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Overlapping Structure Detection in Protein-Protein Interaction Networks Using a Modified Version of Particle Swarm Optimization

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Abstract

In today's world, the science of bioinformatics is developing rapidly, especially with regard to the analysis and study of biological networks. Scientists have used various nature-inspired algorithms to find protein complexes in protein-protein interaction (PPI) networks. These networks help scientists guess the molecular function of unknown proteins and show how cells work regularly. It is very common in PPI networks for a protein to participate in multiple functions and belong to many complexes, and as a result, complexes may overlap in the PPI networks. However, developing an efficient and reliable method to address the problem of detecting overlapping protein complexes remains a challenge since it is considered a complex and hard optimization problem. One of the main difficulties in identifying overlapping protein complexes is the accuracy of the partitioning results. In order to accurately identify the overlapping structure of protein complexes, this paper has proposed an overlapping complex detection algorithm termed OCDPSO-Net, which is based on PSO-Net (a well-known modified version of the particle swarm optimization algorithm). The framework of the OCDPSO-Net method consists of three main steps, including an initialization strategy, a movement strategy for each particle, and enhancing search ability in order to expand the solution space. The proposed algorithm has employed the partition density concept for measuring the partitioning quality in PPI network complexes and tried to optimize the value of this quantity by applying the line graph concept of the original graph representing the protein interaction network. The OCDPSO-Net algorithm is applied to a Collins PPI network and the obtained results are compared with different state-of-the-art algorithms in terms of precision (P), recall (R), and F-measure (F - measure). Experimental results confirm that the proposed algorithm has good clustering performance and has outperformed most of the existing recent overlapping algorithms.

Keywords: Overlapping structure, Protein complex detection, Protein-protein interaction network (PPI), Particle swarm optimization algorithm.

الكشف عن الهياكل المتداخلة في شبكات التفاعل البروتينية باستعمال نسخة معدلة من خوارزمية تحسين سرب الجسيمات

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الخلاصة

في عالم اليوم، يتطور علم المعلوماتية الحيوبة بشكل سربع، خاصة فيما يتعلق بتحليل ودراسة الشبكات الاحيائية. قام الباحثون بتطبيق خوارزميات مختلفة مستوحاة من الطبيعة من أجل تحديد مركبات البروتين في شبكات تفاعل البروتين البروتين (PPI) ، والتي يمكن من خلالها التنبؤ بالوظيفة الجزيئية للبروتينات غير المعرفة، بالإضافة إلى الكشف عن انتظام نشاط الخلية. من الشائع جدًا في شبكات PPI أن يشارك البروتين في وظائف متعددة وينتمي إلى العديد من المركبات، ونتيجة لذلك، قد تتداخل المركبات في شبكات PPI. ومع ذلك، فإن تطوير طريقة فعالة وموثوقة لمعالجة مشكلة اكتشاف البنية المتداخلة لمركبات البروتين لا يزال يمثل تحديًا كونها تعتبر مشكلة تحسين معقدة و صعبة للغاية. إحدى الصعوبات الرئيسية في تحديد مركبات البروتين المتداخلة هي دقة نتائج التجميع. من أجل تحديد البنية المتداخلة لمركبات البروتين بدقة، اقترح هذا البحث خوارزمية كشف معقدة متداخلة تسمى OCDPSO-Net والتي تعتمد على خوارزمية PSO-Net (نسخة معدلة معروفة من خوارزمية تحسين سرب الجسيمات). يتكون إطار الطريقة المقترحة -OCDPSO Net من ثلاث خطوات رئيسية تشمل: استراتيجية التهيئة، وإستراتيجية حركة البحث لكل جسيم، وتعزيز القدرة على البحث من أجل توسيع مساحة الحل. استعملت الخوارزمية المقترحة مفهوم كثافة التقسيم لقياس جودة تجميع المركبات في شبكاتPPI ، وحاولت تحسين قيمة هذه الكمية من خلال تطبيق مفهوم الرسم البياني الخطى للرسم البياني الأصلى الذي يمثل شبكة تفاعل البروتين. تم تطبيق الخوارزمية المقترحة-OCDPSO Net على شبكة Collins PPI ومقارنة النتائج التي تم الحصول عليها مع خوارزميات حديثة مختلفة من حيث precision (P), recall (R) و F-measure . أكدت النتائج التجريبية أن الخوارزمية المقترحة OCDPSO-Netتمتع بأداء وإعد وإمكانيات كبيرة في تحديد البنية المتداخلة للمركبات البروتينية في شبكات .PPI

