L is Ps -continuous. Then L has a fixed point

5-When f is a fixed point, then for a $(f_1, f_1, f_2) \in D \times D \times D, \exists h \in D$ such that $\alpha_{Ps}(f_1, f_1, h) \geq 1$ and

$\alpha_{Ps}(f_2, f_2, h) \geq 1$. Then L has a unique fixed point.

Proof: Let $u_0, u_1 \in D \implies \alpha_{Ps}(u_0, u_0, Lu_0) \geq 1, \alpha_{Ps}(u_0, u_0, u_1) \geq 1$.

Since $L: D \rightarrow D$ Then $L(D) \subseteq D$.

By the assumption (3), we get $d_{Ps}(Lu_0, Lu_0, Lu_1) = d_{Ps}(D, D, D) = 0$.

$$d_{Ps}(Lu_1, Lu_1, Lu_1) = d_{Ps}(D, D, D) = 0.$$

$$R(d_{Ps}(Lu_0, Lu_0, Lu_1), M(u_0, u_0, u_1)) > 0.$$

Then L is generalized α_{Ps} -prox R -cont. All conditions of Theorem 2.1 hold; therefore, L has a unique best prox point $c \in D$, such that $d_{Ps}(c, c, Lc) = d_{Ps}(D, D, D) = 0 \implies c = Lc$.

Then L has a unique fixed point. ■

Theorem 2.7: Let (D, d_{Ps}, \leq) be a partially ordered Ps -complete. If

$$1-R(p, q) < q - p \forall p, q > 0;$$

$$2- \exists u_0 \in D, \text{ s.t } u_0 \leq Lu_0;$$

$$3- \forall u, r \in D, \text{ we have } u \leq r, u \neq r \implies R(d_{Ps}(Lu, Lu, Lr), M(u, u, r)) > 0,$$

where $M(u, u, r) = \max\{d_{Ps}(u, u, r), d_{Ps}(u, u, Lu), d_{Ps}(r, r, Lr)\}$.

4- L is Ps -continuous or (D, d_{Ps}, \leq) is regular.

Then L has a fixed point.

5-If f is a fixed point, then for a $(f_1, f_1, f_2) \in D \times D \times D \exists h \in D$ s.t $f_1 \leq h, f_2 \leq h$.

Then L has a unique fixed point.

Proof: Let $u_0 \in D, ,$ the assumption (2) $u_0 \leq Lu_0$, if $u_0 = Lu_0$. Then u_0 is a fixed point. Let $u_0 \neq Lu_0$ (we suppose $Lu_0 = u_1$) we get:

$$u_0 \leq u_1, u_0 \neq u_1 \text{ and}$$

$$d_{Ps}(Lu_0, Lu_0, Lu_0) = d_{Ps}(D, D, D) = 0.$$

$$d_{Ps}(Lu_1, Lu_1, Lu_1) = d_{Ps}(D, D, D) = 0.$$

$$\text{Since } R(d_{Ps}(Lu_0, Lu_0, Lu_1), M(u_0, u_0, u_1)) > 0.$$

Then L is a prox order-preserving respect to the Ps -dislo metric. All conditions of the above theorem hold; therefore, L has a unique best prox point $c \in D$. ■

3- Conclusions

In this paper, a Ps -dis metric space, Ps -proximal contraction map, and the generalized Ps -prox cont map are introduced. Also, the existence and uniqueness of a best approximation point for the non-self-map in this space are studied. Then, we used these results to obtain theorems of a best approximation point on Ps -dis metric spaces with partial ordering. Also, an example to clarify these concepts and show that if the condition of uniqueness is not satisfied, we will get a best proximity point, but it does not necessarily have to be unique.