1. Introduction

Many PPI networks have been mined as a result of the rapid advances in data processing, experimental methods, and computing technology [1, 2]. In accordance with previous studies, it has been stated that PPI networks can be created as complex, scale-free networks that meet small-world properties and high degrees of clustering [3]. In general, PPI networks represent a group of proteins connected among themselves by interactions [4–6], and the proteins within PPI networks are connected in two different types of cluster organizational structures, namely protein complexes and functional modules [7]. For simplicity, the terms protein complexes and functional modules [7]. For simplicity, the terms protein the completion of the Human Genome Project, many studies on the discovery of protein functional modules have been one of the hottest issues in computer science and life sciences [8–15].

Since many structures in the PPI network complexes may overlap, which means that a protein may belong to more than one complex, the identification of overlapping structures of protein complexes has broad prospects in different interesting applications such as the prediction of therapeutic targets, disease-causing genes, and the biological function of proteins. Many researchers have developed various algorithms in recent years that employ computational methodology to find protein complexes in PPI networks that have overlapping organizational structures [16]. Network clustering is one of the most effective and widely used methods for exploring and studying the overlapping topological and functional characteristics of PPI networks, among countless other alternatives [17, 18].

Mathematically, a graph is considered an efficient way, and often used in practice, to represent a complex network, where the graph nodes represent the network objects and the graph edges correspond to the connections between them [19–22]. Based on that, overlapping graph data can be represented using the line graph concept of the original graph, which allows

nodes to be present in multiple clusters [19]. Recent years have witnessed great interest in solving the problem of detecting the overlapping structures of functional modules or protein complexes in PPI networks [23–33], but developing efficient and reliable methods for addressing the aforementioned problem remains a difficult and significant scientific problem in computational biology [34]. One of the main difficulties in discovering overlapping protein complexes is the accuracy of the partitioning results.

Accordingly, the main contributions of this paper are: (1) Enhancing the detection accuracy of the overlapping protein complexes by proposing an overlapping complex detection algorithm termed OCDPSO-Net using the modified version of particle swarm optimization (PSO-Net) that was proposed by Abdollahpouri et al. [35]. (2) Employing the concept of partition density D [36] to assess the division quality of the captured complexes in the PPI network, and optimizing the value of this quantity by applying the line graph concept L(G) of the graph G [37, 19] representing the protein interaction network. (3) Applying the proposed algorithm to the Collins PPI network and comparing the obtained results with different state-of-the-art algorithms (namely, DMCL-EHO [33], K-means [32], MCODE [26], MCL [24], and ClusterOne [27]) in terms of R, P and F – measure. Experimental results confirm that the proposed algorithm, OCDPSO-Net, has promising performance and great potential for identifying complexes in PPI networks. The rest of the paper is processed as follows: Section 2 presents some recent related works. Section 3 describes the proposed OCDPSO-Net algorithm in detail. Section 4 presents the settings for the experiments, including the dataset used to evaluate the proposed algorithm, the evaluation metrics, and the experimental results obtained. The last section summarizes the paper with concluding remarks.

2. Related Works

Over the past years, a lot of algorithms have been proposed to address the problem of detecting overlapping or non-overlapping protein complexes in PPI networks [23]. For instance, Nepuse et al. [27] proposed the ClusterOne algorithm, which took advantage of the well-known greedy strategy. In general, the vertex or protein having the highest degree in the entire network was selected as the seed, and then, using a function with a greedy approach, some vertices were inserted or deleted from the seed. All the pair complexes in which the Overlap Score function's value exceeds a predetermined threshold are merged in order to discover overlapping clusters. Finally, complexes with a number of proteins lower than 3 or a density value below a predetermined threshold are eliminated. In the face of multiobjective optimization functions, Cao et al. [28] introduced the MOEPGA algorithm. The main aspect of the MOEPGA algorithm is to take advantage of various properties related to the network topology, such as size, name, distance, length, and density.

At first, the MOEPGA algorithm analyzed the structure of the PPI network and, based on the multiple topological characteristics of the network, formulated a multiobjective function. In each subgraph, three steps are taken, which are: generating an initial population, mutation, and selection. For clustering a PPI network by taking into account both biological properties and topological patterns. Sikandar et al. [29] introduced such an algorithm in which decision tree learners were used to model each complex subgraph. The authors employed a training set of known complexes to build decision trees, using the strategy of divide and conquer, in a best-first and depth-first manner.

Gu et al. [30] developed a Markov-based clustering algorithm that identified overlapping structures using link similarity information. They have demonstrated in their study that the proposed technique can discover more biologically significant modules in PPI networks.

Ramadan et al. [31] proposed a genetic algorithm for predicting protein complexes in a PPI network where its population was generated through spectral and random methods. In addition, genetic operations and different objective functions were used to improve the clustering quality. At first, the algorithm employed spectral clustering to determine the minimum cut that occurs between the subgraphs because, in general, the main aim of clustering is to capture subgraphs with the highest intraconnections. Accordingly, the authors used eigenvector, Laplacian, and diagonal matrices to derive the network's minimum cut [23]. Kalaivani et al. [32] adopted the k-means algorithm as an efficient algorithm for protein complex detection.

In 2019, Rani et al. [33] proposed the DMCL-EHO approach, which used Markov Clustering-based Elephant Optimization to apply clustering analysis to each subnetwork and find dynamic protein complexes. Shirmohammady et al. [23] recently proposed PPI-GA, a new clustering algorithm based on the genetic algorithm. To reduce the search space, they also came up with a new way to encode solutions. In addition, the authors adopted a new multiobjective quality function to optimize both cluster intraconnections in terms of maximization language and cluster interconnections in terms of minimization language.

3.The Proposed OCDPSO-Net to Identify Overlapping Protein Complexes

The PSO algorithm is an exciting and ever-expanding research topic that falls under the category of swarm intelligence algorithms, meaning "working with a set of particles." It has been the focus of attention for many scholars from various domains to tackle different challenging issues [38–42]. There are two crucial steps in the modified version of particle swarm optimization (PSO-Net) that Abdollahpouri et al. [35] proposed: (1) initialization and (2) moving. In PSO-Net, the particles of the algorithm are approaching their local and global best positions by taking part in crossover operations. After that, to spread within the search space, a mutation operator is applied to each particle. PSO-Net optimizes each particle based on the modularity measure for which it is selected as a fitness function.

Based on the PSO version of Abdollahpouri et al. [35], the framework of the proposed OCDPSO-Net algorithm consists of three main steps, including: initialization strategy (i.e., particle structure representation scheme (as shown in Section 3.1) and fitness computation (as shown in Section 3.2)), movement strategy for each particle (i.e., search strategy) (as shown in Section 3.3), and enhancing search ability in order to expand the solution space (as shown in Section 3.4). Figure 1 shows the suggested method's flowchart, and details of each step are presented in the subsections that follow.



Figure 1: Flowchart of the proposed OCDPSO-Net algorithm. The algorithm is based on the PSO version of [35]

3.1Particle Representation and Initialization

Given a graph G = (V, E) representing a PPI network \mathcal{N} et, the proposed PSO algorithm has been applied to the line graph L(G) of G. The L(G) of an undirected graph G is another graph L(G) where: 1) each L(G)'s node is an edge of G, 2) two nodes of L(G) are adjacent if and only if their corresponding edges in G have a common end node. Thus, a L(G) represents the adjacency between G's edges. The clustering approach based on the line graph yields an overlapping graph partitioning of the original graph G, thus allowing nodes to be present in multiple clusters [37]. OCDPSO-Net encodes on edges of the network, where a particle p in the population consists of m edges { $p_0, p_1, \dots, p_i, \dots, p_{m-1}$ }, in which $i \in \{0, \dots, m-1\}$ is the edges' identifier (i.e., links), m is the edges' number, and each p_i at random selects one from the edges adjacent to edge i.

According to graph theory, if two edges share one node in an undirected graph, then they are adjacent. A genotype is transferred to an edge complex partition during the decoding phase. Since p_i has the value j, edge i and edge j share a common node. Therefore, they ought to be classified under the same component. During the decoding process, it is necessary to determine all linked components. All edges that belong to the same connected component are mapped into a single complex. This decoding step can be done in linear time [36]. In the

process of initializing a population, a set of particles is randomly generated. For each particle p, at random, each p_i is assigned one of its adjacent links.