Reference

- [1] P. Hitzler, AK. Seda, "Dislocated topologies," *Journal of Electrical Engineering* vol. 51, no. 12 pp.3-7, 2000.
- [2] H. Bouhadjera, "Fixed point results in incomplete metric and dislocated metric spaces," *Annals of West University of Timisoara-Mathematics and Computer Science*, vol. 59, no. 1, pp.130-150, 2023.
- [3] K. Zoto, I. Vardhami, D. Bajović, Z.Mitrović, S. Radenović, "On some novel fixed-point results for generalized F-contractions in b-metric-like spaces with application," *Computer Modeling in Engineering & Sciences*, vol.135, no. 1 pp. 673-686, 2023.
- [4] B. Alqahtani, S. Alzaid, A. Fulga, AF. Roldán López de Hierro, "Proinov type contractions on dislocated b-metric spaces," *Advances in Difference Equations*, vol. 2021, pp.1-16, 2021.
- [5] M. Younis, D. Singh, AA. Abdou, "A fixed-point approach for tuning circuit problem in dislocated b-metric spaces," *Mathematical Methods in the Applied Sciences*, vol.45, no. 4 pp.2234-2253, 2022.
- [6] S. Sedghi, N. Shobe, A. Aliouche, "A generalization of fixed point theorems in S -metric spaces," *Matematički vesnik*, vol.64, no. 249, pp. 258-266, 2012.
- [7] N. OZGUR, N. TAS, "On S -metric spaces with some topological aspects," *Electronic Journal of Mathematical Analysis and Applications*, vol. 11, no. 2, pp.1-8, 2023.
- [8] S. Duraj, S. Liftaj, "A common fixed-point theorem of mappings on S -metric spaces," *Asian Journal of Probability and Statistics*, vol. 20, no. 2, pp. 40-45, 2022.
- [9] S. Devi, M. Kumar, S. Devi, "Some Fixed-Point Theorems in S -metric Spaces via Simulation Function," *Asian Research Journal of Mathematics*, vol. 19, no. 9, pp.13-24, 2023.
- [10] G.S. Saluja, HK. Nashine, R. Jain, RW. Ibrahim, HA. Nabwey, "Common Fixed-Point Theorems on S -Metric Spaces for Integral Type Contractions Involving Rational Terms and Application to Fractional Integral Equation," *Journal of Function Spaces*, vol. 2024, no. 1, pp. 5108481, 2024.
- [11] N. Priyobarta, Y. Rohen, S. Thounaojam, S. Radenović, "Some remarks on α -admissibility in S -metric spaces," *Journal of Inequalities and Applications*, vol. 2022, no. 1, pp. 34, 2022.
- [12] F. Nora, R. Stojan, "On some fixed-point results for expansive mappings in S -metric spaces." *Vojnotehnički glasnik*, vol.72, no. 3, pp. 1004-1018, 2024.
- [13] V. Popa, AM. Patriciu, "A General Fixed-Point Theorem for a Sequence of Multivalued Mappings in S -Metric Spaces," *Axioms*, vol. 13, no. 10, p. 670, Sep. 2024.
- [14] M. Bukatin, R. Kopperman, S. Matthews, H. Pajoohesh, "Partial metric spaces," *The American Mathematical Monthly*, vol. 116, no. 8, pp.708-718, 2009.
- [15] S. Czerwik, "Contraction mappings in b - S -metric spaces," *Acta mathematica et informatica universitatis ostraviensis*, vol. 1, no. 1, pp. 5-11, 1993.
- [16] C. Middlebrook, W. Feng, "Integral Operators in b -Metric and Generalized b -Metric Spaces and Boundary Value Problems," *Fractal and Fractional*, vol. 8, no. 11, pp. 674, 2024.
- [17] N. Kumar, S. Mehra, D. Santina, N. Mlaiki, "Some fixed-point results concerning various contractions in extended b -metric space endowed with a graph," *Results in Applied Mathematics*, vol. 25, pp. 100524, 2025.
- [18] Z. Mitrovic, H. Işık, S. Radenovic, "The new results in extended b - S -metric spaces and applications," *International Journal of Nonlinear Analysis and Applications*, vol.11, no. 1, pp. 473-482, 2020.
- [19] V. Parvaneh, SJ. Hosseini Ghoncheh, "Fixed points of (Ψ, Φ) Ω -contractive mappings in ordered P -metric spaces," *Global Analysis and Discrete Mathematics*, vol. 4, no. 1, pp. 15-29, 2019.
- [20] S. Banach, "Sur les opérations dans les ensembles abstraits et leur application aux équations intégrals," *Fundamenta mathematicae*, vol. 3, no. 1, pp. 133-181, 1922.
- [21] L.N. Mishra, V.K. Pathak, and D. Baleanu, "Approximation of solutions for nonlinear functional integral equations," *Mathematics*, vol.7, no. 9, pp.17486-17506, 2022.
- [22] D. Chand, Y. Rohen, N. Saleem, M. Aphane, A. Razzaque. "S-Pata-type contraction: a new approach to fixed-point theory with an application," *Journal of Inequalities and Applications*, vol. 2024, no. 1, pp. 59, 2024.
- [23] H.A. Hammad, M. Zayed, "Solving a system of differential equations with infinite delay by using tripled fixed- point techniques on graphs," *Symmetry*, vol. 14, no. 7, pp.1388, 2022.
- [24] P. Lo'lo, M. Shabibi, "Common best proximity points theorems for H -contractive non-self mappings," *Advances in the Theory of Nonlinear Analysis and its Application*, vol. 5, no. 2, pp. 173-179, 2021.