3.2Fitness Computation

In OCDPSO-Net, the objective function's value represents the particles' fitness, which indicates the particles' merit. The objective function directs the random search of OCDPSO-Net. In overlapping protein complexes, one protein is allowed to belong to more than one complex, which makes the conventional complex (or community) definitions unreasonable [36, 43]. As a result, a new definition of community has been adopted and employed in many nature-inspired algorithms to detect overlapping communities. Ahn *et al.* [43] proposed the partition density D for overlapping communities, which evaluates the edge density within communities. For a network with M links, suppose $C = \{c_1, \ldots, c_k\}$ as a partition of the network's links into k subsets, $m_{c_i} = |c_i|$ is the number of links in subset c_i . Note that $\sum_{i=1}^{k} m_{c_i} = M$ and $\sum_{i=1}^{k} n_{c_i} \ge N$ (assuming no unconnected nodes). Accordingly, D_{c_i} refers to the link density of subset c_i , Equation (1) shows its definition [36, 43]:

$$D_{c_i} = \frac{m_{c_i} - (n_{c_i} - 1)}{n_{c_i}(n_{c_i} - 1)/2 - (n_{c_i} - 1)} \tag{1}$$

The partition density, D, is the average of D_{c_i} , over all communities, weighted by the fraction of links presenting in each community. Equation (2) shows its definition [36, 43]:

$$D = \frac{2}{M} \sum_{i=1}^{k} m_{c_i} \frac{m_{c_i} - (n_{c_i} - 1)}{(n_{c_i} - 2)(n_{c_i} - 1)}$$
(2)

Equation (2) does not possess a resolution limit since each term is local in c_i [43].

3.3 Search Strategy

The search strategy of the PSO is based on moving each particle toward its local best and also moving it toward the swarm's global best. Genetic operators like crossover and mutation based on line graph representation are used to move each particle toward the best positions. The main steps of the movement strategy in the OCDPSO-Net are presented as follows [35, 44, 45].

3.3.1 Moving toward personal best

Firstly, each particle executes a two-point crossover with its personal best. The outcome of the crossover process is the production of two new particles. After that, the fitness values of the obtained outcomes are compared, and the solution that achieves a higher value of fitness, or higher partition density (D), is selected as a temporary position for the present addressed particle. Figure 2 illustrates an example of how the two-point crossover operator can be applied. Figure 2 (a) shows two arbitrary solutions, $parent_1$ and $parent_2$ considered as parents, and two random points (i.e., two random edges' identifiers) i = 5 and j = 7 are determined. Figure 2(b) illustrates the crossover operator. To generate $child_1$ (the first child), the values of the edges from the particle's beginning to i (the first crossover point) are copied from the parent $parent_2$, and the rest is copied from $parent_1$. This procedure is carried out in reverse order to create $child_2$ (the second child) [35, 44].

Index:	1	2	3	4	5	6	7	8	9	10	11
$parent_1$:	1	5	6	4	9	2	11	17	4	11	7
				1							

Index:	1	2	3	4	5	6	7	8	9	10	11
parent ₂ :	6	7	4	9	7	11	11	7	4	8	7

(a) **Parent individuals**

Index:	1	2	3	4	5	6	7	8	9	10	11
child ₁ :	1	5	6	4	7	11	11	7	4	11	7

Index:	1	2	3	4	5	6	7	8	9	10	11
child ₂ :	6	7	4	9	9	2	11	7	4	8	7

(b) Crossover operator

Figure 2: Illustration of a 2-point crossover (a) illustrates the representation of two arbitrary particles. (b) Shows the crossover operator

3.3.2 Moving toward global best

In this step, a two-point crossover is carried out between the global best and each particle in the population so as to move the particles toward the identified global best point. After this process, two new solutions are generated, and the temporary state of the present particle is chosen from the resulting solutions based on the highest fitness value (i.e., the highest partition density, D value).

3.4 Enhancing Search Ability

Finally, neighbor edge-based mutation is applied to the particles under the predetermined probability of the mutation operator [46] in order to move the solutions around the entire search space. To ensure that there are only possible and feasible solutions in the solution space, a gene or edge identifier i is randomly chosen for the selected mutated particle, where the possible values of gene i are restricted to its adjacent edges. The outcome of the mutation operator is compared to the native personal best value of the mutated particle, and the personal best value is replaced by the mutated particle value if the mutated particle shave been moved and their personal bests have been updated, fitness values are then computed again using the partition density (D) measure. The particle with the highest fitness value is chosen as the global best of the entire swarm. This procedure is carried out over a predetermined number of iterations [35, 44].

4. Experiments and Evaluation

4.1 Dataset

Since there are numerous high-confidence datasets of the PPI network from the yeast organism [47], they are selected and studied in this paper. In the research experiment, the Collins PPI network derived from the BioGrid dataset has been used [31, 48] to test the performance of the proposed overlapping clustering algorithm. There are 1,004 proteins (or nodes) and 8,319 interactions (or edges) in this network. It has an average degree equal to 16.57, where a node's degree in a network is determined by the number of links it has with other nodes; on the other hand, this network has a density of 0.016, which is the ratio of total connections to connections that may potentially exist in the network. The network has been illustrated as an interactive graph in Figure 3 using Gephi software. Gephi is a software package written in Java for network analysis and visualization. High-quality datasets are

needed as gold standards or reference complexes to validate the quality of the clustering approaches [31]. Collections of yeast protein complexes taken from literature and listed in the MIPS (known yeast genome database) have been used [49], in addition to a hand-curated reference complex set termed CYC2008 [50]. Table 1 presents a summary of the characteristics of the dataset used.

tuble 1. Summary of the characteristics of the dataset ased						
Network Category	Biological					
Network Name	Collins PPI network					
Network Pattern	Overlapping complex structure					
Number of Proteins	1,004					
Number of Interactions	8,319					
Average Degree	16.57					
Density	0.016					
Reference Complex Sets	MIPS and CYC2008					

Table 1: Summar	y of the	characteristics	of the	dataset	used
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Figure 3: Collins interactive network in Gephi software

4.2 Evaluation Measures

The *P* (i.e., positive predictive value), *R* (i.e., sensitivity), and F – measure assessment metrics are used for assessing the predicted clusters' quality. All of these criteria will be calculated over pairs of nodes (in this case, proteins). According to the obtained overlapped clustering results, for each protein's pair that participates in at least one complex, these evaluation measures attempt to determine if the prediction of this protein's pair is correct, that is, if it is mapped to the same cluster of underlying complexes in the database (i.e., the true reference complexes) [23]. Given a predicted cluster *C* and a reference protein complex *G*, let true positive (TP) refer to the set of proteins present only in the complex *C*, and true negative (TN) refers to the set of proteins that are members of the complex *G* but are not members of complex *C* [31]. Hence, *P*, *R*, and *F* – measure can be formally expressed as [23, 31]:

$$P = \frac{TP}{TP + FP} \tag{3}$$

$$R = \frac{TP}{TP + TN} \tag{4}$$

$$F - measure = \frac{2 \times (P \times R)}{P + R}$$
(5)

4.3 The Results

In this section, the analysis of the results of experiments on the Collins network is presented in detail. The proposed algorithm (OCDPSO-Net) is simulated using the MATLAB

platform. The number of iterations in OCDPSO-Net was set to 50, and the size of the population was customized to 100. In addition, we have discussed the results obtained by the OCDPSO-Net algorithm on the Collins PPI network when mutation rate $p_m = \{0.0, 0.3, 0.5, 0.7, 1\}$. Since the OCDPSO-Net algorithm is a random optimization method, all test results achieved by the proposed method are computed over twenty individual runs.

Figures 4 and 5 show clustering results achieved by OCDPSO-Net on MIPS and CYC2008 complexes reference, respectively, in terms of R, P, and F – measure when $p_m = \{0.0, 0.3, 0.5, 0.7, 1\}$. These figures show that, given the different measures, the results obtained by the proposed algorithm in different individual runs are not significantly different. When $p_m = 0.7$, the proposed algorithm reported the best average values in terms of F – measure which are equal to 0.4431 and 0.6603 when using MIPS and CYC2008 as reference complexes, respectively. Therefore, we set $p_m = 0.7$ in this study.

According to [23], the algorithm's stability points out that the algorithm's performance is correct. When an algorithm is stable, the results it produces are not scattered, which means that even if it is executed many times on the same sample and under the same settings, the results' quality is not very different in all the tests and will be within about the same range. To look more closely and to demonstrate the proposed algorithm's stability, the results of twenty individual runs in terms of F - measure have been collected when $p_m = 0.7$ and presented in Figures 6 and 7 for the Collins data sample when CYC2008 and MIPS have been used as reference clusters, respectively. As shown in Figures 6 and 7, the obtained F - measure values are within about one range and not much different, so the solutions obtained from the proposed algorithm have good stability.