- [25] K. Sawangsup, W. Sintunavarat, "Some common fixed-point theorems for F-contraction mappings with applications to functional equations in the dynamic programming," *Bangmod International Journal of Mathematical and Computational Science*, vol. 7, pp. 126-135, 2021.
- [26] V.K. Pathak, L.N. Mishra, V.N. Mishra, D. Baleanu, "On the solvability of mixed-type fractional-order non-linear functional integral equations in the Banach space $C(I)$," *Fractal and Fractional*, vol. 6, no. 12, pp.744, 2022.
- [27] J. Matkowski, "A refinement of the Browder–Göhde–Kirk fixed point theorem and some applications." *Journal of Fixed-Point Theory and Applications*, vol. 24, no. 4, pp. 70, 2022.
- [28] G.X. Yuan, "Fixed point theorem and related nonlinear analysis by the best approximation method in p-vector spaces," *Numerical Functional Analysis and Optimization*, vol. 44, no. 4, pp. 221-295, 2023.
- [29] T. Rasham, S. Abdullah, A. Shaif, P. Choonkil, and J.R. Lee. "Study of multivalued fixed- point problems for generalized contractions idouble controlled dislocated quasi metric type spaces," *AIMS Mathematics*, vol. 7, no. 1, pp.1058-1073, 2022.
- [30] T. Muhammad, "Approximation of fixed points of a finite family of multivalued Lipschitz pseudo-contractive mappings in Banach spaces: Implicit and Explicit Algorithms," *Journal of the Nigerian Mathematical Society*, vol. 41, no. 2, pp.151-162, 2022.
- [31] I. Altun, A. Taşdemir, "On best proximity points of interpolative proximal contractions," *Quaestiones Mathematicae*, vol. 44, no. 9, pp. 1233-1241, 2021.
- [32] M. Gabeleh, J. Markin, "Some notes on the paper “On best proximity points of interpolative proximal contractions,”” *Quaestiones Mathematicae*, vol. 45, no. 10, pp.1539-1544, 2022.
- [33] L. Gholizadeh, E. Karapınar, "Best proximity point results in dislocated metric spaces via R-functions," *Revista de la Real Academia de Ciencias Exactas, Físicas y Naturales. Serie A. Matemáticas*, vol. 112, no. 4, pp. 1391-1407, 2018.
- [34] A.F. Roldán López de Hierro, N. Shahzad, "New fixed-point theorem under R-contractions." *Fixed Point Theory and Applications*, vol. 2015, pp.1-18, 2015.
- [35] O. Popescu, "Some new fixed- point theorems for α -Geraghty contraction type maps in metric spaces," *Fixed Point Theory and Applications*, vol. 2014, pp.1-12, 2014.
- [36] K. Fallahi, G.S. Rad, A. Fulga, "Best proximity points for $(\phi-\psi)$ -weak contractions and some applications," *Filomat*, vol. 37, no. 6, pp. 1835-1842, 2023.
- [37] A.S. Owolabi, T.O. Alakoya, A. Taiwo, O.T. Mewomo, "A new inertial-projection algorithm for approximating common solution of variational inequality and fixed-point problems of multivalued mappings," *Numerical Algebra, Control and Optimization*, vol. 12, no. 2, pp.255-278, 2022.
- [38] Z.H. Maibed and A. Thajil, "Equivalence of Some Iterations for Class of Quasi Contractive Mappings," *In Journal of Physics: Conference Series*, vol. 1879, no. 2, pp. 022115, 2021.
- [39] Z. Z. Jamil, Z. Hussein, "Common Fixed Point of Jungck Picard Iterative for Two Weakly Compatible Self-Mappings," *Iraqi Journal of Science*, vol. 62, no. 5, pp.1695-170, 2021.
- [40] S.S. Abed, A.N. Faraj, "Fixed points results in G-metric spaces," *Ibn AL-Haitham Journal for Pure and Applied Sciences*, vol. 32, no. 1, pp.139-146, 2019.
- [41] A.Q. Thajil and Z.H. Maibed, "On the Convergence Speediness of K^* and D-Iterations," *In Journal of Physics: Conference Series*, vol. 1897, no. 1, pp. 012056, 2021.
- [42] R. Hazim and S. Majeed, "Quasi Semi and Pseudo Semi (p, E)-Convexity in Non-Linear Optimization Programming," *Ibn AL-Haitham Journal for Pure and Applied Sciences*, vol.36, no. 1, pp. 355-366, 2023.
- [43] S.S. Abed, Z.M. Hasan, "Convergence comparison of two schemes for common fixed points with an application," *Ibn AL-Haitham Journal For Pure and Applied Sciences* 32, no. 2, pp. 81-92, 2019.
- [44] R.I. Sabri1, B.A. Ahmed, "Best proximity point results for generalization of α - η proximal contractive mapping in fuzzy banach spaces," *Indonesian Journal of Electrical Engineering and Computer Science*, vol. 28, no. 3, pp. 1451-1462, 2022.
- [45] S.H. Malih, W.M. Mukhlif, S.B. Smeein, "Common Fixed Points of Three Multivalued Nonexpansive Random Operators for One Step Iterative Scheme," *Ibn AL-Haitham Journal for Pure and Applied Sciences*, vol. 37, no. 2, pp. 424-431, 2024.