Figure 4: Collins data sample clustering results in twenty individual runs on MIPS complexes referenced in terms of *R*, *P*, and *F* – *measure* when $p_m = \{0, 0.3, 0.5, 0.7, 1\}$



Figure 5: Collins data sample clustering results in twenty individual runs on CYC2008 complexes referenced in terms of *R*, *P*, and *F* – *measure* when $p_m = \{0, 0.3, 0.5, 0.7, 1\}$



Figure 6: The F – measure stability diagram for the MIPS data sample

Figure 7: The F – measure stability diagram for the CYC2008 data sample

Lastly, the proposed algorithm (OCDPSO-Net) has been compared with some recent state-of-the-art algorithms. Comparison algorithms fall into the category of overlapping community detection algorithms, including DMCL-EHO [33], K-means [32], MCODE [26], MCL [24], and ClusterOne [27]. The comparison results in terms of P, R, and F - measure are presented in Table 2. It should be mentioned that the results of all the counterpart state-of-the-art algorithms in Table 2 are taken from the reference [23]. In general, compared to the other state-of-the-art algorithms, our proposed algorithm reports the highest results in terms of P, R and F - measure in clustering MIPS references and in terms of R and F - measure in clustering CYC2008 references, where the first highest result in terms of P has been reported by the K-means clustering algorithm. This is due to the fact that the particles' representation of OCDPSO-Net guarantees convergence, and employing the PSO algorithm as a search

engine guarantees fast convergence. In addition, selecting partition density D as an objective function ensures the quality of the overlapping complex detection and helps in finding protein complex structures that are closer to the gold standard ones.

Looking closely, Table 2 demonstrates that the OCDPSO-Net clustering algorithm has the same accuracy values as the MCODE algorithm, which are 0.48 and 0.59 in clustering the MIPS and CYC2008 references, respectively. For the *R* measure, OCDPSO-Net records a value of 0.43 and 0.84 compared to MCODE results of 0.27 and 0.66. Regarding the F - measure, it is obviously clear from Table 2 that the proposed algorithm has yielded a higher value than the MCODE algorithm. On the other hand, the suggested algorithm exhibits higher values in terms of *P*, *R*, and F - measure when compared to MCL, which employs the random walk process for clustering, as well as higher *P*, *R*, and F - measure values when compared to ClusterOne, which is based on network density.

As for the comparison of the OCDPSO-Net result with DMCL-EHO and K-means clustering, it is shown that OCDPSO-Net recorded the best solutions in all cases except in clustering the CYC2008 in terms of *P*. In summary, OCDPSO-Net has presented good clustering performance and outperformed the existing recent overlapping algorithms.

Table 2: Comparison of OCDPSO-Net algorithm results with existing recent overlapping algorithms

Mathad		CYC2008			MIPS			
Method	R	Р	F-m	R	Р	F-m		
DMCL-EHO	0.74	0.61	0.66	0.42	0.41	0.41		
K-means clustering	0.55	0.67	0.6	0.28	0.4	0.32		
MCODE	0.66	0.59	0.63	0.27	0.48	0.35		
MCL	0.65	0.45	0.54	0.27	0.34	0.3		
ClusterOne	0.55	0.43	0.49	0.2	0.34	0.25		
OCDPSO-Net (our)	0.84	0.59	0.69	0.43	0.48	0.45		

5 Conclusion

The main contribution of this research is to propose a robust clustering algorithm, termed OCDPSO-Net, to identify the overlapping structures of protein complexes in PPI networks. The proposed algorithm makes use of the new version of the PSO algorithm to improve the clustering accuracy of protein complexes, uses the concept of partition density to measure the clustering quality in complexes of a PPI network, and attempts to maximize this quantity by applying the PSO algorithm to the line graph L(G) of the graph G representing the protein interaction network. The OCDPSO-Net algorithm has been applied to the Collins PPI network and compared with a number of competent state-of-the-art algorithms in terms of R, P, and F - measure. Experimental results have shown that OCDPSO-Net has promising performance and great potential for identifying complexes in the Collins PPI network. Future research will focus on enhancing the algorithm's performance by developing a local problem-specific operator and integrating it with multiobjective models. Also, it is interesting to investigate the ability of the proposed algorithm in other types of complex biological networks, such as metabolic networks.

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